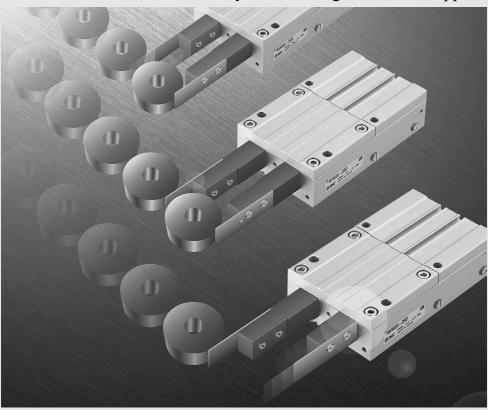
# **Escapements**

# MIW/MIS Series

Ø8, Ø12, Ø20, Ø25, Ø32

Ideal for separating and feeding individual parts from vibratory feeders, magazines, and hoppers.



# **Series variations**

Series	Bore size (mm)	8	10	1 <u>2</u>	troke	e (mi	m) 30	32	50	Finger option	Stroke adjuster	Scraper
MIW	8 12 20 25 32	<b>*</b>		<b>*</b>	‡ ‡	+	#	‡ •				
MIS	8 12 20 25 32		*	#	*	#	<b>+</b>	#	<b>+</b>			

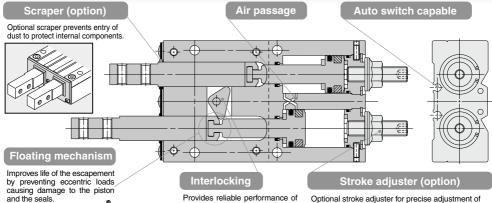
|-**X**□

D-□

RSQ RSG RS2H RSH

617

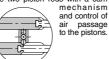
# Ideal for separating and from vibratory feeders.



As this mechanism separates the fingers from the piston, it is possible to replace the fingers with ease when required.



the escapement by interlocking the two piston rods with a cam



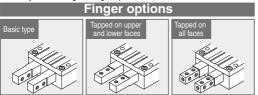
For ø25 and ø32, lock mechanism for heavier load is available

Optional stroke adjuster for precise adjustment of the retracted position of each piston rod.

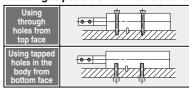


## Three variations of fingers

Flexibility in mounting the finger options.

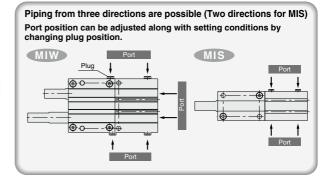


# Mounting is possible from 2 directions.

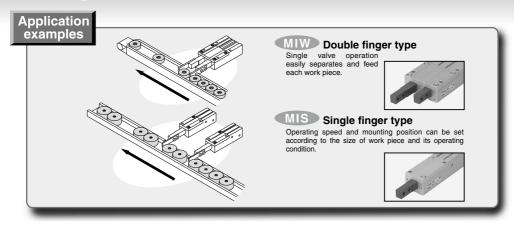


Positioning pin holes allow for easy mounting.





# feeding individual parts magazines, and hoppers.

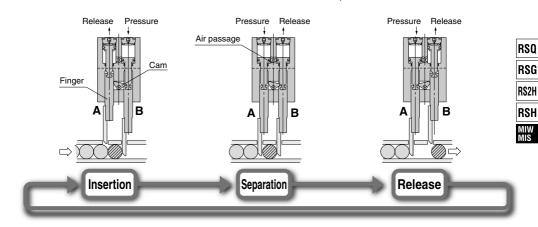


# Working principle

The cam locks Finger B.

When Finger A is extended to reach the stroke end, air is supplied to retract Finger B.

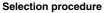
Extension of Finger A rotates the cam to unlock Finger B and lock finger A to allow retraction of Finger B



D-□ -x□

# MIW/MIS Series **Model Selection**

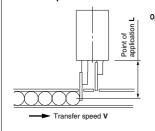
## **Model Selection**





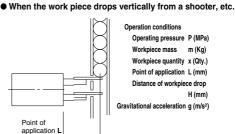
# Procedure 1 Confirmation of conditions

The work piece moves horizontally on the conveyor.



