GENERAL DESCRIPTION

The PAX Digital Input Panel Meters offer many features and performance capabilities to suit a wide range of industrial applications. Available in three different models, PAXC Counter, PAXR Rate Meter and the PAXI which offers both counting and rate in the same package. Refer to pages 4 - 5 for the details on the specific models. The PAXC and PAXR offer only the Setpoint Option, while the PAXI is the fully featured version offering all the capabilities as outlined in this bulletin. The optional plug-in output cards allow the opportunity to configure the meter for present applications, while providing easy upgrades for future needs.

The meters employ a bright 0.56" LED display. The unit is available with a red sunlight readable or standard green LED display. The intensity of the display can be adjusted from dark room applications up to sunlight readable, making it ideal for viewing in bright light applications.

The meters accept digital inputs from a variety of sources including switch contacts, outputs from CMOS or TTL circuits, magnetic pickups and all standard RLC sensors. The meter can accept directional, uni-directional or Quadrature signals simultaneously. The maximum input signal varies up to 34 KHz depending on the count mode and function configurations programmed. Each input signal can be independently scaled to various process values.

The Rate Meters provide a MAX and MIN reading memory with programmable capture time. The capture time is used to prevent detection of false max or min readings which may occur during start-up or unusual process events.

The meters have four setpoint outputs, implemented on Plug-in option cards. The Plug-in cards provide dual FORM-C relays (5A), quad FORM-A (3A), or either quad sinking or quad sourcing open collector logic outputs. The setpoint alarms can be configured to suit a variety of control and alarm requirements.

Communication and Bus Capabilities are also available as option cards for the PAXI only. These include RS232, RS485, Modbus, DeviceNet, and Profibus-DP. Readout values and setpoint alarm values can be controlled through the bus. Additionally, the meters have a feature that allows a remote computer to directly control the outputs of the meter. With an RS232 or RS485 card installed, it is possible to configure the meter using a Windows® based program. The configuration data can be saved to a file for later recall.

A linear DC output signal is available as an optional Plug-in card for the PAXI only. The card provides either 20 mA or 10 V signals. The output can be scaled independent of the input range and can track any of the counter or rate displays. Only the meters have been initially configured, the parameter list may be locked out from further modification in its entirety or only the setpoint values can be made accessible.

The meters have been specifically designed for harsh industrial environments. With NEMA 4X/IP65 sealed bezel and extensive testing of noise effects to CE requirements, the meter provides a tough yet reliable application solution.

SAFETY SUMMARY

All safety related regulations, local codes and instructions that appear in this literature or on equipment must be observed to ensure personal safety and to prevent damage to either the instrument or equipment connected to it. If equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

Do not use this meter to directly command motors, valves, or other actuators not equipped with safeguards. To do so can be potentially harmful to persons or equipment in the event of a fault to the meter.

DIMENSIONS In inches (mm)

Note: Recommended minimum clearance (behind the panel) for mounting clip installation is 2.1" (53.4) H x 5" (127) W.
# Table of Contents

- Ordering Information .......................... 2
- General Meter Specifications .............. 3
- PAXC Counter ................................ 4
- PAXR Rate Meter ............................... 4
- PAXI Counter/Rate Meter ..................... 5
- Optional Plug-In Output Cards .......... 6
- Installing the Meter ......................... 7
- Setting the Jumper and DIP Switches .... 7
- Installing Plug-In Cards .................... 8
- Wiring the Meter ............................... 9
- Reviewing the Front Buttons and Display 11
- Programming the Meter ..................... 12
- Factory Service Operations ............... 28
- Troubleshooting ............................... 29
- Parameter Value Chart ...................... 30
- Programming Overview .................... 32

# Ordering Information

## Meter Part Numbers

<table>
<thead>
<tr>
<th>PAX</th>
<th>0</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>R</td>
<td></td>
<td></td>
</tr>
<tr>
<td>I</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- C - Counter
- R - Rate Meter
- I - Counter/Rate Meter

<table>
<thead>
<tr>
<th>0</th>
<th>Red, Sunlight Readable Display</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Green Display</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>0</th>
<th>85 to 250 VAC</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>11 to 36 VDC, 24 VAC</td>
</tr>
</tbody>
</table>

## Option Card and Accessories Part Numbers

<table>
<thead>
<tr>
<th>TYPE</th>
<th>MODEL NO.</th>
<th>DESCRIPTION</th>
<th>PART NUMBERS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Optional Plug-In Cards</td>
<td>PAXCDS</td>
<td>Dual Setpoint Relay Output Card</td>
<td>PAXCDS10</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Quad Setpoint Relay Output Card</td>
<td>PAXCDS20</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Quad Setpoint Sinking Open Collector Output Card</td>
<td>PAXCDS30</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Quad Setpoint Sourcing Open Collector Output Card</td>
<td>PAXCDS40</td>
</tr>
<tr>
<td></td>
<td>PAXCDC</td>
<td>RS485 Serial Communications Output Card with Terminal Block</td>
<td>PAXCDC10</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Extended RS485 Serial Communications Output Card with Dual RJ11 Connector</td>
<td>PAXCDC1C</td>
</tr>
<tr>
<td></td>
<td></td>
<td>RS232 Serial Communications Output Card with Terminal Block</td>
<td>PAXCDC20</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Extended RS232 Serial Communications Output Card with 9 Pin D Connector</td>
<td>PAXCDC2C</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DeviceNet Communications Card</td>
<td>PAXCDC30</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Modbus Communications Card</td>
<td>PAXCDC40</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Extended Modbus Communications Card with Dual RJ11 Connector</td>
<td>PAXCDC4C</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Profibus-DP Communications Card</td>
<td>PAXCDC50</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Analog Output Card</td>
<td>PAXCDL10</td>
</tr>
</tbody>
</table>

| Accessories | SFPAX* | PC Configuration Software for Windows 3.x and 95 (3.5” disk) | SFPAX         |

*Software can be downloaded from www.redlion-controls.com

Shaded areas are only available for the PAXI.
1. **DISPLAY:** 6 digit, 0.56” (14.2 mm) red sunlight readable or standard green LED

2. **POWER:**
   AC Versions:
   - AC Power: 85 to 250 VAC, 50/60 Hz, 18 VA
   - Isolation: 2300 Vrms for 1 min. to all inputs and outputs. (300 V working)

   DC Versions:
   - DC Power: 11 to 36 VDC, 14 W
     (derate operating temperature to 40°C if operating <15 VDC and three plug-in option cards are installed)
   - AC Power: 24 VAC, ± 10%, 50/60 Hz, 15 VA
   - Isolation: 500 Vrms for 1 min. to all inputs and outputs (50 V working).

3. **SENSOR POWER:** 12 VDC, ±10%, 100 mA max. Short circuit protected

4. **KEYPAD:** 3 programmable function keys, 5 keys total

5. **USER INPUTS:** Three programmable user inputs
   - Max. Continuous Input: 30 VDC
   - Isolation To Sensor Input Commons: Not isolated
   - Response Time: 6 msec. typical; function dependent. Certain resets, stores and inhibits respond within 25 usec if an edge occurs with the associated counter or within 6 msec if no count edge occurs with the associated counter. These functions include T-PHE, T-PHE, H-PHE, and P-PHE. Once activated, all functions are latched for 50 msec min. to 100 msec max. After that period, another edge/level may be recognized.

6. **MEMORY:** Nonvolatile E2PROM retains all programmable parameters and display values.

7. **CERTIFICATIONS AND COMPLIANCES:**
   - SAFETY
     - UL Recognized Component, File #E179259, UL3101-1, CSA C22.2 No. 1010-1
     - Recognized to U.S. and Canadian requirements under the Component Recognition Program of Underwriters Laboratories, Inc.
     - UL Listed, File #E137808, UL508, CSA C22.2 No. 14-M95
     - LISTED by Und. Lab. Inc. to U.S. and Canadian safety standards
     - Type 4X Enclosure rating (Face only), UL50
     - IEC/IEEE CB Scheme Test Certificate #UL5834B/UL
     - CB Scheme Test Report #02ME04503-04122002
     - Issued by Underwriters Laboratories, Inc.
     - IEC 1010-1, EN 61010-1: Safety requirements for electrical equipment for measurement, control, and laboratory use, Part 1.
     - IP65 Enclosure rating (Face only), IEC 529
     - IP20 Enclosure rating (Rear of unit), IEC 529

8. **ELECTROMAGNETIC COMPATIBILITY**
   - **Immunity to EN 50082-2**
     - Electrostatic discharge
       - 61000-4-2 Level 2: 4 Kv contact
       - Level 3: 8 Kv air
     - Electromagnetic RF fields
       - 61000-4-3 Level 3: 10 V/m
       - 80 MHz - 1 GHz
     - Fast transients (burst)
       - 61000-4-4 Level 4: 2 Kv I/O
       - Level 3: 2 Kv power
     - RF conducted interference
       - 61000-4-6 Level 3: 10 V/rms
       - 150 KHz - 80 MHz
     - Simulation of cordless telephones
       - ENV 50204 Level 3: 10 V/m
       - 900 MHz ±5 MHz
       - 200 Hz, 50% duty cycle

9. **ENVIRONMENTAL CONDITIONS:**
   - Operating Temperature Range: 0 to 50°C (0 to 45°C with all three plug-in cards installed)
   - Storage Temperature Range: -40 to 60°C
   - Operating and Storage Humidity: 0 to 85% max. relative humidity non-condensing
   - Altitude: Up to 2000 meters

10. **CONNECTIONS:**
    - High compression cage-clamp terminal block
    - Wire Strip Length: 0.3” (7.5 mm)
    - Wire Gage: 30-14 AWG copper wire
    - Torque: 4.5 inch-lbs (0.51 N-m) max.

11. **CONSTRUCTION:** This unit is rated for NEMA 4X/IP65 outdoor use. IP20 Touch safe. Installation Category II, Pollution Degree 2. One piece bezel/case. Flame resistant. Synthetic rubber keypad. Panel gasket and mounting clip included.

**WEIGHT:** 10.1 oz. (286 g)
MODEL PAXC - 1/8 DIN COUNTER

PAXC SPECIFICATIONS

MAXIMUM SIGNAL FREQUENCIES:
To determine the maximum frequency for the input(s), first answer the questions with a yes (Y) or no (N). Next determine the Count Mode to be used for the counter(s). If dual counters are used with different Count Modes, then the lowest frequency applies to both counters.

<table>
<thead>
<tr>
<th>FUNCTION QUESTIONS</th>
<th>Single: Counter A or B</th>
<th>Dual: Counter A &amp; B</th>
</tr>
</thead>
<tbody>
<tr>
<td>Are any setpoints used?</td>
<td>N</td>
<td>N</td>
</tr>
<tr>
<td>Is Counter C used?</td>
<td>N</td>
<td>Y</td>
</tr>
<tr>
<td>COUNT MODE (Values are in KHz)</td>
<td>Count x1</td>
<td>34</td>
</tr>
<tr>
<td>Quadrature x1</td>
<td>22</td>
<td>19</td>
</tr>
<tr>
<td>Quadrature x2</td>
<td>17</td>
<td>13</td>
</tr>
<tr>
<td>Quadrature x4</td>
<td>8</td>
<td>6</td>
</tr>
</tbody>
</table>

Notes:
1. Counter Modes are explained in the Module 1 programming section.
2. Listed values are with frequency DIP switch set on HI frequency.

ANNUNCIATORS:
A - Counter A
B - Counter B
C - Counter C
+- Upper significant digit display of counter
SP1 - setpoint 1 output state
SP2 - setpoint 2 output state
SP3 - setpoint 3 output state
SP4 - setpoint 4 output state

COUNTER DISPLAYS:
Maximum display: 8 digits: ± 99999999 (greater than 6 digits display
Alternates between high order and low order.)

INPUTS A and B:
DIP switch selectable to accept pulses from a variety of sources including
switch contacts, TTL outputs, magnetic pickups and all standard RLC sensors.
LOGIC: Input trigger levels VIL = 1.5 V max.; VIH = 3.75 V min.
Current sinking: Internal 7.8 KΩ pull-up to +12 VDC, IMAX = 1.9 mA.
Current sourcing: Internal 3.9 KΩ pull-down, 7.3 mA max. @ 28 VDC,
VMAX = 30 VDC.
Filter: Damping capacitor provided for switch contact bounce. Limits
input frequency to 50 Hz and input pulse widths to 10 msec. minimum.
DUAL COUNT MODES:
When any dual count mode is used, then User Inputs 1 and/or 2 will
accept the second signal of each signal pair. The user inputs do not have
the Logic/Mag, HI/LO Freq, and Sink/Source input setup switches. The
user inputs are inherently a logic input with no low frequency filtering.
Any mechanical contacts used for these inputs in a dual count mode
must be debounced externally. The user input may only be selected for
sink/source by the User Jumper placement.