Operation conditions Operating pressure P (MPa) Workpiece mass m (Kg) Workpiece quantity x (Qty.) Point of application L (mm) Workpiece transfer speed V (m/min) Coefficient of friction

between the workpiece and conveyor



Operating pressure P (MPa) Workpiece mass m (Kg) Workpiece quantity x (Qty.) Point of application L (mm) Distance of workpiece drop H (mm)

Gravitational acceleration q (m/s2)

Operation conditions

# Procedure 2 Confirmation of impact

From the graph of operating range, obtain the point of intersection of the total mass of the workpiece x · m (kg) indicated by the axis of ordinates and the transfer speed V (m/min) indicated by the axis of abscissas. Select a model so that the intersection will fall below the point of application L indicated by a line.

1. Calculation of workpiece collision speed The collision speed V is calculated from the distance of work piece fall H.

Workpiece collision speed V = \( \sqrt{2gH/1000} \times 60 \text{ (m/min)} \)

2. From the graph of operating range, obtain the intersection of the total mass of the workpiece x · m (kg) indicated by the axis of ordinates and the collision speed V (m/min) obtained by calculation. Select a model so that the intersection will fall below the point of application L indicated by a line.

# Procedure 3 Confirmation of allowable lateral load

1. Calculation of applied lateral load F The lateral load F equals the coefficient between the work piece and the conveyor. Thus, from the total amount of the workpiece and coefficient of friction.

 $\mathbf{F} = \mu \cdot \mathbf{x} \cdot \mathbf{m} \cdot \mathbf{g} (\mathbf{N})$ 

1. Calculation of applied lateral load The lateral load F equals the total load of the work piece.

Thus,  $F = x \cdot m \cdot g(N)$ 

2. From the graph of allowable lateral load, obtain the allowable lateral load F max from the intersection of the operating pressure and the point of application L indicated by the axis of abscissas. Select a model so that the value will be larger than the lateral load F applied in real operation.

Lateral load: F ≤ Allowable lateral load: Fmax

## Model Selection

## Operating range

## Procedure 1 Confirmation of conditions

The workpiece moves horizontally on the conveyor.

Operating conditions

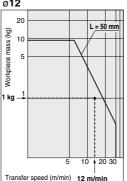
Operating pressure P = 0.4 MPa Workpiece mass m = 0.1 kgWorkpiece quantity x = 10Point of application L = 50 mmWorkpiece transfer speed V = 12 m/min Coefficient of friction between the work piece and conveyor  $\mu = 0.2$  When the workpiece drops vertically from a shooter, etc.

Operating conditions

Operating pressure P = 0.4 MPa Workpiece mass m = 0.05 kgWorkpiece quantity x = 5Point of application I = 60 mmDistance of workpiece drop H = 15 mm Gravitation acceleration  $a = 9.8 \text{ m/s}^2$ 

# Procedure 2 Confirmation of impact

- · Obtain the total amount of the workpiece. Total mass  $m = 10 \times 0.1 (kg) = 1 (kg)$
- . Obtain the intersection of the transfer speed V and the total weight of workpiece m. Confirm that the value is within the operating range of the point of application L = 50 mm ø12



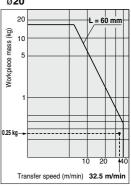
- · Obtain the total amount of the workpiece. Total mass m = 5 × 0.05 (kg) = 0.25 (kg)
- · Obtain the collision speed of the workpiece V.

 $V = \sqrt{2qH/1000 \times 60}$ 

 $=\sqrt{2 \times 9.8 \times 15/1000} \times 60$ ø**20** 

= 32.5 (m/min)

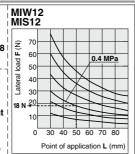
· Obtain the intersection of the collision speed V and the total mass of the workpiece m. Confirm that the value is within the operating range of the point of application L = 60 mm.



# Procedure 3 Confirmation of allowable lateral load

- 1. Calculation of applied lateral load F
  - $F = \mu \cdot N \cdot m \cdot q(N)$ = 0.2 x 10 x 0.1 x 9.8 = 2.1 (N)
- 2. Confirmation of allowable lateral load From the graph, the allowable lateral load at L = 50 mm and P = 0.4 MPa is 18 N. Because 2.1 N < 18 N, it is applicable.

Therefore select MIW (MIS) 12.



1. Calculation of applied lateral load The lateral load F equals the total load of the work piece. Thus.

F= 5 x 0.05 x 9.8

= 2.5 (N)

2. Confirmation of allowable lateral load In the same way, the lateral load at L = 50 mm and P = 0.4 MPa is 48 N from the graph. Because 2.5 N < 48 N, it is applicable.