MODEL PAXR - 1/8 DIN RATE METER

PAXR SPECIFICATIONS

ANNUNCIATORS:
* - Rate
H - Maximum (High) Rate
L - Minimum (Low) Rate
SP1 - setpoint 1 output state
SP2 - setpoint 2 output state
SP3 - setpoint 3 output state
SP4 - setpoint 4 output state

RATE DISPLAY:
Accuracy: ±0.01%
Minimum Frequency: 0.01 Hz
Maximum Frequency: 34 KHz
Maximum Display: 5 Digits: 99999
Adjustable Display (low) Update: 0.1 to 99.9 seconds
Over Range Display: “D D D”

INPUT A:
DIP switch selectable to accept pulses from a variety of sources including
TTL outputs, magnetic pickups and all standard RLC sensors.
LOGIC: Input trigger levels VIL = 1.5 V max.; VIH = 3.75 V min.
Current sinking: Internal 7.8 KΩ pull-up to +12 VDC, IMAX = 1.9 mA.
Current sourcing: Internal 3.9 KΩ pull-down, 7.3 mA max. @ 28 VDC,
VMAX = 30 VDC.
MAGNETIC PICKUP:
Sensitivity: 200 mV peak
Hysteresis: 100 mV
Input impedance: 3.9 KΩ @ 60 Hz
Maximum input voltage: ±40 V peak, 30 Vrms

● 6-DIGIT LED DISPLAY (Alternating 8 digits for counting)
● DUAL COUNT QUAD INPUTS
● UP TO 3 COUNTER DISPLAYS
● SETPOINT ALARM OUTPUTS (W/Plug-in card)

● 5-DIGIT LED DISPLAY
● RATE INDICATION
● MINIMUM/MAXIMUM RATE DISPLAYS
● SETPOINT ALARM OUTPUTS (W/Plug-in card)
MODEL PAXI - 1/8 DIN COUNTER/ RATE METER

- COUNT, RATE AND SLAVE DISPLAY
- 6-DIGIT 0.56" RED SUNLIGHT READABLE DISPLAY
- VARIABLE INTENSITY DISPLAY
- 10 POINT SCALING (FOR NON-LINEAR PROCESSES)
- FOUR SETPOINT ALARM OUTPUTS (W/OPTION CARD)
- RETRANSMITTED ANALOG OUTPUT (W/OPTION CARD)
- COMMUNICATION AND BUS CAPABILITIES (W/OPTION CARD)
- BUS CAPABILITIES; DEVICENET, MODBUS, AND PROFIBUS-DP
- PC SOFTWARE AVAILABLE FOR METER CONFIGURATION

PAXI SPECIFICATIONS

MAXIMUM SIGNAL FREQUENCIES TABLE
To determine the maximum frequency for the input(s), first answer the questions with a yes (Y) or no (N). Next determine the Count Mode to be used for the counter(s). If dual counters are used with different Count Modes, then the lowest frequency applies to both counters.

<table>
<thead>
<tr>
<th>FUNCTION QUESTIONS</th>
<th>Single: Counter A or B (with/without rate) or Rate only</th>
<th>Dual: Counter A &amp; B or Rate not assigned to active single counter</th>
</tr>
</thead>
<tbody>
<tr>
<td>Are any setpoints used?</td>
<td>N N N N Y Y Y Y</td>
<td>N N N N Y Y Y Y</td>
</tr>
<tr>
<td>Is Prescaler Output used?</td>
<td>N N Y Y N N Y Y</td>
<td>N N Y Y N N Y Y</td>
</tr>
<tr>
<td>Is Counter C used?</td>
<td>N Y N Y N Y N Y</td>
<td>N Y N Y N Y N Y</td>
</tr>
<tr>
<td>COUNT MODE (Values are in KHz)</td>
<td>(Values are in KHz)</td>
<td></td>
</tr>
<tr>
<td>Count x1</td>
<td>34 25 21 17</td>
<td>18 15 13 11</td>
</tr>
<tr>
<td>Count x2</td>
<td>17 13 16 12</td>
<td>9 7 8 7</td>
</tr>
<tr>
<td>Quadrature x1</td>
<td>22 19 20 17</td>
<td>12 10 11 10</td>
</tr>
<tr>
<td>Quadrature x2</td>
<td>17 13 16 12</td>
<td>9 7 8 6</td>
</tr>
<tr>
<td>Quadrature x4</td>
<td>8 6 8 6</td>
<td>4 3 4 3</td>
</tr>
<tr>
<td>Rate Only</td>
<td>34 N/A 21 N/A</td>
<td>34 N/A 21 N/A</td>
</tr>
</tbody>
</table>

Notes:
1. Counter Modes are explained in the Module 1 programming section.
2. If using Rate with single counter with direction or quadrature, assign it to Input A for the listed frequency.
3. * Double the listed value for Rate frequency.
4. Listed values are with frequency DIP switch set on HI frequency.
5. Derate listed frequencies by 20% during serial communications. (Placing a 5 msec. delay between serial characters will eliminate the derating.)

ANNUNCIATORS:
A - Counter A
B - Counter B
C - Counter C
r - Rate
H - Maximum (High) Rate
L - Minimum (Low) Rate
SD - Upper significant digit display of counter
SP1 - setpoint 1 output state
SP2 - setpoint 2 output state
SP3 - setpoint 3 output state
SP4 - setpoint 4 output state

RATE DISPLAY:
Accuracy: ±0.01%
Minimum Frequency: 0.01 Hz
Maximum Frequency: see Max Signal Frequencies Table.
Maximum Display: 5 Digits: 99999
Adjustable Display (low) Update: 0.1 to 99.9 seconds
Over Range Display: “" or """

COUNTER DISPLAYS:
Maximum display: 8 digits: ±99999999 (greater than 6 digits display
Alternates between high order and low order.)

INPUTS A and B:
DIP switch selectable to accept pulses from a variety of sources including switch contacts, TTL outputs, magnetic pickups and all standard RLC sensors.
LOGIC: Input trigger levels \( V_{IL} = 1.5 \text{ V max.} \); \( V_{IH} = 3.75 \text{ V min.} \)
Current sinking: Internal 7.8 \( \Omega \) pull-up to +12 VDC, \( I_{MAX} = 1.9 \text{ mA.} \)
Current sourcing: Internal 3.9 \( \Omega \) pull-down, 7.3 mA max. @ 28 VDC,
\( V_{MAX} = 30 \text{ VDC.} \)
Filter: Damping capacitor provided for switch contact bounce. Limits input frequency to 50 Hz and input pulse widths to 10 msec. minimum.

MAGNETIC PICKUP:
Sensitivity: 200 mV peak
Hysteresis: 100 mV
Input impedance: 3.9 \( \Omega \) @ 60 Hz
Maximum input voltage: ±40 V peak, 30 Vrms

DUAL COUNT MODES:
When any dual count mode is used, then User Inputs 1 and/or 2 will accept the second signal of each signal pair. The user inputs do not have the Logic/Mag, HI/LO Freq, and Sink/Source input setup switches. The user inputs are inherently a logic input with no low frequency filtering. Any mechanical contacts used for these inputs in a dual count mode must be debounced externally. The user input may only be selected for sink/source by the User Jumper placement.

PRESCALER OUTPUT:
NPN Open Collector: \( I_{SNK} = 100 \text{ mA max.} \); \( V_{OL} = 1 \text{ VDC max.} \)
\( V_{OH} = 30 \text{ VDC max.} \) With duty cycle of 25% min. and 50 % max.
OPTIONAL PLUG-IN OUTPUT CARDS

WARNING: Disconnect all power to the unit before installing Plug-in cards.

Adding Option Cards
The PAX and MPAX series meters can be fitted with up to three optional plug-in cards. The details for each plug-in card can be reviewed in the specification section below. Only one card from each function type can be installed at one time. The function types include Setpoint Alarms (PAXCDS), Communications (PAXCDC), and Analog Output (PAXCDL). The plug-in cards can be installed initially or at a later date.

PAXI COMMUNICATION CARDS (PAXCDC)
A variety of communication protocols are available for the PAX and MPAX series. Only one of these cards can be installed at a time. When programming the unit via RLCPro, a Windows® based program, the RS232 or RS485 Cards must be used.
PAXCDC10 - RS485 Serial (Terminal)  PAXCDC30 - DeviceNet
PAXCDC1C - RS485 Serial (Connector)  PAXCDC40 - Modbus (Terminal)
PAXCDC20 - RS232 Serial (Terminal)  PAXCDC4C - Modbus (Connector)
PAXCDC2C - RS232 Serial (Connector)  PAXCDC50 - Profibus-DP

SERIAL COMMUNICATIONS CARD
Type: RS485 or RS232
Isolation To Sensor & User Input Commons: 500 Vrms for 1 min.
Working Voltage: 50 V. Not Isolated from all other commons.
Data: 7/8 bits
Baud: 300 to 19,200
Parity: no, odd or even
Bus Address: Selectable 0 to 99, Max. 32 meters per line (RS485)
Transmit Delay: Selectable for 2 to 50 msec or 50 to 100 msec (RS485)

DEVICENET™ CARD
Compatibility: Group 2 Server Only, not UCMM capable
Baud Rates: 12.5Kbaud, 250 Kbaud, and 500 Kbaud
Bus Interface: Phillips 82C250 or equivalent with MIS wiring protection per DeviceNet™ Volume I Section 10.2.2
Node Isolation: Bus powered, isolated node
Host Isolation: 500 Vrms for 1 minute (50 V working) between DeviceNet™ and meter input common.

MODBUS CARD
Type: RS485; RTU and ASCII MODBUS modes
Isolation To Sensor & User Input Commons: 500 Vrms for 1 minute.
Working Voltage: 50 V. Not isolated from all other commons.
Baud Rates: 300 to 38400.
Data: 7/8 bits
Parity: No, Odd, or Even
Addresses: 1 to 247.
Transmit Delay: Programmable; See Transmit Delay explanation.

PROFIBUS-DP CARD
Fieldbus Type: Profibus-DP as per EN 50170, implemented with Siemens SPC3 ASCII
Conformance: PNO Certified Profibus-DP Slave Device
Baud Rates: Automatic baud rate detection in the range 9.6 Kbaud to 12 Mbaud
Station Address: 0 to 126, set by the master over the network. Address stored in non-volatile memory.
Connection: 9-pin Female D-Sub connector
Network Isolation: 500 Vrms for 1 minute (50 V working) between Profibus network and sensor input commons. Not isolated from all other commons.

PROGRAMMING SOFTWARE
The SFPAx is a Windows® based program that allows configuration of the PAX meter from a PC. Using the SFPAx makes it easier to program the PAX meter and allows saving the PAX program in a PC file for future use. On-line help is available within the software. A PAX serial plug-in card is required to program the meter using the software.

SETPOINT CARDS (PAXCDS)
The PAX and MPAX series has 4 available setpoint alarm output plug-in cards. Only one of these cards can be installed at a time. (Logic state of the outputs can be reversed in the programming.) These plug-in cards include:
PAXCDS10 - Dual Relay, FORM-C, Normally open & closed
PAXCDS20 - Quad Relay, FORM-A, Normally open only
PAXCDS30 - Isolated quad sinking NPN open collector
PAXCDS40 - Isolated quad sourcing PNP open collector

DUAL RELAY CARD
Type: Two FORM-C relays
Isolation To Sensor & User Input Commons: 2000 Vrms for 1 min.
Working Voltage: 240 Vrms
Contact Rating:
One Relay Energized: 5 amps @ 120/240 VAC or 28 VDC (resistive load), 1/8 HP @ 120 VAC, inductive load
Total current with both relays energized not to exceed 5 amps
Life Expectancy: 100 K cycles min. at full load rating. External RC snubber extends relay life for operation with inductive loads
Response Time: 5 msec. nominal with 3 msec. nominal release
Time Accuracy: Counter = ± 0.01% + 10 msec.
Rate = ± 0.01% + 20 msec.

QUAD RELAY CARD
Type: Four FORM-A relays
Isolation To Sensor & User Input Commons: 2300 Vrms for 1 min.
Working Voltage: 250 Vrms
Contact Rating:
One Relay Energized: 3 amps @ 250 VAC or 30 VDC (resistive load), 1/10 HP @ 120 VAC, inductive load
Total current with all four relays energized not to exceed 4 amps
Life Expectancy: 100K cycles min. at full load rating. External RC snubber extends relay life for operation with inductive loads
Response Time: 5 msec. nominal with 3 msec. nominal release
Time Accuracy: Counter = ± 0.01% + 10 msec.
Rate = ± 0.01% + 20 msec.

QUAD SINKING OPEN COLLECTOR CARD
Type: Four isolated sinking NPN transistors.
Isolation To Sensor & User Input Commons: 500 Vrms for 1 min.
Working Voltage: 50 V. Not isolated from all other commons.
Rating: 100 mA max @ VSA = 0.7 V max. VMAX = 30 V
Response Time: Counter = 25 msec; Rate = Low Update time
Time Accuracy: Counter = ± 0.01% + 10 msec.
Rate = ± 0.01% + 20 msec.

QUAD SOURCING OPEN COLLECTOR CARD
Type: Four isolated sourcing PNP transistors.
Isolation To Sensor & User Input Commons: 500 Vrms for 1 min.
Working Voltage: 50 V. Not isolated from all other commons.
Rating: Internal supply: 24 VDC ± 10% , 30 mA max. total
External supply: 30 VDC max., 100 mA max. each output
Response Time: Counter = 25 msec; Rate = Low Update time
Time Accuracy: Counter = ± 0.01% + 10 msec.
Rate = ± 0.01% + 20 msec.

PAXI LINEAR DC OUTPUT (PAXCDL)
Either a 0(4)-20 mA or 0-10 V retransmitted linear DC output is available from the analog output plug-in card. The programmable output low and high scaling can be based on various display values. Reverse slope output is possible by reversing the scaling point positions.
PAXCDL10 - Retransmitted Analog Output Card

ANALOG OUTPUT CARD
Types: 0 to 20 mA, 4 to 20 mA or 0 to 10 VDC
Isolation To Sensor & User Input Commons: 500 Vrms for 1 min.
Working Voltage: 50 V. Not isolated from all other commons.
Accuracy: 0.17% of FS (18 to 28°C); 0.4% of FS (0 to 50°C)
Resolution: 1/3500
Compliance: 10 VDC; 10 KΩ load min., 20 mA; 500 Ω load max.
Response Time: 50 msec. max., 10 msec. typ.
1.0 INSTALLING THE METER

Installation

The PAX meets NEMA 4X/IP65 requirements for indoor use when properly installed. The unit is intended to be mounted into an enclosed panel. Prepare the panel cutout to the dimensions shown. Remove the panel latch from the unit. Slide the panel gasket over the rear of the unit to the back of the bezel. The unit should be installed fully assembled. Insert the unit into the panel cutout.

Warning: Exposed line voltage exists on the circuit boards. Remove all power to the meter and load circuits before accessing inside of the meter.

2.0 SETTING THE JUMPER AND DIP SWITCHES

To access the jumper and switches, remove the meter base from the meter case by firmly squeezing and pulling back on the side rear finger tabs. This should lower the latch below the case slot (which is located just in front of the finger tabs). It is recommended to release the latch on one side, then start the other side latch.

2.1 SETTING THE JUMPER

The meter has one jumper for user input logic. When using the user inputs this jumper must be set before applying power. The Main Circuit Board figure shows the location of the jumper and DIP switch.

The user input jumper determines signal logic for the user inputs, when they are used with user functions or for input signal direction. All user inputs are set by this jumper.

2.2 SETTING THE INPUT DIP SWITCHES

The meter has six DIP switches for Input A and Input B terminal set-up that must be set before applying power. NOTE: The PAXR only uses switches 1-3.

Switches 3 and 6

<table>
<thead>
<tr>
<th>Switch</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>Hi Freq.</td>
</tr>
<tr>
<td>6</td>
<td>LO Freq.</td>
</tr>
</tbody>
</table>

Switches 2 and 5

<table>
<thead>
<tr>
<th>Switch</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>SRC.</td>
</tr>
<tr>
<td>5</td>
<td>SNK.</td>
</tr>
<tr>
<td>3</td>
<td>Logic</td>
</tr>
<tr>
<td>4</td>
<td>Hi Freq.</td>
</tr>
</tbody>
</table>

Switches 1 and 4

<table>
<thead>
<tr>
<th>Switch</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Logic</td>
</tr>
<tr>
<td>4</td>
<td>Logic</td>
</tr>
</tbody>
</table>

SWITCHES 3 and 6

Hi Frequency: Removes damping capacitor and allows max. frequency.
LO Frequency: Adds a damping capacitor for switch contact bounce. Also limits input frequency to 50 Hz and input pulse widths to 10 usec.

SWITCHES 2 and 5

SRC.: Adds internal 3.9 KΩ pull-down resistor, 7.3 mA max. @ 28 VDC, $V_{MAX} = 30$ VDC.
SNK.: Adds internal 7.8 KΩ pull-up resistor to +12 VDC, $I_{MAX} = 1.9$ mA.

SWITCHES 1 and 4

LOGIC: Input trigger levels $V_{IL} = 1.5$ V max.; $V_{IH} = 3.75$ V min.
MAG: 200 mV peak input (must also have SRC on). Not recommended with counting applications.
The Plug-in cards are separately purchased optional cards that perform specific functions. These cards plug into the main circuit board of the meter. The Plug-in cards have many unique functions when used with the PAX. The literature that comes with these cards should be discarded, unless it specifically states in the Plug-in Card literature that the information applies to the PAX. Note: The PAXC and PAXR only use the setpoint option card.

CAUTION: The Plug-in card and main circuit board contain static sensitive components. Before handling the cards, discharge static charges from your body by touching a grounded bare metal object. Ideally, handle the cards at a static controlled clean workstation. Also, only handle the cards by the edges. Dirt, oil or other contaminants that may contact the cards can adversely affect circuit operation.

To Install:
1. With the case open, locate the Plug-in card connector for the card type to be installed. The types are keyed by position with different main circuit board connector locations. When installing the card, hold the meter by the rear terminals and not by the front display board.*
2. Install the Plug-in card by aligning the card terminals with the slot bay in the rear cover. Be sure the connector is fully engaged and the tab on the Plug-in card rests in the alignment slot on the display board.
3. Slide the meter base back into the case. Be sure the rear cover latches fully into the case.
4. Apply the Plug-in card label to the bottom side of the meter in the designated area. Do Not Cover the vents on the top surface of the meter. The surface of the case must be clean for the label to adhere properly.

Quad Sourcing Open Collector Output Card Supply Select
* If installing the Quad sourcing Plug-in Card (PAXCDS40), set the jumper for internal or external supply operation before continuing.
4.0 WIRING THE METER

WIRING OVERVIEW

Electrical connections are made via screw-clamp terminals located on the back of the meter. All conductors should conform to the meter's voltage and current ratings. All cabling should conform to appropriate standards of good installation, local codes and regulations. It is recommended that the power supplied to the meter (DC or AC) be protected by a fuse or circuit breaker. When wiring the meter, compare the numbers embossed on the back of the meter case against those shown in wiring drawings for proper wire position.

Strip the wire, leaving approximately 0.3" (7.5 mm) bare lead exposed (stranded wires should be tinned with solder.) Insert the lead under the correct screw-clamp terminal and tighten until the wire is secure. (Pull wire to verify tightness.) Each terminal can accept up to one #14 AWG (2.55 mm), two #18 AWG (1.02 mm), or four #20 AWG (0.61 mm).

EMC INSTALLATION GUIDELINES

Although this meter is designed with a high degree of immunity to Electro-Magnetic Interference (EMI), proper installation and wiring methods must be followed to ensure compatibility in each application. The type of the electrical noise, source or coupling method into the meter may be different for various installations. The meter becomes more immune to EMI with fewer I/O connections. Cable length, routing, and shield termination are very important and can mean the difference between a successful or troublesome installation. Listed below are some EMC guidelines for successful installation in an industrial environment.

1. The meter should be mounted in a metal enclosure, which is properly connected to protective earth.
2. Use shielded (screened) cables for all Signal and Control inputs. The shield (screen) pigtail connection should be made as short as possible. The connection point for the shield depends somewhat upon the application. Listed below are the recommended methods of connecting the shield, in order of their effectiveness.
   a. Connect the shield only at the panel where the unit is mounted to earth ground (protective earth).
   b. Connect the shield to earth ground at both ends of the cable, usually when the noise source frequency is above 1 MHz.
   c. Connect the shield to common of the meter and leave the other end of the shield unconnected and insulated from earth ground.
3. Never run Signal or Control cables in the same conduit or raceway with AC power lines, conductors feeding motors, solenoids, SCR controls, and heaters, etc. The cables should be run in metal conduit that is properly grounded. This is especially useful in applications where cable runs are long and portable two-way radios are used in close proximity or if the installation is near a commercial radio transmitter.
4. Signal or Control cables within an enclosure should be routed as far as possible from contactors, control relays, transformers, and other noisy components.
5. In extremely high EMI environments, the use of external EMI suppression devices, such as ferrite suppression cores, is effective. Install them on Signal and Control cables as close to the unit as possible. Loop the cable through the core several times or use multiple cores on each cable for additional protection. Install line filters on the power input cable to the unit to suppress power line interference. Install them near the power entry point of the enclosure. The following EMI suppression devices (or equivalent) are recommended:
   Ferrite Suppression Cores for signal and control cables:
   Fair-Rite # 0443167251 (RLC# FCOR0000)
   TDK # ZCAT3035-1330A
   Steward # 28B2029-0A
   Line Filters for input power cables:
   Schaffner # FN610-1/07 (RLC# LFIL0000)
   Schaffner # FN670-1.8/07
   Corcom # 1 VR3
   Note: Reference manufacturer’s instructions when installing a line filter.
6. Long cable runs are more susceptible to EMI pickup than short cable runs. Therefore, keep cable runs as short as possible.
7. Switching of inductive loads produces high EMI. Use of snubbers across inductive loads suppresses EMI.
   Snubber: RLC# SNUB0000.

4.1 POWER WIRING

<table>
<thead>
<tr>
<th>AC Power</th>
<th>DC Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>Terminal 1: VAC</td>
<td>Terminal 1: +VDC</td>
</tr>
<tr>
<td>Terminal 2: VAC</td>
<td>Terminal 2: -VDC</td>
</tr>
</tbody>
</table>

4.2 USER INPUT WIRING

Before connecting the wires, the User Input Logic Jumper should be verified for proper position. If User Input 1 and/or 2 are wired for quadrature or directional counting, an additional switching device should not be connected to that User Input terminal. Only the appropriate User Input terminal has to be wired.

Sinking Logic

Terminals 7-9: Connect external switching device between the appropriate User Input terminal and User Comm.

The user inputs of the meter are internally pulled up to +12 V with 5.1 K resistance. The input is active when it is pulled low (<0.9 V).

Sourcing Logic

Terminals 7-9: +VDC through external switching device

Terminal 10: -VDC through external switching device

The user inputs of the meter are internally pulled down to 0 V with 5.1 K resistance. The input is active when a voltage greater than 3.6 VDC is applied.
### 4.3 INPUT WIRING

**CAUTION:** Sensor input common is NOT isolated from user input common. In order to preserve the safety of the meter application, the sensor input common must be suitably isolated from hazardous live earth referenced voltage; or input common must be at protective earth ground potential. If not, hazardous voltage may be present at the User Inputs and User Input Common terminals. Appropriate considerations must then be given to the potential of the user input common with respect to earth ground; and the common of the isolated plug-in cards with respect to input common.

If you are wiring Input B, connect signal to Terminal 6 instead of 5, and set DIP switches 4, 5, and 6 to the positions shown for 1, 2, and 3.

<table>
<thead>
<tr>
<th><strong>Magnetic Pickup</strong></th>
<th><strong>Input A</strong></th>
<th><strong>AC Inputs From Tach Generators, Etc.</strong></th>
<th><strong>Input A</strong></th>
<th><strong>Two Wire Proximity, Current Source</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Diagram" /></td>
<td><img src="image2" alt="Diagram" /></td>
<td><img src="image3" alt="Diagram" /></td>
<td><img src="image4" alt="Diagram" /></td>
<td><img src="image5" alt="Diagram" /></td>
</tr>
</tbody>
</table>

#### Current Sinking Output

- **Input A**

- **Switch or Isolated Transistor; Current Sink**

- **Current Sink Output; Quad/Direction**

- **Current Sink Output; Quad/Direction**

- **Current Sink Output; Quad/Direction**

- **Switch position is application dependent.**

- **Shaded areas not recommended for counting applications.**

### 4.4 SETPOINT (ALARMS) WIRING

#### SETPOINT PLUG-IN CARD TERMINALS

<table>
<thead>
<tr>
<th>DUAL RELAY PAXCD50</th>
<th>QUAD RELAY PAXCD50</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 = RLY1</td>
<td>20 = RLY1</td>
</tr>
<tr>
<td>21 = RLY2</td>
<td>21 = RLY2</td>
</tr>
<tr>
<td>22 = RLY3</td>
<td>22 = RLY3</td>
</tr>
<tr>
<td>23 = RLY4</td>
<td>23 = RLY4</td>
</tr>
<tr>
<td>24 = RLY5</td>
<td>24 = RLY5</td>
</tr>
<tr>
<td>25 = RLY6</td>
<td>25 = RLY6</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>QUAD SINKING PAXCD50</th>
<th>QUAD SOURCING PAXCD50</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 = COMMON</td>
<td>20 = EXTERNAL SUPPLY</td>
</tr>
<tr>
<td>21 = 01 SNK.</td>
<td>21 = 01 SRC.</td>
</tr>
<tr>
<td>22 = 02 SNK.</td>
<td>22 = 02 SRC.</td>
</tr>
<tr>
<td>23 = 03 SNK.</td>
<td>23 = 03 SRC.</td>
</tr>
<tr>
<td>24 = 04 SNK.</td>
<td>24 = 04 SRC.</td>
</tr>
<tr>
<td>25 = COMMON</td>
<td>25 = COMMON</td>
</tr>
</tbody>
</table>

#### SOURCING OUTPUT LOGIC CARD

- **+24V**
- **EXTERNAL SUPPLY (30 V MAX.)**
- **ISOLATION**
- **SOURCE OUT**
- **COMM.**

#### SINKING OUTPUT LOGIC CARD

- **+12V**
- **SINK OUT (30 V MAX.)**
- **ISOLATION**
- **COMM.**
RS232 Communications

RS232 is intended to allow two devices to communicate over distances up to 50 feet. Data Terminal Equipment (DTE) transmits data on the Transmitted Data (TXD) line and receives data on the Received Data (RXD) line. Data Computer Equipment (DCE) receives data on the TXD line and transmits data on the RXD line. The PAX emulates a DTE. If the other device connected to the meter also emulates a DTE, the TXD and RXD lines must be interchanged for communications to take place. This is known as a null modem connection. Most printers emulate a DCE device while most computers emulate a DTE device.

Some devices cannot accept more than two or three characters in succession without a pause in between. In these cases, the meter employs a busy function. As the meter begins to transmit data, the RXD line (RS232) is monitored to determine if the receiving device is “busy”. The receiving device asserts that it is busy by setting the RXD line to a space condition (logic 0). The meter then suspends transmission until the RXD line is released by the receiving device.

RS485 Communications

The RS485 communication standard allows the connection of up to 32 devices on a single pair of wires, distances up to 4,000 ft. and data rates as high as 10M baud (the PAX is limited to 19.2k baud). The same pair of wires is used to both transmit and receive data. RS485 is therefore always half-duplex, that is, data cannot be received and transmitted simultaneously.

4.6 PAXI ANALOG OUTPUT WIRING

ANALOG OPTION CARD FIELD TERMINALS

16 + 0–10V ANALOG OUTPUT

17 –

18 + 0–20mA ANALOG OUTPUT

19 –

4.7 PAXI PRESCALER OUTPUT WIRING

5.0 REVIEWING THE FRONT BUTTONS AND DISPLAY

KEY

DSP Index display through the selected displays.

PAR Access Programming Mode

F1▲ Function key 1; hold for 3 seconds for Second Function 1 **

F2▼ Function key 2; hold for 3 seconds for Second Function 2 **

RST Reset (Function key) ***

* Counters B, and C are locked out in Factory Settings (PAXC and PAXI only).

** Factory setting for the F1, and F2 keys is NO mode.

*** Factory setting for the RST key is $\text{RST}$ (Reset Display).

PROGRAMMING MODE OPERATION

Quit programming and return to Display Mode

Store selected parameter and index to next parameter

Increment selected parameter value or selections

Decrement selected parameter value or selections

Advances digit location in parameter values
6.0 PROGRAMMING THE METER

OVERVIEW

PROGRAMMING MENU

PROGRAMMING MODE ENTRY (PAR KEY)

The meter normally operates in the Display Mode. No parameters can be programmed in this mode. The Programming Mode is entered by pressing the PAR key. If it is not accessible then it is locked by either a security code, or a hardware lock.