Therefore select MIW (MIS) 20.

D--**X**□

RSQ RSG

RS2H

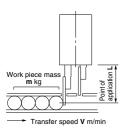
**RSH** 

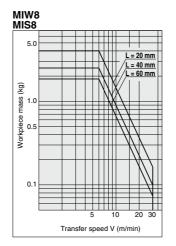
# MIW/MIS Series

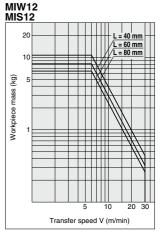
## **Model Selection**

# Operating range

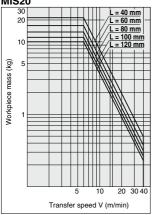
The graph at right shows conditions of the workpiece to be stopped; that is, the mass, transfer speed and the operating range of the point of application L.



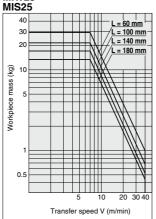




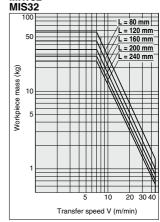
## MIW20 MIS20



# MIW25



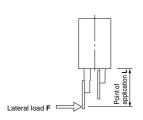
# MIW32

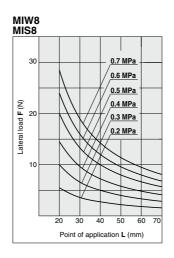


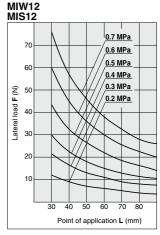
# Model Selection **MIW/MIS** Series

# **Model Selection**

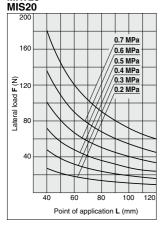
## Allowable lateral load



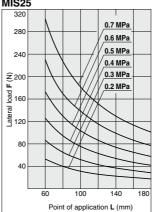




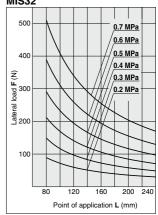








## MIW32 MIS32



D-□ -X□

RSQ RSG RS2H

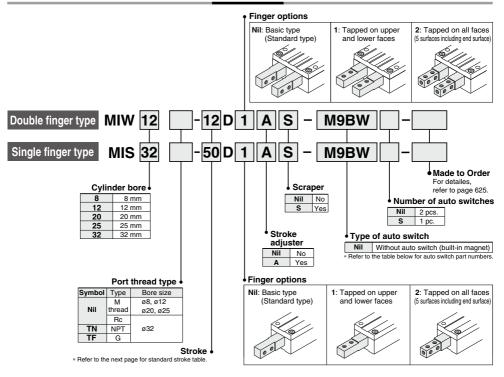
RSH MIW MIS



# In the second of the second of



## How to Order



Applicable auto switches/Refer to pages 941 to 1067 for detailed specifications of auto switches.

			E	T T	I I	oad volta	ne .	Auto swite	ch models	Lead	wiro I	onath	(m)	0											
Туре	Special function	Electrical entry	Indicator light	Wiring (output)		C C	AC	Perpendicular	In-line	0.5 (Nil)	1	3	5	Pre-wired connector	Applicable load										
_				3-wire (NPN)		5 V.12 V		M9NV	M9N	•	•	•		0	IC										
switch				3-wire (PNP)		5 V, 12 V	5 V, 12 V		M9PV	M9P	•	•	•	0	0	circuit									
S		2-wire		12 V		M9BV	M9B	•	•	•	0	0	_												
욕	Dia anno atto in alto atto			3-wire (NPN)		24 V 5 V,12 V		M9NWV	M9NW	•	•	•		0	IC	D-1									
<u>a</u>	Diagnostic indication	Grommet	Yes	3-wire (PNP)			24 V 3 V, 12 V	_	M9PWV	M9PW	•	•	•	0	0	circuit	Relay, PLC								
state	(2-color display)			2-wire		12 V		M9BWV	M9BW	•	•	•	0	0	_	FLC									
	Mater registent		3-wire (NPN)		51/401/	51/401/	5 1/ 40 1/	5 V 10 V	5 V 10 V	5 V 40 V	5 V.12 V	5 V 40 V	5 V 40 V	5 V 10 V	51/401/		M9NAV**	M9NA**	0	0	•		0	IC	
흥	Water resistant			3-wire (PNP)		5 V, 12 V		M9PAV**	M9PA**	0	0	•	0	0	circuit										
S	(2-color indicator)			2-wire	1	12 V		M9BAV**	M9BA**	0	0	•	0	0	_										