Two types of programming modes are available. Quick Programming Mode permits only certain parameters to be viewed and/or modified. All meter functions continue to operate except the front panel keys change to Programming Mode Operations. Quick Programming Mode is configured in Module 3. Full Programming Mode permits all parameters to be viewed and modified. In this mode, incoming counts may not be recognized correctly, the front panel keys change to Programming Mode Operations and certain user input functions are disabled. Throughout this document, Programming Mode (without Quick in front) always refers to “Full” Programming.

MODULE ENTRY (ARROW & PAR KEYS)

The Programming Menu is organized into nine modules. These modules group together parameters that are related in function. The display will alternate between &! and the present module. The arrow keys (F1 & F2) are used to select the desired module. The displayed module is entered by pressing the PAR key.

MODULE MENU (PAR KEY)

Each module has a separate module menu (which is shown at the start of each module discussion). The PAR key is pressed to advance to a particular parameter to be changed, without changing the programming of preceding parameters. After completing a module, the display will return to &! . Programming may continue by accessing additional modules.

SELECTION / VALUE ENTRY (ARROW & PAR KEYS)

For each parameter, the display alternates between the present parameter and the selections/value for that parameter. The arrow keys (F1 & F2) are used to move through the selections/values for that parameter. Pressing the PAR key, stores and activates the displayed selection/value. This also advances the meter to the next parameter.

For numeric values, the RST key may be used to select a specific digit to be changed. Once a digit is selected, the arrow keys are used to increment or decrement that digit to the desired number.

PROGRAMMING MODE EXIT (DSP KEY or at &!)

The Programming Mode is exited by pressing the DSP key (from anywhere in the Programming Mode) or the PAR key (with &! displayed). This will commit any stored parameter changes to memory and return the meter to the Display Mode. If a parameter was just changed, the PAR key should be pressed to store the change before pressing the DSP key. (If power loss occurs before returning to the Display Mode, verify recent parameter changes.)

PROGRAMMING TIPS

It is recommended to start with Module 1 for counting and Module 4 for rate. If lost or confused while programming, press the DSP key and start over. When programming is complete, it is recommended to record the parameter programming on the Parameter User Chart and lock out parameter programming with a user input or lock-out code.

FACTORY SETTINGS

Factory Settings may be completely restored in Module 9. This is a good starting point for programming problems. Most parameters can be left at their Factory Settings without affecting basic start-up. These parameters are identified throughout the module explanations.

ALTERNATING SELECTION DISPLAY

In the explanation of the modules, the following dual display with arrows will appear. This is used to illustrate the display alternating between the parameter on top and the parameter’s Factory Setting on the bottom. In most cases, selections and values for the parameter will be listed on the right.

6.1 MODULE 1 - COUNT A & B INPUT PARAMETERS (1- IINP)

Module 1 is the programming for Counter A, Counter B and the Prescaler Output. Counter B parameters follow the Prescaler parameters. For maximum input frequency, the counters should be set to mode NONE and the Prescaler to NO when they are not in use. When set to NONE or NO, the remaining related parameters are not accessible. A corresponding annunciator indicates the counter being shown in the Display Mode. An Exchange Parameter Lists feature for scale factors and count load values is explained in Module 2.
COUNTER A OPERATING MODE

Select the operating mode for Counter A.

<table>
<thead>
<tr>
<th>SELECTION</th>
<th>MODE</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>NONE</td>
<td></td>
<td>None</td>
</tr>
<tr>
<td>CNT</td>
<td>Count X1</td>
<td>Adds Input A falling edge.</td>
</tr>
<tr>
<td>CNTUD</td>
<td>Count X1</td>
<td>Adds Input A falling edge if Input B is high. Subtracts Input A falling edge if Input B is low.</td>
</tr>
<tr>
<td>DCTUD</td>
<td>Count X1</td>
<td>Adds Input A falling edge if User 1 is high. Subtracts Input A falling edge if User 1 is low.</td>
</tr>
<tr>
<td>W/DIR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>QWAD1</td>
<td>Quad X1</td>
<td>Adds Input A rising edge when Input B is high. Subtracts Input A rising edge when Input B is low.</td>
</tr>
<tr>
<td>QWAD2</td>
<td>Quad X2</td>
<td>Adds Input A rising edge when Input B is high and Input A rising edge when Input B is low.</td>
</tr>
<tr>
<td>QWAD4</td>
<td>Quad X4</td>
<td>Adds Input A rising edge when Input B is high, Input A falling edge when Input B is low, Input B rising edge when Input A is high, and Input B falling edge when Input A is low.</td>
</tr>
<tr>
<td>DQWAD1</td>
<td>Quad X1</td>
<td>Adds Input A rising edge when User 1 is high. Subtracts Input A falling edge when User 1 is high.</td>
</tr>
<tr>
<td>DQWAD2</td>
<td>Quad X2</td>
<td>Adds Input A rising edge when User 1 is high and Input A rising edge when User 1 is low.</td>
</tr>
<tr>
<td>CNT2</td>
<td>Count X2</td>
<td>Adds Input A rising and falling edges.</td>
</tr>
<tr>
<td>CNTUD2</td>
<td>Count X2</td>
<td>Adds Input A rising and falling edges if Input B is high. Subtracts Input A rising and falling edge if Input B is low.</td>
</tr>
<tr>
<td>DCTUD2</td>
<td>Count X2</td>
<td>Adds Input A rising and falling edges if User 1 is high. Subtracts Input A rising and falling edge if User 1 is low.</td>
</tr>
</tbody>
</table>

COUNTER A SCALE FACTOR

The number of input counts is multiplied by the scale factor and the scale multiplier to obtain the desired process value. A scale factor of 1.00000 will result in the display of the actual number of input counts. (Details on scaling calculations are explained at the end of this section.)

COUNTER A SCALE MULTIPLIER *

The number of input counts is multiplied by the scale multiplier and the scale factor to obtain the desired process value. A scale multiplier of 1 will result in only the scale factor affecting the display. (Details on scaling calculations are explained at the end of this section.)

COUNTER A COUNT LOAD VALUE *

When reset to count load action is selected, Counter A will reset to this value.

COUNTER A RESET POWER-UP *

Counter A may be programmed to reset at each meter power-up.

PAXI: PRESCALER OUTPUT ENABLE *

This enables the prescaler output. The prescaler output is useful for providing a lower frequency scaled pulse train to a PLC or another external counter. On each falling edge of Input A, the prescaler output register increments by the prescaler scale value (PR URL). When the register equals or exceeds 1.0000, a pulse is output and the register is lowered by 1.0000. The prescaler register is reset to zero whenever Counter A is reset (except for Setpoint Counter Auto Reset). (See Prescaler Output Figure.)

PAXI: PRESCALER SCALE VALUE *

The prescaler output frequency is the Input A frequency times the prescaler scale value.

* Factory Setting can be used without affecting basic start-up.
COUNTER B OPERATING MODE

<table>
<thead>
<tr>
<th>SELECTION</th>
<th>MODE</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>None</td>
<td>Count X1</td>
<td>Adds Input B falling edge.</td>
</tr>
<tr>
<td>cnt</td>
<td>Count X1</td>
<td>Adds Input B falling edge if User 2 is high. Subtracts Input B falling edge if User 2 is low.</td>
</tr>
<tr>
<td>dcntud</td>
<td>Count X1</td>
<td>Adds Input B rising edge if User 2 is high. Subtracts Input B falling edge when User 2 is high.</td>
</tr>
<tr>
<td>dquAd1</td>
<td>Quad X1</td>
<td>Adds Input B rising edge when User 2 is high. Subtracts Input B falling edge when User 2 is low.</td>
</tr>
<tr>
<td>dquAd2</td>
<td>Quad X2</td>
<td>Adds Input B rising edge when User 2 is high and Input B falling edge when User 2 is low.</td>
</tr>
<tr>
<td>cnt2</td>
<td>Count X2</td>
<td>Adds Input B rising and falling edges.</td>
</tr>
<tr>
<td>dctud2</td>
<td>Count X2</td>
<td>Adds Input B rising and falling edges if User 2 is User 2 is low.</td>
</tr>
</tbody>
</table>

COUNTER B SCALE MULTIPLIER *

The number of input counts is multiplied by the scale multiplier and the scale factor to obtain the desired process value. A scale multiplier of 1 will result in only the scale factor affecting the display. (Details on scaling calculations are explained at the end of this section.)

COUNTER B CNT LOAD VALUE *

When reset to count load action is selected, Counter B will reset to this value.

COUNTER B SCALE FACTOR

The number of input counts is multiplied by the scale factor and the scale multiplier to obtain the desired process value. A scale factor of 1.00000 will result in the display of the actual number of input counts. (Details on scaling calculations are explained at the end of this section.)

COUNTER B DECIMAL POSITION

This selects the decimal point position for Counter B and any setpoint value assigned to Counter B. The selection will also affect Counter B scale factor calculations.

COUNTER B RESER POWER-UP *

Counter B may be programmed to reset at each meter power-up.

8 DIGIT COUNT VALUES

Any counter display value below -999999 or above 9999999 (less decimal point) will consist of a two part display. This display alternates between the least 6 significant digits and the remaining most significant digits beginning with "9" in the display. If the display exceeds ±99999999 the display will roll to zero and continue counting. Outputs cannot be set to counter values above 6 digits. The annunciator, indicating the counter being displayed, will flash when the value is above 6 digits.

SCALING CALCULATIONS

Each counter has the ability to scale an input signal to a desired display value. This is accomplished by the counter mode (X-EN), scale factor (XSCFAC), scale multiplier (XSCMLR) and decimal point (XDEEP). The scale factor is calculated using:

\[
SF = \text{Desired Display Decimal DDD} \\
\times (\text{Number of pulses per 'single' unit} \times CM \times SM)
\]

Where:

- Desired Display Decimal DDD
- XDEEP: Counter Decimal Selection
- CM: Counter Mode (X-EN) times factor of the mode 1, 2 or 4.
- SM: Scale Multiplier (XSCMLR) selection of 1, 0.1 or 0.01.

Number of pulses per 'single' unit: pulses per unit generated by the process (i.e. # of pulses per foot)

Example:

1. Show feet to the hundredths (0.00) with 100 pulses per foot:
   Scale factor would be 100 / (100 x 1 x 1) = 1
   (In this case, the scale multiplier and counter mode factor are 1)
2. Show feet with 120 pulses per foot:
   Scale Factor would be 1 / (120 x 1 x 1) = 0.008333.
   (In this case, the scale multiplier of 0.01 could be used: 1 / (120 x 1 x 0.01) = 0.83333 or show to hundredths (0.00): 100 / (120 x 1 x 1) = 0.83333)

General Rules on Scaling

1. It is recommended that, the scale factor be as close as possible to, but not exceeding 1.00000. This can be accomplished by increasing or decreasing the counter decimal position, using the scale multiplier, or selecting a different count mode.
2. To double the number of pulses per unit, use counter modes direction X2 or quad X2. To increase it by four times, use counter mode quad X4. Using these modes will decrease the maximum input frequency.
3. A scale factor greater than 1.00000 will cause Counter display rounding. In this case, digit jumps could be caused by the internal count register rounding the display. The precision of a counter application cannot be improved by using a scale factor greater than 1. 00000.
4. The number of pulses per single unit must be greater than or equal to the DDD value for the scale factor to be less than or equal to one.
5. Lowering the scale factor can be accomplished by lowering the counter decimal position. (Example: 100 (Hundredths)/10 pulses = 10.000 lowering to 10 (Tenths)/10 = 1.000.)

Factory Setting can be used without affecting basic start-up.
Module 2 is the programming for rear terminal user inputs and front panel function keys.

Three rear terminal user inputs are individually programmable to perform specific meter control functions. While in the Display Mode, the function is executed when the user input transitions to the active state. (Refer to the user input specifications for active state response times.) Certain user input functions are disabled in “full” Programming Mode.

Three front panel function F1, F2 and RST keys are also individually programmable to perform specific meter control functions. While in the Display Mode, the primary function is executed when the key is pressed. Holding the F1 and F2 function keys for three seconds executes a secondary function. It is possible to program a secondary function without a primary function. The front panel key functions are disabled in both Programming Modes.

In most cases, if more than one user input and/or function key is programmed for the same function, the maintained (level trigger) actions will be performed while at least one of those user inputs or function keys are active. The momentary (edge trigger) actions are performed every time any of those user inputs or function keys transition to the active state. All functions are available to both user inputs and function keys.

Some of the user functions have a sublist of parameters. The sublist is accessed when PAR is pressed at the listed function. The function will only be performed for the parameters entered as YES. If a user input or function key is programmed for the same function, the maintained (level trigger) actions will be performed while at least one of those user inputs or function keys are active, and the other list values must be reprogrammed.

In this selection, NO function is performed. This is the factory setting for all user inputs and function keys except the Reset (RST) Key.

**NOTE:** When a user input is used to accept a quad or directional input signal, then that user input should be programmed for NO function.

**PROGRAMMING MODE LOCK-OUT**

Programming Mode is locked-out, as long as activated (maintained action). In Module 3, certain parameters can be set up where they are still accessible during Programming Mode Lockout. A security code can be configured to allow complete programming access during user input lockout. Function keys should not be programmed for PLOC.

**ADVANCE DISPLAY**

When activated (momentary action), the display advances to the next display that is not locked out from the Display Mode.

**RESET DISPLAY**

When activated (momentary action), the shown display is reset. This is the factory setting for the Reset (RST) Key.

**EXCHANGE PARAMETER LISTS**

Two lists of values are available for SP-1, SP-2, SP-3, SP-4, RCSCFAR, USCFAR, ECFAR, RCNLD, RNCNLD, ECNLD. The two lists are named l ISX-R and l ISX-B. If a user input is used to select the list then l ISX-R is selected when the user input is not active and and l ISX-B is selected when the user input is active, (maintained action). If a front panel key is used to select the list then the list will toggle for each key press, (momentary action). The meter will suspend ALL operations for approximately 1 msec. while the new values are loaded. The display will only indicate which list is active when the list is changed or when entering any Programming Mode.

To program the values for l ISX-R and l ISX-B, first complete the programming of all the parameters. Exit programming and switch to the other list. Re-enter programming and enter the values for SP-1, SP-2, SP-3, SP-4, RCSCFAR, USCFAR, ECFAR, RCNLD, RNCNLD, ECNLD. If any other parameters are changed then the other list values must be reprogrammed.

Shaded parameters do not apply to the PAXR.

**PAXI: PRINT REQUEST**

The meter issues a block print through the serial port when activated. The data transmitted during the print request is configured in Module 7. If the user input is still active after the transmission is complete (about 100 msec.), an additional transmission will occur. Only one transmission will take place with each function key depression. This selection will only function when a serial communications Plug-in card is installed in the meter.

**PAXI: PRINT REQUEST AND RESET DISPLAYS**

The meter issues a block print through the serial port when activated just like the Print Request function. In addition, when activated (momentary action), the meter performs a reset of the displays configured as YES. The print aspect of this action only functions when a serial communication plug-in card is installed. The reset action functions regardless.
MAINTAINED (LEVEL) RESET AND INHIBIT

The meter performs a reset and inhibits the displays configured as YES, as long as activated (maintained action).

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>A Cnt</td>
<td>Counter A</td>
<td>NO</td>
</tr>
<tr>
<td>B Cnt</td>
<td>Counter B</td>
<td>NO</td>
</tr>
<tr>
<td>C Cnt</td>
<td>Counter C</td>
<td>NO</td>
</tr>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

PAXR: MAINTAINED (LEVEL) RESET AND INHIBIT

The meter performs a reset and inhibits the displays configured as YES, as long as activated (maintained action).

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

MOMENTARY (EDGE) RESET

When activated (momentary action), the meter resets the displays configured as YES. (Momentary resets improve max. input frequencies over maintained resets.)

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

PAXR: MOMENTARY (EDGE) RESET

When activated (momentary action), the meter resets the displays configured as YES. (Momentary resets improve max. input frequencies over maintained resets.)

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

INHIBIT

The meter inhibits the displays configured as YES, as long as activated (maintained action).

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

STORE DISPLAY

The meter holds (freeze) the displays configured as YES, as long as activated (maintained action). Internally the counters and max. and min. values continue to update.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>

DEACTIVATE SETPOINT MAINTAINED (LEVEL)

The meter deactivates the setpoints configured as YES, as long as activated (maintained action). This action only functions with a Setpoint card installed.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP-1</td>
<td>Setpoint 1</td>
<td>NO</td>
</tr>
<tr>
<td>SP-2</td>
<td>Setpoint 2</td>
<td>NO</td>
</tr>
<tr>
<td>SP-3</td>
<td>Setpoint 3</td>
<td>NO</td>
</tr>
<tr>
<td>SP-4</td>
<td>Setpoint 4</td>
<td>NO</td>
</tr>
</tbody>
</table>

DEACTIVATE SETPOINT MOMENTARY (EDGE)

When activated (momentary action), the meter deactivates the setpoints configured as YES. This action only functions with a Setpoint card installed.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP-1</td>
<td>Setpoint 1</td>
<td>NO</td>
</tr>
<tr>
<td>SP-2</td>
<td>Setpoint 2</td>
<td>NO</td>
</tr>
<tr>
<td>SP-3</td>
<td>Setpoint 3</td>
<td>NO</td>
</tr>
<tr>
<td>SP-4</td>
<td>Setpoint 4</td>
<td>NO</td>
</tr>
</tbody>
</table>

HOLD SETPOINT STATE

The meter holds the state of the setpoints configured as YES, as long as activated (maintained action). This action only functions with a Setpoint plug-in card installed.

ACTIVATE SETPOINT MAINTAINED (LEVEL)

The meter activates the setpoints configured as YES, as long as activated (maintained action). This action only functions with a Setpoint card installed.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP-1</td>
<td>Setpoint 1</td>
<td>NO</td>
</tr>
<tr>
<td>SP-2</td>
<td>Setpoint 2</td>
<td>NO</td>
</tr>
<tr>
<td>SP-3</td>
<td>Setpoint 3</td>
<td>NO</td>
</tr>
<tr>
<td>SP-4</td>
<td>Setpoint 4</td>
<td>NO</td>
</tr>
</tbody>
</table>

ACTIVATE SETPOINT MOMENTARY (EDGE)

When activated (momentary action), the meter activates the setpoints configured as YES. This action only functions with a Setpoint card installed.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP-1</td>
<td>Setpoint 1</td>
<td>NO</td>
</tr>
<tr>
<td>SP-2</td>
<td>Setpoint 2</td>
<td>NO</td>
</tr>
<tr>
<td>SP-3</td>
<td>Setpoint 3</td>
<td>NO</td>
</tr>
<tr>
<td>SP-4</td>
<td>Setpoint 4</td>
<td>NO</td>
</tr>
</tbody>
</table>

CHANGE DISPLAY INTENSITY LEVEL

When activated (momentary action), the display intensity changes to the next intensity level (of 4). The four levels correspond to Display Intensity Level (d-LEv) settings of 0, 3, 8 & 15. The intensity level, when changed via the User Input/Function Key, is not retained at power-down, unless Quick Programming or Full Programming mode is entered and exited. The meter will power-up at the last saved intensity level.

<table>
<thead>
<tr>
<th>DISPLAY</th>
<th>DESCRIPTION</th>
<th>FACTORY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max</td>
<td>Maximum</td>
<td>NO</td>
</tr>
<tr>
<td>Min</td>
<td>Minimum</td>
<td>NO</td>
</tr>
</tbody>
</table>
Module 3 is the programming for Display lock-out and “Full” and “Quick” Program lock-out.

When in the Display Mode, the available displays can be read consecutively by repeatedly pressing the DSP key. An annunciator indicates the display being shown. These displays can be locked from being visible. It is recommended that the display be set to LOC when the corresponding function is not used.

“Full” Programming Mode permits all parameters to be viewed and modified. This Programming Mode can be locked with a security code and/or user input. When locked and the PAR key is pressed, the meter enters a Quick Programming Mode. In this mode, setpoint, count load and scale factor values can still be read and/or changed per the selections below. The Display Intensity Level (LOC) parameter also appears whenever Quick Programming Mode is enabled, and the security code is greater than zero.

**SETPOINT 1 to 4 ACCESS LOCK-OUT**

The setpoint displays can be programmed for LOC, rEd, or Enb (See the following table). Accessible only with the Setpoint Plug-in card installed.

**COUNT LOAD A B C ACCESS LOCK-OUT**

These displays can be programmed for LOC, rEd, or Enb.

**SCALE FACTOR A B C ACCESS LOCK-OUT**

The Scale Factor values can be programmed for LOC, rEd, or Enb.

**SECURITY CODE**

Entry of a non-zero value will cause the prompt Code to appear when trying to access the “Full” Programming Mode. Access will only be allowed after entering a matching security code or universal code of 222. With this lock-out, a user input would not have to be configured for Program Lock-out. However, this lock-out is overridden by an inactive user input configured for Program Lock-out.

* Factory Setting can be used without affecting basic start-up.

**PROGRAMMING MODE ACCESS**

<table>
<thead>
<tr>
<th>SECURITY CODE</th>
<th>USER INPUT CONFIGURED</th>
<th>USER INPUT STATE</th>
<th>WHEN PAR KEY IS PRESSED</th>
<th>“FULL” PROGRAMMING MODE ACCESS</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>not LOC</td>
<td>————</td>
<td>“Full” Programming</td>
<td>Immediate access.</td>
</tr>
<tr>
<td>&gt;0</td>
<td>not LOC</td>
<td>————</td>
<td>Quick Programming w/Display Intensity</td>
<td>After Quick Programming with correct code # at Code prompt.</td>
</tr>
<tr>
<td>&gt;0</td>
<td>LOC</td>
<td>Active</td>
<td>Quick Programming w/Display Intensity</td>
<td>After Quick Programming with correct code # at Code prompt.</td>
</tr>
<tr>
<td>&gt;0</td>
<td>LOC</td>
<td>Not Active</td>
<td>“Full” Programming</td>
<td>Immediate access.</td>
</tr>
<tr>
<td>0</td>
<td>LOC</td>
<td>Active</td>
<td>Quick Programming</td>
<td>No access</td>
</tr>
<tr>
<td>0</td>
<td>LOC</td>
<td>Not Active</td>
<td>“Full” Programming</td>
<td>Immediate access.</td>
</tr>
</tbody>
</table>

Throughout this document, Programming Mode (without Quick in front) always refers to “Full” Programming (all meter parameters are accessible).
Module 4 is the programming for the Rate parameters. For maximum input frequency, Rate assignment should be set to No when not in use. When set to No, the remaining related parameters are not accessible. The Rate value is shown with an annunciator of ‘r’ in the Display Mode.

Note: For PAXR, r IMP is actually r IMP on the unit’s display and rDSP is actually rDSP on the unit’s display.

PAXI: RATE ASSIGNMENT

For measuring the rate (speed) of pulses on Input A, select rLK-R. For Input B select rLK-b. This assignment is independent of the counting modes.

LOW UPDATE TIME (DISPLAY UPDATE) *

LO-Udt  0.1 to 999 seconds

The Low Update Time is the minimum amount of time between display updates for the Rate display. Values of 0.1 and 0.2 seconds will update the display correctly but may cause the display to appear unsteady. The factory setting of 1.0 will update the display every second minimum.

HIGH UPDATE TIME (DISPLAY ZERO) *

HI-Udt  0.2 to 999 seconds

The High Update Time is the maximum amount of time before the Rate display is forced to zero. (For more explanation, refer to Input Frequency Calculation.) The High Update Time must be higher than the Low Update Time and higher than the desired slowest readable speed (one divided by pulses per second). The factory setting of 2.0, will force the display to zero for speeds below 0.5 Hz or a pulse every 2 seconds.

RATE DECIMAL POSITION

rLK dP  0  000  00000
  0  000  0000

This selects the decimal point position for Rate, Minimum and Maximum rate displays and any setpoint value assigned to these displays. This parameter does not affect rate scaling calculations.

PAXI: LINEARIZER SEGMENTS

SE65  0 to 9

This parameter specifies the number of linear segments used for the Rate Scaling function. Each linear segment has two scaling points which define the upper and lower endpoints of the segment. The number of segments used depends on the linearity of the process and the display accuracy required as described below.

Linear Application – 2 Scaling Points

Linear processes use a single segment (two scaling points) to provide a linear Rate display from 0 up to the maximum input frequency. For typical zero based frequency measurements (0 Hz = 0 on display), leave SE65:0 (factory setting). For non-zero based 2 scaling point applications, set SE65:1, to enter both the zero segment (r IMP 0 & rDSP 0) and segment 1 (r IMP 1 & rDSP 1).

PAXI: RATE DISPLAY VALUE FOR SCALING POINT 1

rDSP 0  0 to 999999

Confirm the Rate Display Value for the first Scaling Point is 0. This parameter is automatically set to 0 and does not appear when SE65:0. (See Note)

PAXI: RATE INPUT VALUE FOR SCALING POINT 1

r IMP 0  0 to 999999

Confirm the Rate Input Value for the first Scaling Point is 0.0. (See Note)

Note: For all linear and most non-linear applications, the Scaling Point 1 input parameter set is automatically set to 0 and does not appear when SE65:0. Consult the factory before using any non-zero values for Scaling Point 1. These parameters are automatically set to 0 and do not appear when SE65:0.

RATE DISPLAY VALUE FOR SCALING POINT 2

rDSP 1  0 to 999999

Enter the desired Rate Display Value for the second Scaling Point by using the arrow keys.

* Factory Setting can be used without affecting basic start-up.

Non-linear Application – Up to 10 Scaling Points

Non-linear processes may utilize up to nine segments (ten scaling points) to provide a piece-wise linear approximation representing the non-linear function. The Rate display will be linear throughout each individual segment (i.e. between sequential scaling points). Thus, the greater the number of segments, the greater the conformity accuracy. Several linearization equations are available in the SPPAX software.

About Scaling Points

Each Scaling Point is specified by two programmable parameters: A desired Rate Display Value (rDSP) and a corresponding Rate Input Value (r IMP). Scaling points are entered sequentially in ascending order of Rate Input Value.

Two scaling points must be programmed to define the upper and lower endpoints of the first linear segment. Setting SE65:0, automatically factory sets the first scaling point to 0.0 for typical single segment, zero based applications. When multiple segments are used, the upper scaling point for a given segment becomes the lower scaling point for the next sequential segment. Thus, for each additional segment used, only one additional scaling point must be programmed.

The following chart shows the Scaling Points, the corresponding Parameter mnemonics, and the Factory Default Settings for each point.
RATE INPUT VALUE FOR SCALING POINT 2

Enter the corresponding Rate Input Value for the second Scaling Point by using the arrow keys. Rate Input values for scaling points can be entered by using the Key-in or the Applied method described below.

**Key-in Method:**
Enter the Rate Input value (r IIP) that corresponds to the entered Rate Display value (r dSP) by pressing the F1 or F2 keys. This value is always in pulses per second (Hz).

**Applied Method:**
Apply an external rate signal to the appropriate input terminals. At the Rate Input Value (r IIP) press and hold the F1 and F2 keys at the same time. The applied input frequency (in Hz) will appear on the display. (To verify correct reading wait for at least the length of the Low Update Time. Then press and hold the F1 and F2 keys at the same time again. The new value should be ± 0.1% of the previous entered value.) Press PAR to enter the displayed frequency as the Rate Input value. To prevent the displayed value from being entered, press DSP. This will take the meter out of Programming Mode and the previous Rate Input value will remain.

**RATE DISPLAY ROUND**

<table>
<thead>
<tr>
<th>ROUND</th>
<th>1</th>
<th>5</th>
<th>20</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>2</td>
<td>10</td>
<td>50</td>
<td></td>
</tr>
</tbody>
</table>

Rounding values other than one round the Rate display to the nearest increment selected (e.g. rounding of ‘5’ causes 122 to round to 120 and 123 to round to 125). Rounding starts at the least significant digit of the Rate display.