- \*\* Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
- \* Lead wire length symbols: 0.5 m ...... Nii (Example) M9NW 1 m ..... M (Example) M9NWM 3 m ..... L (Example) M9NWL 5 m ..... Z (Example) M9NWL
- \* Solid state auto switches marked with "O" are produced upon receipt of order.
- \* Refer to pages 1014 and 1015 for the details of auto switches with a pre-wired connector.
- \* Auto switches are shipped together (not assembled).



# Escapements **MIW/MIS** Series



# **Specifications**

Series	MIW (Double finger)	MIS (Single finger)	
Fluid	Air		
Operating pressure	0.2 to 0.7 MPa		
Ambient temperature and fluid temperature	-10 to 60°C (No freezing)		
Lubrication	Non-lube		
Action	Double	acting	
Auto switch (optional) Note) Solid state auto switch (3-wire, 2			
Stroke tolerance	<sup>+1</sup> <sub>0</sub> mm		

# Option

Finger options	Standard, Tapped on upper and lower faces, Tapped on all faces (5 surfaces including end surface)
	MI□8: Arrangement range 4 mm
Stroke adjuster	MI□12: Arrangement range 6 mm
(Rear end	MI□20: Arrangement range 12 mm
stroke only)	MI□25: Arrangement range 15 mm
	MI□32: Arrangement range 20 mm
Scraper	Can be mounted on standard products

# **Theoretical Output**

									Unit: N
Bore size	Rod size	Operating	Piston area			Operating p	ressure MPa		
(mm)	(mm)	direction	(mm <sup>2</sup> )	0.2	0.3	0.4	0.5	0.6	0.7
8	4	OUT	50	10	15	20	26	31	36
	4	IN	38	7	11	15	19	23	26
12	6	OUT	113	23	34	45	57	68	79
12		IN	85	17	26	34	43	51	60
20	10	OUT	314	63	94	126	157	188	220
20		IN	236	47	71	94	118	142	165
25	10	OUT	491	98	147	196	245	295	344
25	10	IN	412	82	124	165	206	247	288
32	12	OUT	804	161	241	322	402	482	563
32	12	IN	691	138	207	276	346	415	484

# **Standard Stroke**

Double finger type/MIW (mm							
Bore size	Stroke						
8	8 mm						
12	12 mm						
20	20 mm						
25	25 mm						
32	32 mm						

<sup>\*</sup> For MIW, same stroke as bore size

Single finger type/MIS						
Bore size	Stroke					
8	10, 20 mm					
12	10, 20, 30 mm					
20	10, 20, 30 mm					
25	30, 50 mm					
32	30, 50 mm					

Made to Order	Made to Order: Individual Specifications (For detailes, refer to page 633.)
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	Symbol	Specifications					
-X4 Heat resistant (-10 to 100°C)							
-X5 Fluororubber seal							
-X63 Fluorine grease							
-X79 Grease for food							

# Weight

Model	Model	Stroke (mm)	Weight (g)	Increase by stroke adjuster (g)	Increase by scraper (g)	
	MIW8-8D	8	110	6	3	
	MIW12-12D	12	240	10	5	
MIW	MIW20-20D	20	650	30	10	
	MIW25-25D	25	1550	30	20	
	MIW32-32D	32	2650	100	35	
	MIS8-10D	10	62	3	2	
	MIS8-20D	20	80	3	2	
	MIS12-10D	10	130			
	MIS12-20D	20	160	5	3	
	MIS12-30D	30	190			
MIS	MIS20-10D	10	300			
WIIO	MIS20-20D	20	355	15	5	
	MIS20-30D	30	410			
	MIS25-30D	30	800	15	10	
	MIS25-50D	50	1000	15	10	
	MIS32-30D	30	1350	50	18	
	MIS32-50D	50	1650	50	18	