**LOW CUT OUT**

<table>
<thead>
<tr>
<th>LOWCUT</th>
<th>0</th>
<th>999999</th>
</tr>
</thead>
</table>

The Low Cut Out value forces the Rate display to zero when the Rate display falls below the value entered.

**MAXIMUM CAPTURE DELAY TIME**

<table>
<thead>
<tr>
<th>UOT</th>
<th>0</th>
<th>999999</th>
</tr>
</thead>
</table>

When the Rate value is above the present Maximum rate value for the entered amount of time, the meter will capture that Rate value as the new Maximum value. A delay time helps to avoid false captures of sudden short spikes. Maximum detection will only function if Rate is assigned to Input A or B. The Maximum rate value is shown with an annunciator of ‘M’ in the display and will continue to function independent of being displayed.

**MINIMUM CAPTURE DELAY TIME**

<table>
<thead>
<tr>
<th>LDT</th>
<th>0</th>
<th>999999</th>
</tr>
</thead>
</table>

When the Rate value is below the present Minimum rate value for the entered amount of time, the meter will capture that Rate value as the new Minimum value. A delay time helps to avoid false captures of sudden short spikes. Minimum detection will only function if Rate is assigned to Input A or B. The Minimum rate value is shown with an annunciator of ‘L’ in the display and will continue to function independent of being displayed.

**RATE DISPLAY EXCEEDED**

If the rate of the input signal causes a display that exceeds the capacity of the Rate display (5 digits, 99999), then the display will indicate an overflow condition by showing “r loLo”. During this overflow condition, the Minimum and Maximum rate values will stay at their values even during resets.

* Factory Setting can be used without affecting basic start-up.

**RATE SCALING**

To scale the Rate, enter a Scaling Display value with a corresponding Scaling Input value. (The Display and Input values can be entered by Key-in or Applied Methods.) These values are internally plotted to a Display value of 0 and Input value of 0 Hz. A linear relationship is formed between these points to yield a rate display value that corresponds to the incoming input signal rate. The PAXI and PAXR are capable of showing a rate display value for any linear process.

**KEY-IN SCALING METHOD CALCULATION**

If a display value versus input signal (in pulses per second) is known, then those values can be entered into Scaling Display (r dSP) and Scaling Input (r IIP). No further calculations are needed.

If only the number of pulses per ‘single’ unit (i.e. # of pulses per foot) is known, then it can be entered as the Scaling Input value and the Scaling Display value will be entered as the following:

<table>
<thead>
<tr>
<th>RATE PER</th>
<th>DISPLAY (r dSP)</th>
<th>INPUT (r IIP)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Second</td>
<td>1</td>
<td># of pulses per unit</td>
</tr>
<tr>
<td>Minute</td>
<td>60</td>
<td># of pulses per unit</td>
</tr>
<tr>
<td>Hour</td>
<td>3600</td>
<td># of pulses per unit</td>
</tr>
</tbody>
</table>

**NOTES:**

1. If # of pulse per unit is less than 10, then multiply both Input and Display values by 10.
2. If # of pulse per unit is less than 1, then multiply both Input and Display values by 100.
3. If the Display value is raised or lowered, then Input value must be raised or lowered by the same proportion (i.e. Display value for per hour is entered by a third less (1200) then Input value is a third less of # of pulses per unit). The same is true if the Input value is raised or lowered, then Display value must be raised or lowered by the same proportion.
4. Both values must be greater than 0.0.

**EXAMPLE:**

1. With 15.1 pulses per foot, show feet per minute in tenths. Scaling Display = 60.0 Scaling Input = 15.1.
2. With 0.25 pulses per gallon, show whole gallons per hour. (To have greater accuracy, multiply both Input and Display values by 10.) Scaling Display = 36000 Scaling Input = 2.5.

**INPUT FREQUENCY CALCULATION**

The meter determines the input frequency by summing the number of falling edges received during a sample period of time. The sample period begins on the first falling edge. At this falling edge, the meter starts accumulating time towards Low Update and High Update values. Also, the meter starts accumulating the number of falling edges. When the time reaches the Low Update Time value, the meter looks for one more falling edge to end the sample period. If a falling edge occurs (before the High Update Time value is reached), the Rate display will update to the new value and the next sample period will start on the same edge. If the High Update Time value is reached (without receiving a falling edge after reaching Low Update Time), then the sample period will end but the Rate display will be forced to zero. The High Update Time value must be greater than the Low Update Time value. Both values must be greater than 0.0. The input frequency calculated during the sample period, is then shown as a Rate value determined by either scaling method.
6.5 MODULE 5 - COUNTER C INPUT PARAMETERS (CCTR C)

Module 5 is the programming for Counter C. For maximum input frequency, the counter operating mode should be set to \textit{NONE} when not in use. When set to \textit{NONE} the remaining related parameters are not accessible. The C annunciator indicates that Counter C is being shown in the Display Mode. An Exchange Parameter List feature for scale factor and count load values is explained in Module 2.

**COUNTER C OPERATING MODE**

- **NONE**
  - Counter C counts the incoming pulses from Counter A input as per Counter A mode of operation. The signal is scaled only according to Counter C parameters.
  - **Add Ab**
    - Counter C counts the incoming pulses from Counter A and B inputs as per Counter A and B modes of operation. The result is scaled only according to Counter C parameters.
    - Example: If Counter A is set for Count X1 mode and Counter B is set for Count X2 mode, then Counter C will increment by 1 for each pulse received on Input A and increment by 2 for each pulse received on Input B.
  - **Sub Ab**
    - Counter C counts the incoming pulses from Counter A and B inputs as per Counter A and B modes of operation and subtracts the B counts from the A counts. The result is scaled only according to Counter C parameters.
    - Example: If Counter A is set for Count X1 mode and Counter B is set for Count X2 mode, then Counter C will increment by 1 for each pulse received on Input A and decrement by 2 for each pulse received on Input B.

Note: When using Add Ab or Sub Ab, Counter A, B and C must all be reset at the same time for the math to be performed on the display values.

**COUNTER C SCALE FACTOR**

- \(0.0000\) to \(999999\)

The number of input counts is multiplied by the scale factor and the scale multiplier to obtain the desired process value. A scale factor of 1.00000 will result in the display of the actual number of input counts. For Numeric transmissions (Numeric transmissions) modes of operation, the input signal is scaled directly. For \textit{Add Ab} and \textit{Sub Ab} modes of operation, the math is performed on the input signals and then the result is scaled. To achieve correct results, both Input A and Input B must provide the same amount of pulses per unit of measurement. (Details on scaling calculations are explained at the end of Module 1 section.)

**COUNTER C SCALE MULTIPLIER**

- \(1.0000\)

The number of input counts is multiplied by the scale multiplier and the scale factor to obtain the desired process value. A scale multiplier of 1 will result in only the scale factor affecting the display. (Details on scaling calculations are explained at the end of Module 1 section.)

**COUNTER C COUNT LOAD VALUE**

- \(-999999\) to \(999999\)

When reset to count load action is selected, Counter C will reset to this value.

**COUNTER C RESET POWER-UP**

- \(YES\)
- \(NO\)

Counter C may be programmed to reset at each meter power-up.

* Factory Setting can be used without affecting basic start-up.
Module 6 is the programming for the setpoint (alarms) output parameters. To have setpoint outputs, a setpoint Plug-in card needs to be installed into the PAX (see Ordering Information). Depending on the card installed, there will be two or four setpoint outputs available. This section replaces the bulletin that comes with the setpoint plug-in card. Please discard the separate literature when using the Plug-in card with the Digital PAX. For maximum input frequency, unused Setpoints should be configured for +55 action.

The setpoint assignment and the setpoint action determine certain setpoint feature availability. The chart below illustrates this.

### SETPOINT PARAMETER AVAILABILITY

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>DESCRIPTION</th>
<th>RATE</th>
<th>COUNTER</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lit-n</td>
<td>Annunciators</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Out-n</td>
<td>Output Logic</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Sup-n</td>
<td>Power Up State</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Sp-n</td>
<td>Setpoint Value</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Trc-n</td>
<td>Setpoint Tracking</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Typ-n</td>
<td>Boundary Type</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Sbb-n</td>
<td>Standby Operation</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Hys-n</td>
<td>Setpoint Hysteresis</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Off-n</td>
<td>Setpoint Off Delay</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>On-n</td>
<td>Setpoint On Delay</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Out-n</td>
<td>Setpoint Time Out</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Auto-n</td>
<td>Counter Auto Reset</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Rs-d-n</td>
<td>Reset With Display Reset</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Rs-as-n</td>
<td>Reset When SPn1 Activates</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
<tr>
<td>Rs-a-e-n</td>
<td>Reset When SPn1 Deactivates</td>
<td>Timer Outbound</td>
<td>Latch LATCH</td>
</tr>
</tbody>
</table>

### SETPOINT SELECT

Select a setpoint (alarm output) to open the remaining module menu. (The "n" in the following parameters will reflect the chosen setpoint number.) After the chosen setpoint is programmed, the display will default to SPSEL NO. Select the next setpoint to be programmed and continue the sequence for each setpoint. Pressing PAR at SPSEL NO will exit Module 6.

### SETPOINT ANNUNCIATORS*

OFF disables the display of the setpoint annunciator. Normal (NO) displays the corresponding setpoint annunciator of an "on" alarm output. Reverse (RE) displays the corresponding setpoint annunciator of an "off" alarm output. FLASH flashes the display and the corresponding setpoint annunciator of an "on" alarm output.

### SETPOINT OUTPUT LOGIC *

Normal (NO) turns the output "on" when activated and "off" when deactivated. Reverse (RE) turns the output "off" when activated and "on" when deactivated.

### SETPOINT POWER UP STATE *

Save will restore the output to the same state it was at before the meter was powered down. On will activate the output at power up. Off will deactivate the output at power up.

* Factory Setting can be used without affecting basic start-up.
SETPOINT ACTION

OFF: When not using a setpoint, it should be set to OFF (no action).

For Counter Assignments:
- LATCH: With Latch action, the setpoint output activates when the count value equals the setpoint value. The output remains active until reset. This action is not associated with Boundary types.
- bOUND: With boundary action, the setpoint output activates when the count value is greater than or equal to (for $\text{TP} = \text{H}$) or less than or equal to (for $\text{TP} = \text{L}$) the setpoint value. The setpoint output will deactivate when the count value is less than (for $\text{TP} = \text{H}$) or greater than (for $\text{TP} = \text{L}$) the setpoint value.
- tOUt: With Timed Out action, the setpoint output activates when the count value equals the setpoint value and deactivates after the Time Out value. This action is not associated with Boundary types.

For Rate Assignments:
- LATCH: With Latch action, the setpoint output activates when the rate value is greater than or equal to the setpoint value. The output remains active until reset. This action is not associated with Boundary types.
- bOUND: With boundary action, the setpoint output activates when the rate value is greater than or equal to (for $\text{TP} = \text{H}$) or less than or equal to (for $\text{TP} = \text{L}$) the setpoint value. The setpoint output will deactivate when the rate value is less than (for $\text{TP} = \text{H}$) or greater than (for $\text{TP} = \text{L}$) the setpoint value.
- tOUt: With Timed Out action, the setpoint output cycles when the rate value is greater than or equal to (for $\text{TP} = \text{H}$) or less than or equal to (for $\text{TP} = \text{L}$) the setpoint value. The Time Out value is determined by the hysteresis value.

SETPOINT TRACKING *

If a selection other than NO is chosen, then the value of the setpoint being programmed ("n") will track the entered selection’s value. Tracking means that when the selection’s value is changed (in the Quick Programming Mode), the "n" setpoint value will also change (or follow) by the same amount.

SETPOINT STANDBY OPERATION *

Selecting YES will disable low acting setpoints at a power up until the display value crosses into the alarm “off” area. Once in the alarm “off” area, the setpoint will function according to the configured setpoint parameters.

SETPOINT ACTION

OFF LATCH tOut bOUND

SELECTION ACTION

NO No auto reset.

2E:0:0:0 Reset to zero at the start of output activation.

ClrdAS Reset to count load value at the start of output activation.

2E:0:0:0 Reset to zero at the end of output activation. (tOUt action only).

ClrdAE Reset to count load value at the end of output activation. (tOUt action only).

* Factory Setting can be used without affecting basic start-up.
PAXC & I: SETPOINT RESET WHEN SPn+1 ACTIVATES *

Select **YES**, so the setpoint output will deactivate (reset) when SPn+1 activates. (Example: SP1 deactivates when SP2 activates and SP4 when SP1 activates.) The last setpoint will wrap around to the first.

* Factory Setting can be used without affecting basic start-up.

---

**PAXR & I: SETPOINT (ALARM) FIGURES FOR RATE**

(For Reverse Action, The Alarm state is opposite.)

---

**PAXC & I: SETPOINT RESET WHEN SPn+1 DEACTIVATES **

Select **YES**, so the setpoint output will deactivate (reset) when SPn+1 deactivates and then times out (deactivates). This function may only be used if the SPn+1 is programmed for Setpoint Action of **tOut**. (Example SP1 deactivates when SP2 is activated and then times out.) The last setpoint will wrap around to the first.

---

**Factory Setting can be used without affecting basic start-up.**
Module 7 is the programming module for the Serial Communications Parameters. These parameters are used to match the serial settings of the PAXI with those of the host computer or other serial device, such as a terminal or printer. This programming module can only be accessed if an RS232 or RS485 Serial Communications card is installed.

This section also includes an explanation of the commands and formatting required for communicating with the PAXI. In order to establish serial communications, the user must have host software that can send and receive ASCII characters. Red Lion's SFPAX software can be used for configuring the PAXI (See Ordering Information). For serial hardware and wiring details, refer to section 4.5 Serial Communication Wiring.

This section replaces the bulletin shipped with the RS232 and RS485 serial communications plug-in cards. Discard the separate bulletin when using those serial plug-in cards with the PAXI. Also, this section does NOT apply to the DeviceNet, Modbus, or Profibus-DP communication cards. For details on the operation of the Fieldbus cards, refer to the bulletin shipped with each card.

**BAUD RATE**

Set the baud rate to match the other serial communications equipment on the serial link. Normally, the baud rate is set to the highest value that all the serial equipment are capable of transmitting and receiving.

**DATA BIT**

Select either 7 or 8 bit data word lengths. Set the word length to match the other serial communications equipment on the serial link.

**PARITY BIT**

Set the parity bit to match that of the other serial communications equipment on the serial link. The meter ignores the parity when receiving data and sets the parity bit for outgoing data. If no parity is selected with 7 bit word length, an additional stop bit is used to force the frame size to 10 bits.

**METER UNIT ADDRESS**

Enter the serial meter (node) address. With a single unit, an address is not needed and a value of zero can be used. With multiple units (RS485 applications), a unique 2 digit address number must be assigned to each meter.

**ABBREVIATED PRINTING**

Select no for full print or Command T transmissions (meter address, parameter data and mnemonics) or yes for abbreviated print transmissions (parameter data only). This will affect all the parameters selected in the print options. (If the meter address is 00, it will not be sent during a full transmission.)

**PRINT OPTIONS**

**PARAMETER MENU**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>Factory</th>
<th>Mnemonic</th>
</tr>
</thead>
<tbody>
<tr>
<td>Addr</td>
<td>Counter A</td>
<td>yes</td>
<td>CTA</td>
</tr>
<tr>
<td>dArt</td>
<td>Counter B</td>
<td>no</td>
<td>CTB</td>
</tr>
<tr>
<td>Par</td>
<td>Counter C</td>
<td>no</td>
<td>CTC</td>
</tr>
<tr>
<td>Rate</td>
<td>Rate</td>
<td>no</td>
<td>RTE</td>
</tr>
<tr>
<td>Max Min</td>
<td>Max. &amp; Min.</td>
<td>no</td>
<td>MIN MAX</td>
</tr>
<tr>
<td>SCFRC</td>
<td>A B C Scale Factors</td>
<td>no</td>
<td>SFA SFB SFC</td>
</tr>
<tr>
<td>CardLoad</td>
<td>A B C Count Load</td>
<td>no</td>
<td>LDA LDB LDC</td>
</tr>
<tr>
<td>SPnt</td>
<td>1 2 3 4 Setpoints</td>
<td>no</td>
<td>SP1 SP2 SP3 SP4</td>
</tr>
</tbody>
</table>

*Setpoints are plug-in card dependent.*
SENTING SERIAL COMMANDS AND DATA

When sending commands to the meter, a string containing at least one command character must be constructed. A command string consists of a command character, a value identifier, numerical data (if writing data to the meter) followed by the command terminator character * or $. The <CR> is also available as a terminator when Counter C is in the SLAVE mode.

Command String Construction

The command string must be constructed in a specific sequence. The meter does not respond with an error message to invalid commands. The following procedure details construction of a command string:

1. The first characters consist of the Node Address Specifier (N) followed by a 2 character address number. The address number of the meter is programmable. If the node address is 0, this command and the node address itself may be omitted. This is the only command that may be used in conjunction with other commands.
2. After the optional address specifier, the next character is the command character. It prints according to the selections made in print options.
3. The next character is the Register ID. This identifies the register that the command affects. The P command does not require a Register ID character. It prints according to the selections made in print options.
4. If constructing a value change command (writing data), the numeric data is sent next.
5. All command strings must be terminated with the string termination characters *, $ or when Counter C is set for slave mode <CR>. The meter does not begin processing the command string until this character is received.

See Timing Diagram figure for differences between terminating characters.

Command String Examples:
1. Address = 17, Write 350 to Setpoint 1
   String: N17VM350$  
2. Address = 5, Read Count A value, response time of 50 - 100 msec. min.  
   String: N05TA*  
3. Address = 0, Reset Setpoint 4 output  
   String: RS*

Transmitting Data To the Meter

Numeric data sent to the meter must be limited to Transmit Details listed in the Register Identification Chart. Leading zeros are ignored. Negative numbers must have a minus sign. The meter ignores any decimal point and conforms the number to the scaled resolution. (ie. The meter’s scaled decimal point position is set for 0.0 and 25 is written to a register. The value of the register is now 2.5. In this case, write a value of 250 to equal 25.0).

Note: Since the meter does not issue a reply to value change commands, follow with a transmit value command for readback verification.

Transmitting Data From the Meter

Data is transmitted from the meter in response to either a transmit command (T), a print block command (P) or User Function print request. The response from the meter is either a full field transmission or an abbreviated transmission. The meter response is established in Module 7.

Full Transmission

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2</td>
<td>2 byte Node (Meter) Address field [00-99]</td>
</tr>
<tr>
<td>3</td>
<td>&lt;SP&gt; (Space)</td>
</tr>
<tr>
<td>4-6</td>
<td>3 byte Register Mnemonic field</td>
</tr>
<tr>
<td>7-18</td>
<td>12 byte numeric data field: 10 bytes for number, one byte for sign, one byte for decimal point</td>
</tr>
<tr>
<td>19</td>
<td>&lt;CR&gt; (Carriage return)</td>
</tr>
<tr>
<td>20</td>
<td>&lt;LF&gt; (Line feed)</td>
</tr>
<tr>
<td>21</td>
<td>&lt;SP&gt; (Space)</td>
</tr>
<tr>
<td>22</td>
<td>&lt;CR&gt; (Carriage return)&lt;sup&gt;3&lt;/sup&gt;</td>
</tr>
<tr>
<td>23</td>
<td>&lt;LF&gt; (Line feed)&lt;sup&gt;3&lt;/sup&gt;</td>
</tr>
</tbody>
</table>

These characters only appear in the last line of a block print.

The first two characters transmitted (bytes 1 and 2) are the unit address. If the address assigned is 00, two spaces are substituted. A space (byte 3) follows the unit address field. The next three characters (bytes 4 to 6) are the register mnemonic. The numeric data is transmitted next.

The numeric field (bytes 7 to 18) is 12 characters long. When the requested value exceeds eight digits for count values or five digits for rate values, an * (used as an overflow character) replaces the space in byte 7. Byte 8 is always a space. The remaining ten positions of this field (bytes 9 to 18) consist of a minus sign (for negative values), a floating decimal point (if applicable), and eight positions for the requested value. The data within bytes 9 to 18 is right-aligned with leading spaces for any unfilled positions.

The end of the response string is terminated with <CR> (byte 19), and <LF> (byte 20). When a block print is finished, an extra <SP> (byte 21), <CR> (byte 22), and <LF> (byte 23) are used to provide separation between the transmissions.

Abbreviated Transmission

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-12</td>
<td>12 byte data field, 10 bytes for number, one byte for sign, one byte for decimal point</td>
</tr>
<tr>
<td>13</td>
<td>&lt;CR&gt; (Carriage return)</td>
</tr>
<tr>
<td>14</td>
<td>&lt;LF&gt; (Line feed)</td>
</tr>
<tr>
<td>15</td>
<td>&lt;SP&gt; (Space)&lt;sup&gt;3&lt;/sup&gt;</td>
</tr>
<tr>
<td>16</td>
<td>&lt;CR&gt; (Carriage return)&lt;sup&gt;3&lt;/sup&gt;</td>
</tr>
<tr>
<td>17</td>
<td>&lt;LF&gt; (Line feed)&lt;sup&gt;3&lt;/sup&gt;</td>
</tr>
</tbody>
</table>

These characters only appear in the last line of a block print.

The abbreviated response suppresses the address and register mnemonics, leaving only the numeric part of the response.

Meter Response Examples:
1. Address = 17, full field response, Count A = 875  
   17 CTA  
   875 <CR> <LF>  
2. Address = 0, full field response, Setpoint 2 = 250.5  
   SP2  
   250.5 <CR> <LF> |
| 3. Address = 0, abbreviated response, Setpoint 2 = 250, last line of block print |
| 250<CR><LF><SP><CR><LF>|
Auto/Manual Mode Register (MMR) ID: \text{U} \\
This register sets the controlling mode for the outputs. In Auto Mode (0) the 
meter controls the setpoint and analog output. In Manual Mode (1) the outputs 
are defined by the registers SOR and AOR. When transferring from auto mode 
to manual mode, the meter holds the last output value (until the register is 
changed by a write). Each output may be independently changed to auto or 
manual. In a write command string (VU), any character besides 0 or 1 in a field 
will not change the corresponding output mode.

\begin{center}
\begin{tabular}{|c|c|c|c|}
\hline
Register Value & 0-20 mA & 4-20 mA & 0-10V \\
\hline
0 & 0.000 & 4.000 & 0.000 \\
1 & 0.005 & 4.004 & 0.0025 \\
2047 & 10.000 & 12.000 & 5.000 \\
4095 & 20.000 & 20.000 & 10.000 \\
\hline
\end{tabular}
\end{center}

\textbf{Example:} \text{VU00011} places SP4 and Analog in manual.

Analog Output Register (AOR) ID: \text{W} \\
This register stores the present signal value of the analog output. The range 
of values of this register is 0 to 4095, which corresponds to the analog output 
range per the following chart:

\textit{Due to the absolute accuracy rating and resolution of the output 
card, the actual output signal may differ 0.15\% FS from the table values. The 
output signal corresponds to the range selected (0-20 mA, 4-20 mA or 0-10 V).}

\textbf{Setpoint Output Register (SOR) ID: \text{X}} \\
This register stores the states of the setpoint outputs. Reading from this 
register (TX) will show the present state of all the setpoint outputs. A “0” in the 
setpoint location means the output is off and a “1” means the output is on.

\textbf{Numeric Transmissions} \\
When a string that does not begin with #, T, V, P or R is received, the meter 
processes it as a Numeric transmission. In this case, only the recognized numbers 
and punctuation are displayed. All other characters in the string are discarded. If 
a negative sign appears anywhere in the string the resulting number will be 
negative. Only the most significant decimal point is retained. If no numerical 
characters are received, then the numeric value will be zero. The numeric display 
can be used for setpoint (boundary action only) and analog output functions. 
When using this display for setpoint and analog output values, the decimal point 
position must match the programming entered through the front panel. The numeric value is retained in Counter C memory until another Numeric transmission is received.

\textbf{Recognized Numbers} = 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 \\
\textbf{Recognized Punctuation} = period, comma, minus

\textbf{Literal Transmissions} \\
When a string that begins with # is received, the meter processes it as a Literal transmission. In this case, any unrecognized characters will be replaced with a space. A Literal display will replace a Numeric value in the Counter C display. However, it will not remove a previous Numeric value from Counter C memory or prevent the Counter C outputs from functioning with the Numeric value. Literal transmissions are only possible when using RS232 or RS485 cards.

\textbf{Recognized Characters} = a, b, c, d, e, f, g, h, i, j, l, n, o, p, q, r, s, t, u, y, z (in upper or lower case) \\
\textbf{Recognized Numbers} = 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 \\
\textbf{Recognized Punctuation} = period, comma, minus, blank

\textbf{COUNTER C SLAVE COMMUNICATIONS} \\
Counter C may be programmed for \textit{SLAVE} to act as a serial slave display. By doing this, the carriage return \textit{<CR>} is added as a valid command terminator character for all serial command strings. The \textit{<CR>} as a terminator may be very useful for standard serial commands, even if Counter C is never displayed or sent a slave message. The \textit{$} terminator should not be used in the slave mode. If numeric values are not to be saved to EPROM then send the value as a literal transmission with \textit{<CR>} terminator.

The Counter C slave display is right aligned. It has a capacity of displaying six characters. When less than six characters are received, blank spaces will be placed in front of the characters. If more than six characters are sent, then only the last six are displayed. The meter has a 192 character buffer for the slave display. If more than 192 characters are sent, the additional characters are discarded until a terminator is received. Counter C processes numeric and literal transmissions differently.
COMMUNICATION FORMAT

Data is transferred from the meter through a serial communication channel. In serial communications, the voltage is switched between a high and low level at a predetermined rate (baud rate) using ASCII encoding. The receiving device reads the voltage levels at the same intervals and then translates the switched levels back to a character.

The voltage level conventions depend on the interface standard. The table lists the voltage levels for each standard.

<table>
<thead>
<tr>
<th>Logic</th>
<th>Interface State</th>
<th>RS232*</th>
<th>RS485*</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>mark (idle)</td>
<td>TXD,RXD; -3 to -15 V</td>
<td>a-b &lt; -200 mV</td>
</tr>
<tr>
<td>0</td>
<td>space (active)</td>
<td>TXD,RXD; +3 to +15 V</td>
<td>a-b &gt; +200 mV</td>
</tr>
</tbody>
</table>

* Voltage levels at the Receiver

Data is transmitted one byte at a time with a variable idle period between characters (0 to ∞). Each ASCII character is “framed” with a beginning start bit, an optional parity bit and one or more ending stop bits. The data format and baud rate must match that of other equipment in order for communication to take place. The figures list the data formats employed by the meter.

Start bit and Data bits

Data transmission always begins with the start bit. The start bit signals the receiving device to prepare for reception of data. One byte period later, the least significant bit of the ASCII encoded character is transmitted, followed by the remaining data bits. The receiving device then reads each bit position as they are transmitted.

Parity bit

After the data bits, the parity bit is sent. The transmitter sets the parity bit to a zero or a one, so that the total number of ones contained in the transmission (including the parity bit) is either even or odd. This bit is used by the receiver to detect errors that may occur to an odd number of bits in the transmission. However, a single parity bit cannot detect errors that may occur to an even number of bits. Given this limitation, the parity bit is often ignored by the receiving device. The PAX meter ignores the parity bit of incoming data and sets the parity bit to odd, even or none (mark parity) for outgoing data.