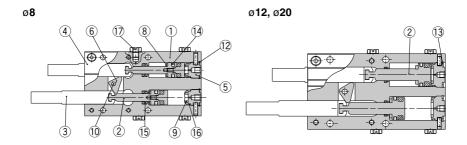
D-□ -X□

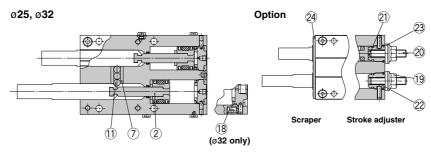
RSQ RSG RS2H RSH



# MIW/MIS Series

# Construction/Double Finger Type (MIW)





## Component parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston assembly		
3	Finger	Carbon steel	Heat treatment/Special treatment
4	Cover	Aluminum alloy	Hard anodized
5	Cap (W)	Aluminum alloy	White anodized
6	Cam	Stainless steel	Heat treatment (MIW8 to 20)
7	Roller holder	Stainless steel	Heat treatment (MIW25, 32)
8	Bumper	Urethane rubber	
9	Head bumper	Urethane rubber	
10	Needle roller	High carbon chromium bearing steel	(MIW8 to 20)

No.	Description	Material	Note
11	Cylinder roller	Carbon steel	(MIW25, 32)
12	Clip	Carbon steel	(MIW8)
13	R shape retaining ring	Carbon steel	(MIW12 to 32)
14	Piston seal	NBR	
15	Rod seal	NBR	
16	Gasket	NBR	
17	Di		(MIW8 ··· M-3P)
17	Plug		(MIW12 to 25 ··· M-5P)
18	Hexagon socket taper plug		(MIW32 ··· Rc1/8)

## Option: adjuster

No.	Description	Material	Note			
19	Hexagon nut with flange	Carbon steel	Nickel plated			
20	Adjustment bolt	Carbon steel	Nickel plated			
21	Adjustment bumper	Urethane rubber				
22	Adjustment cap	Aluminum alloy	White anodized			
23	Die thread					

## Option: scraper

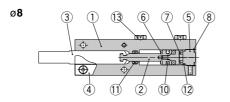
No.	Description	Material	Note
24	Scraper	Stainless steel + NBR	

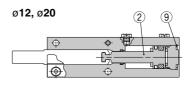
## Replacement parts

Description		Finger		011-4	0	Granen naak	
Model Standard		Tapped on upper and lower faces	Tapped on all faces	Seal kit	Scraper assembly	Grease pack	
MIW8-8D	MI-A0801-8	MI-A0802-8	MI-A0803-8	MIW8-PS	MIW-A0804		
MIW12-12D	MI-A1201-12	MI-A1202-12	MI-A1203-12	MIW12-PS	MIW-A1204	MH-G01 (contents quantity	
MIW20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20	MIW20-PS	MIW-A2004		
MIW25-25D	MI-A2501-25	MI-A2502-25	MI-A2503-25	MIW25-PS	MIW-A2504	30 g)	
MIW32-32D	MIW32-32D MI-A3201-32		MI-A3203-32	MIW32-PS	MIW-A3204		
Main parts No.		③ (1 pc.)		(14), (15), (16)	24		

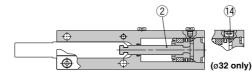
# Escapements **MIW/MIS** Series

# **Construction/Single Finger Type (MIS)**











Option





Scraper

Stroke adjuster

## Component parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston assembly		
3	Finger	Carbon steel	Heat treatment/Special treatment
4	Cover	Aluminum alloy	Hard anodized
5	Cap (S)	Aluminum alloy	White anodized
6	Bumper	Urethane rubber	
7	Head bumper	Urethane rubber	
8	Clip	Carbon steel	(MIS8)
9	R shape retaining ring	Carbon steel	(MIS12 to 32)

No.	Description	Material	Note
10	Piston seal	NBR	
11	Rod seal	NBR	
12	Gasket	NBR	
13	Dive		(MIS8 ··· M-3P)
13	Plug		(MIS12 to 25 ··· M-5P)
14	Hexagon socket taper plug		(MIS32 ··· Rc1/8)

# Ontion: adjuster

- p	···· aajaoto.		
No.	Description	Material	Note
15	Hexagon nut with flange	Carbon steel	Nickel plated
16	Adjustment bolt	Carbon steel	Nickel plated
17	Adjustment bumper	Urethane rubber	
18	Adjustment cap	Aluminum alloy	White anodized
10	Die thread		

## Option: scraper

No.	Description	Material	Note
20	Scraper	Stainless steel + NBR	

RSG RS2H RSH

RSQ

Rep	lacement	parts
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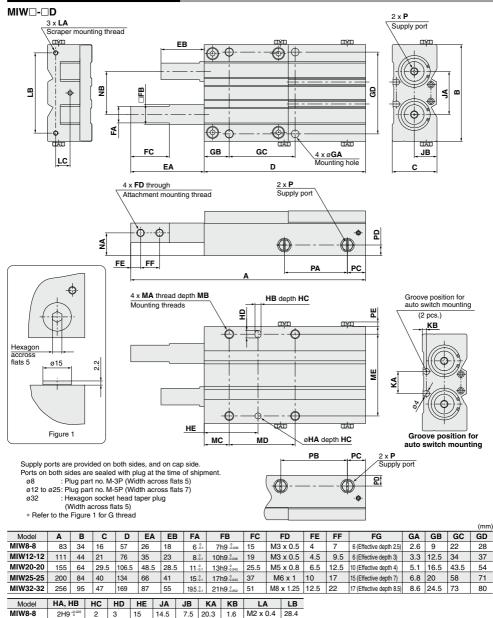
Description		Finger		Seal kit	Scraper assembly	Grease pack	
Model	Standard	Tapped on upper and lower faces	Tapped on all faces	Sear Kit	Scraper assembly	Grease pack	
MIS8-10D	MI-A0801-10	MI-A0802-10	MI-A0803-10	MIS8-PS	MIS-A0804		
MIS8-20D	MI-A0801-20	MI-A0802-20	MI-A0803-20	W150-P5	WIIS-AU604		
MIS12-10D	MI-A1201-10	MI-A1202-10	MI-A1203-10				
MIS12-20D	MI-A1201-20	MI-A1202-20	MI-A1203-20	MIS12-PS	MIS-A1204		
MIS12-30D	MI-A1201-30	MI-A1202-30	MI-A1203-30				
MIS20-10D	MI-A2001-10	MI-A2002-10	MI-A2003-10			MH-G01	
MIS20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20	MIS20-PS	MIS-A2004	(contents quantity	
MIS20-30D	MI-A2001-30	MI-A2002-30	MI-A2003-30			30 g)	
MIS25-30D	MI-A2501-30	MI-A2502-30	MI-A2503-30	MIS25-PS	MIS-A2504		
MIS25-50D	MI-A2501-50	MI-A2502-50	MI-A2503-50	W11323-F3	WII3-A2304		
MIS32-30D	MI-A3201-30	MI-A3202-30	MI-A3203-30	MIS32-PS	MIS-A3204		
MIS32-50D	MI-A3201-50	MI-A3202-50	MI-A3203-50	WII532-P5	WIIS-A3204		
Main parts No.		③ (1 pc.)		10, 11, 12	20		

D-□ -X□



# MIW/MIS Series

# **Dimensions/Double Finger Type**



628

MIW12-12

MIW20-20

MIW25-25

MIW32-32

2.5H9+0

4H9<sup>+</sup>

5H9 \*6

6H9 \*0.030

4 3.5 25 19

5

5 7 40 35.5 20 24.5 3

35.5 28.5 15 14.5 2.8

44.5

M2.6 x 0.45 37

M3 x 0.5

M3 x 0.5 70

M4 x 0.7

2.2

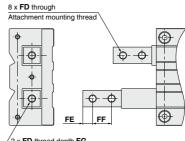
24.1 2.5

# Escapements **MIW/MIS** Series

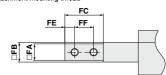
# Finger options Tapped on upper and lower faces