Stop bit

The last character transmitted is the stop bit. The stop bit provides a single bit period pause to allow the receiver to prepare to re-synchronize to the start of a new transmission (start bit of next byte). The receiver then continuously looks for the occurrence of the start bit. If 7 data bits and no parity is selected, then 2 stop bits are sent from the PAXI.

SERIAL TIMING

<table>
<thead>
<tr>
<th>Command</th>
<th>Comment</th>
<th>Process Time ((t_2))</th>
</tr>
</thead>
<tbody>
<tr>
<td>R</td>
<td>Reset</td>
<td>2-50 msec.</td>
</tr>
<tr>
<td>#</td>
<td>Literal</td>
<td>2-50 msec.</td>
</tr>
<tr>
<td>V</td>
<td>Write</td>
<td>100-200 msec.</td>
</tr>
<tr>
<td>T</td>
<td>Transmit</td>
<td>2-50 msec. for $</td>
</tr>
<tr>
<td>P</td>
<td>Print</td>
<td>2-50 msec. for $</td>
</tr>
<tr>
<td></td>
<td></td>
<td>50-100 msec. for * and &lt;CR&gt;</td>
</tr>
</tbody>
</table>

Timing Diagrams

NO REPLY FROM METER

<table>
<thead>
<tr>
<th>Command String</th>
<th>Meter Response Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ready</td>
<td>Transmission</td>
</tr>
<tr>
<td>Command Terminater</td>
<td>Received</td>
</tr>
</tbody>
</table>

RESPONSE FROM METER

<table>
<thead>
<tr>
<th>Command String</th>
<th>Meter Response Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ready</td>
<td>Transmission</td>
</tr>
<tr>
<td>Command Terminater</td>
<td>First Character of Reply</td>
</tr>
</tbody>
</table>

COMMAND RESPONSE TIME

The meter can only receive data or transmit data at any one time (half-duplex operation). During RS232 transmissions, the meter ignores commands while transmitting data, but instead uses RXD as a busy signal. When sending commands and data to the meter, a delay must be imposed before sending another command. This allows enough time for the meter to process the command and prepare for the next command.

At the start of the time interval \(t_1\), the computer program prints or writes the string to the com port, thus initiating a transmission. During \(t_1\), the command characters are under transmission and at the end of this period, the command terminating character (*, $ or slave only <CR>) is received by the meter. The time duration of \(t_1\) is dependent on the number of characters and baud rate of the channel.

\[ t_1 = \left( 10 \times \text{the \# of characters} \right) / \text{baud rate} \]

At the start of time interval \(t_2\), the meter starts the interpretation of the command and when complete, performs the command function. This time interval \(t_2\) varies (See Timing Diagrams). If no response from the meter is expected, the meter is ready to accept another command.

If the meter is to reply with data, the time interval \(t_3\) is controlled by the use of the command terminating character. The ‘*‘ or ‘<CR>‘ terminating character results in a response time window of 50 msec. minimum and 100 msec. maximum. This allows sufficient time for the release of the sending driver on the RS485 bus. Terminating the command line with ‘$‘ results in a response time window \((t_3)\) of 2 msec. minimum and 50 msec. maximum. The faster response time of this terminating character requires that sending drivers release within 2 msec. after the terminating character is received.

At the beginning of time interval \(t_3\), the meter responds with the first character of the reply. As with \(t_1\), the time duration of \(t_3\) is dependent on the number of characters and baud rate of the channel. At the end of \(t_3\), the meter is ready to receive the next command.

\[ t_3 = \left( 10 \times \text{the \# of characters} \right) / \text{baud rate} \]

The maximum serial throughput of the meter is limited to the sum of the times \(t_1\), \(t_2\) and \(t_3\).
Module 8 is the programming for the analog output parameters. To have an analog output signal, an analog output plug-in card needs to be installed (See Ordering Information). This section replaces the bulletin that comes with the analog plug-in card. Please discard the separate literature when using the plug-in card with the PAXI.

**ANALOG TYPE**

<table>
<thead>
<tr>
<th>SELECTION</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>0-20</td>
<td>0 to 20 mA</td>
</tr>
<tr>
<td>4-20</td>
<td>4 to 20 mA</td>
</tr>
<tr>
<td>0-10</td>
<td>0 to 10 V</td>
</tr>
</tbody>
</table>

Enter the analog output type. For voltage output use terminals 16 and 17. For current output use terminals 18 and 19. Only one range can be used at a time.

**ANALOG ASSIGNMENT**

Select the display that the analog output is to follow:

- **A Cnt** = Counter A Value
- **B Cnt** = Counter B Value
- **C Cnt** = Counter C Value
- **r Ate** = Rate Value
- **LO** = Minimum Value
- **HI** = Maximum Value

Enter the display value within the selected Analog Assignment that corresponds to the high limit of the type selected. The decimal point is determined by the decimal point setting of the assigned counter or rate. The scale value cannot be set to read values with more than 6 digits. Reverse acting output is possible by reversing the scaling values.

**ANALOG LOW SCALE VALUE**

-99999 to 999999

**ANALOG HIGH SCALE VALUE**

-99999 to 999999

Enter the display value within the selected Analog Assignment that corresponds to the high limit of the type selected. The decimal point is determined by the decimal point setting of the assigned counter or rate. The scale value cannot be set to read values with more than 6 digits. Reverse acting output is possible by reversing the scaling values.

**DISPLAY INTENSITY LEVEL**

Enter the desired Display Intensity Level (0-15) by using the arrow keys. The display will actively dim or brighten as the levels are changed. This parameter also appears in Quick Programming Mode when enabled.

**RESTORE FACTORY DEFAULTS**

Use the arrow keys to display **CODE 66** and press **PAR**. The meter will display **r ESE** and then returns to **CODE 50**. Press **DSP** key to return to the Display Mode. This will overwrite all user settings with the factory settings.

Pressing the **PAR** and **DSP** keys at the same time on power-up will load the factory settings and display **Err**. This allows operation in the event of a memory failure or corrupted data. Immediately press **RST** key and reprogram the meter. If the meter is powered down again before pressing the **RST** key, the existing dynamic data will not be overwritten.
**PAXI CALIBRATION**

The only item in the PAXI meter that can be calibrated is the Analog Output. The Count A and B values are scaled using the parameters in Module 1, Counter C value is scaled using Module 5 and the Rate value is scaled using Module 4. If the meter appears to be indicating incorrectly or inaccurately, refer to the Troubleshooting section.

When Analog Out recalibration is required (generally every 2 years), it should be performed by qualified technicians using appropriate equipment. Calibration does not change any user programmed parameters. Calibration may be aborted by disconnecting power to the meter before exiting Module 9. In this case, the existing calibration settings remain in effect.

*Note: Allow a 30 minute warm-up period before starting calibration.*

---

**TROUBLESHOOTING**

For further assistance, contact technical support at the appropriate company numbers listed.

<table>
<thead>
<tr>
<th>PROBLEM</th>
<th>REMEDIES</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>NO DISPLAY</strong></td>
<td>CHECK: Power level, power connections</td>
</tr>
<tr>
<td><strong>PROGRAM LOCKED-OUT</strong></td>
<td>CHECK: Active (lock-out) user input</td>
</tr>
<tr>
<td><strong>CERTAIN DISPLAYS ARE LOCKED OUT</strong></td>
<td>CHECK: Module 3 programming</td>
</tr>
<tr>
<td><strong>INCORRECT DISPLAY VALUE or NOT COUNTING</strong></td>
<td>CHECK: Input wiring, DIP switch setting, input programming, scale factor calculation, input signal level, user input jumper, lower input signal frequency</td>
</tr>
<tr>
<td><strong>USER INPUT NOT WORKING CORRECTLY</strong></td>
<td>CHECK: User input wiring, user input jumper, user input being used for signal, Module 2</td>
</tr>
<tr>
<td><strong>OUTPUT DOES NOT WORK</strong></td>
<td>CHECK: Corresponding plug-in card installation, output configuration, output wiring</td>
</tr>
<tr>
<td><strong>JITTERY DISPLAY</strong></td>
<td>CHECK: Wiring is per EMC installation guidelines, input signal frequency, signal quality, scaling, update time, DIP switch setting</td>
</tr>
<tr>
<td><strong>&quot; * DL* &quot; RATE</strong></td>
<td>CHECK: Lower input signal frequency, reduce rate scaling</td>
</tr>
<tr>
<td><strong>MODULES or PARAMETERS NOT ACCESSIBLE</strong></td>
<td>CHECK: Corresponding plug-in card installation, related controlling parameter selected</td>
</tr>
<tr>
<td><strong>ERROR CODE (Err \quad t - 4)</strong></td>
<td>PRESS: Reset key (if unable to clear contact factory.)</td>
</tr>
<tr>
<td><strong>SERIAL COMMUNICATIONS</strong></td>
<td>CHECK: Wiring, connections, meter and host settings</td>
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Shaded areas are model dependent.
### Display and Program Lockout Parameters

<table>
<thead>
<tr>
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<th>PARAMETER</th>
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<th>USER SETTING</th>
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<tbody>
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<td>A CNb</td>
<td>COUNTER A DISPLAY LOCK-OUT</td>
<td>rEd</td>
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<tr>
<td>b CNb</td>
<td>COUNTER B DISPLAY LOCK-OUT</td>
<td>LOC</td>
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<tr>
<td>C CNb</td>
<td>COUNTER C DISPLAY LOCK-OUT</td>
<td>LOC</td>
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</tr>
<tr>
<td>rAEE</td>
<td>RATE DISPLAY LOCK-OUT</td>
<td>rEd</td>
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</tr>
<tr>
<td>L0</td>
<td>MIN DISPLAY LOCK-OUT</td>
<td>LOC</td>
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<tr>
<td>SP-1</td>
<td>SETPOINT 1 ACCESS LOCK-OUT</td>
<td>LOC</td>
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<td>SETPOINT 2 ACCESS LOCK-OUT</td>
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<td>SETPOINT 3 ACCESS LOCK-OUT</td>
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<td>A CNb</td>
<td>COUNT LOAD A ACCESS</td>
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<td>b CNb</td>
<td>COUNT LOAD B ACCESS</td>
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<td>C CNb</td>
<td>COUNT LOAD C ACCESS</td>
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<td>rAEE</td>
<td>SCALE FACTOR A ACCESS</td>
<td>ENb</td>
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### Rate Input Parameters - PAXI & R only

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<td>H1-Ud</td>
<td>HIGH UPDATE TIME</td>
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<td>rEE dp</td>
<td>RATE DECIMAL POINT</td>
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<td>dINP 1</td>
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<td>dSP 1</td>
<td>SCALING PT. 2 - DISPLAY VALUE</td>
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<td>dINP 2</td>
<td>SCALING PT. 2 - INPUT VALUE</td>
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<td>SCALING PT. 3 - INPUT VALUE</td>
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<td>SCALING PT. 4 - INPUT VALUE</td>
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<td>SCALING PT. 5 - DISPLAY VALUE</td>
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<td>dINP 5</td>
<td>SCALING PT. 5 - INPUT VALUE</td>
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<td>dSP 5</td>
<td>SCALING PT. 6 - DISPLAY VALUE</td>
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<td>SCALING PT. 6 - INPUT VALUE</td>
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<td>SCALING PT. 8 - DISPLAY VALUE</td>
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<td>dINP 8</td>
<td>SCALING PT. 8 - INPUT VALUE</td>
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<td>dSP 8</td>
<td>SCALING PT. 9 - DISPLAY VALUE</td>
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<td>dINP 9</td>
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<td>dINP 10</td>
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<td>RATE DISPLAY Rounding</td>
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<td>MINIMUM LOW CUT OUT</td>
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<tr>
<td>H1-Edt</td>
<td>MAX CAPTURE DELAY TIME</td>
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<td>L0-Edt</td>
<td>MIN CAPTURE DELAY TIME</td>
<td>20</td>
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</table>

### Counter C Input Parameters - PAXC & I only

<table>
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<tr>
<th>DISPLAY</th>
<th>PARAMETER</th>
<th>FACTORY SETTING</th>
<th>USER SETTING</th>
</tr>
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<tbody>
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<td>C CNb</td>
<td>COUNTER C OPERATING MODE</td>
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<td>rCENb</td>
<td>COUNTER C RESET ACTION</td>
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<td>CdECPl</td>
<td>COUNTER C DECIMAL POSITION</td>
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<td>rAEE</td>
<td>COUNTER C SCALE FACTOR (A)</td>
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<tr>
<td>C CNb</td>
<td>COUNTER C SCALE FACTOR (B)*</td>
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<td>rAEE</td>
<td>COUNTER C SCALE MULTIPLIER</td>
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<td>COUNTER C COUNT LOAD VALUE (A)</td>
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<td>b CNb</td>
<td>COUNTER C RESET POWER-UP</td>
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</table>

* See Module 2, Exchanging Parameter Lists, for details on programming this value.
**6-SPt Setpoint (Alarm) Parameters**

<table>
<thead>
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<th>DISPLAY</th>
<th>PARAMETER</th>
<th>FACTORY SETTING</th>
<th>USER SETTING</th>
<th>FACTORY SETTING</th>
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<td>Dk-n</td>
<td>SETPOINT OUTPUT LOGIC</td>
<td>NOf</td>
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<td>Sp-n</td>
<td>SETPOINT POWER UP STATE</td>
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<td>r5A-n</td>
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<td>RESET WHEN SPn+1 DEACTIVATES</td>
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* See Module 2, Exchanging Parameter Lists, for details on programming this value.

Shaded areas are model dependent.

**1-5rL Serial Communication Parameters - PAXI only**

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**8-RnR Analog Output Parameters - PAXI only**

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<td>LyP-n</td>
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<td>r5s-n</td>
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<td>No</td>
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<tr>
<td>r5s-n</td>
<td>RESET WHEN SPn+1 DEACTIVATES</td>
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**9-FC5 Factory Service Parameters**

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<td>d-LEU</td>
<td>DISPLAY INTENSITY LEVEL</td>
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Counter parameters apply to the PAXC and PAXI, while the rate parameters apply to the PAXR and PAXI.