# 4 x FD through Attachment mounting thread

# Tapped on all faces

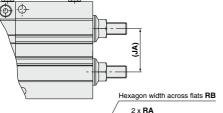


2 x FD thread depth FG
Attachment mounting thread

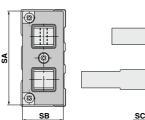


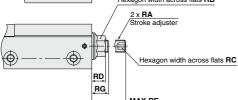


## Stroke adjuster









MAX RE Arrangement range RF mm

Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

																		(mm)
Model	LC	MA	MB	МС	MD	ME	NA	NB	Р	PA	PB	PC	PD	PE	RA	RB	RC	RD
MIW8-8	4.5	M3 x 0.5	6	9	22	28	7.5	14.5	M3 x 0.5	22.5	24	8	4.5	2.2	M4 x 0.7	7	2	5.7
MIW12-12	7.5	M4 x 0.7	7	12.5	34	37	11	19	M5 x 0.8	25	27	10	6	2.8	M5 x 0.8	8	2.5	6
MIW20-20	9.5	M6 x 1	10	16.5	43.5	54	15	28.5	M5 x 0.8	41.5	44	12	7	2.7	M8 x 1	12	4	9
MIW25-25	12	M8 x 1.25	12	20	58	71	20	35.5	M5 x 0.8	50	55	14	8.5	2.7	M8 x 1	12	4	9
MIW32-32	16.5	M10 x 1.5	15	24.5	73	80	25	44.5	Rc1/8	69.5	75.5	14.5	11	_	M12 x 1.25	17	6	12.4

Model	RE	RF	RG	SA	SB	SC	
MIW8-8	12.5	4	8.5	33	14.5	1.4	
MIW12-12	14	6	8	43	18.5	1.8	
MIW20-20	22.5	12	10.5	62	27	2.2	
MIW25-25	26	15	11	81	35	2.8	
MIW32-32	33	20	13	93	42	3.4	

D-□ -X□

RSQ

RSG RS2H

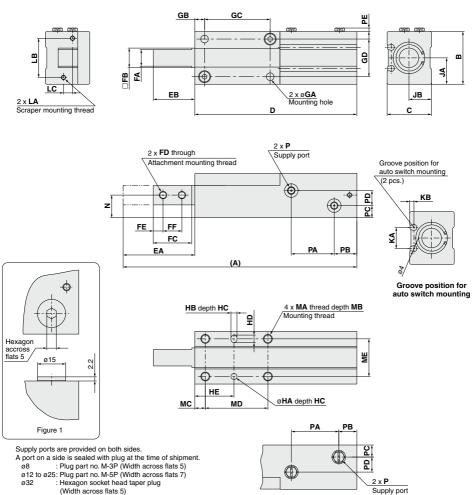
RSH

**SMC** 

# MIW/MIS Series

# **Dimensions/Single Finger Type**



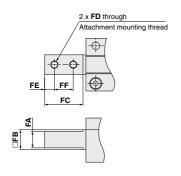


Model	Α	В	С	D	EA	EB	FA	FB	FC	FD	FE	FF	FG	GA	GB	GC	GD	HA, HB
MIS8-10	87	19	16	59	28	18	6.01	7h9 🐫 388	15	M3 x 0.5	4	7	6 (Effective	2.6	4	20	13	2H9 +0.025
MIS8-20	117	19	10	79	38	10	U-0.1	7113 -0.036	13	15   IVI3 X U.5	3 x 0.5 4	4 /	depth 2.5)	2.0	4	30	13	209 0
MIS12-10	105			72	33								6			28		
MIS12-20	135	26	21	92	43	23	8.0.1	10h9 🗓 🖂	19	M3 x 0.5	4.5	9.5	(Effective depth 3)	3.3	5	38	18	2.5H9 +0.025
MIS12-30	165			112	53								deptil 3)			48		
MIS20-10	125			86.5	38.5								10			32		
MIS20-20	155	35	29.5	106.5	48.5	28.5	11.01	13h9 🖧 🛚	25.5	M5 x 0.8	6.5	12.5	(Effective depth 4)	5.1	7	42	25	4H9 +0.030
MIS20-30	185			126.5	58.5								deptil 4)			52		
MIS25-30	215	41	40	144	71	41	15.81	17h9 🖧 😘	37	M6 x 1	10	17	15 (Effective	6.8	10	55	28	5H9 +0.030
MIS25-50	275	41	40	184	91	41	13.0.1	17110 -0.043	31	IVIOXI	10	17	depth 7)	0.0	10	75	20	20 509 0
MIS32-30	250	50	47	165	85	55	19.5 %	21h9 🔐	51	M8 x 1.25	12.5	22	17 (Effective	8.6	12	64	34	6H9+0.030
MIS32-50	310	50	47	205	105	55	19.5.01	21119 -0.052	51	IVIO X 1.25	12.5	22	depth 8.5)	0.0	12	84	34	опэ о

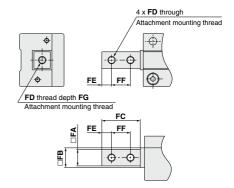
\* Refer to the Figure 1 for G thread

# Escapements **MIW/MIS** Series

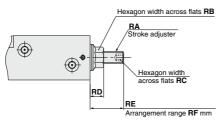
# Finger options Tapped on upper and lower faces



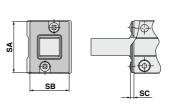
## Tapped on all faces



# With adjuster



# With scraper



Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

Model	НС	HD	HE	JA	JB	KA	KB	LA	LB	LC	MA	MB	MC	MD	ME	N	Р	PA	PB	PC
MIS8-10	2	3	14	9.5	7.5	6.2	1.6	M2 x 0.4	14	3	M3 x 0.5	5	4	20	13	7.5	M3 x 0.5	19	8	4.5
MIS8-20	_	3	14	9.5	7.5	0.2	1.6	W∠ X U.4	14	3	IVI3 X U.5	3	-	30	13	7.5	IVI3 X U.5	29	0	4.5
MIS12-10														28				19		
MIS12-20	4	3.5	17.5	13	11	11.6	2.2	M2.6 x 0.45	19	4	M4 x 0.7	7	5	38	18	11	M5 x 0.8	29	10	6
MIS12-30														48				39		
MIS20-10														32				20.5		
MIS20-20	5	5	26	17.5	15	14	2.8	M3 x 0.5	26	6	M6 x 1	10	7	42	25	15	M5 x 0.8	30.5	12	8
MIS20-30														52				40.5		
MIS25-30	5	7	32	20.5	20	11	3	M3 x 0.5	32	10	M8 x 1.25	14	10	55	28	20	M5 x 0.8	47	14	12
MIS25-50	3	′	32	20.5	20	l''	٥	IVIO X U.S	32	10	IVIO X 1.25	14	10	75	20	20	IVIS X U.6	67	14	12
MIS32-30	6	8	40	25	25	20.4	2.5	M4 x 0.7	39	12	M10 x 1.5	15	12	64	34	25	Rc1/8	47	14.5	44
MIS32-50	٥	° _	40	25	25	20.4	2.5	IVI4 X U.7	39	12	WIIU X 1.5	15	12	84	34	25	HC1/6	67	14.5	

Model	PD	PE	RA	RB	RC	RD	RE	RF	SA	SB	sc		
MIS8-10	6	2.2	M4 x 0.7	7	2	5.7	12.5	4	18.6	14	1.4		
MIS8-20	0	2.2	W4 X U.7	_ ′		5.7	12.5	4	10.0	14	1.4		
MIS12-10													
MIS12-20	7	3	M5 x 0.8	8	2.5	6	14	6	24	18	1.8		
MIS12-30													
MIS20-10													
MIS20-20	10	10	10	3	M8 x 1	12	4	9	22.5	12	34	26	2.2
MIS20-30													
MIS25-30	14	2.7	M8 x 1	12	4	9	26	15	40	36	2.8		
MIS25-50	14	2.1	IVIO X I	12	4	9	20	15	40	30	2.0		
MIS32-30	27		M12 x 1.25	17	6	12.4	33	20	49	41	3.4		
MIS32-50	21		W112 X 1.25	17	0	12.4	33	20	49	41	3.4		

**D-**□

RSQ RSG RS2H



# MIW/MIS Series Auto Switch Mounting

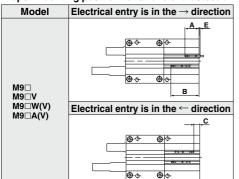
# **Auto Switch Mounting**

When mounting an auto switch, insert the auto switch in the switch mounting groove on the escapement from the direction as below figure. Having set the mounting position, tighten the attached auto switch mounting screws with a flat head watchmaker's screwdriver.

\* When adjusting the auto switch mounting screws, use a watchmaker's screwdriver with a handle 5 to 6 mm in diamterer. (This is to prevent fracture due to an excessive torque.) The guideline of the tightening torque is 0.1 to 0.15 N·m.

# Watchmaker's screwdriver ### Storage ### Storage ### Auto switch mounting screw M2.5 x 4 ### Auto switch ### Auto switch

## Proper mounting position for stroke end detection



## **Auto Switch Operating Range**

MIW (mm										
Auto switch model	ø8	ø12	ø <b>20</b>	ø <b>25</b>	ø <b>32</b>					
D-M9□(V) D-M9□W(V) D-M9□A(V)	3	2.5	4	5.5	7					

MIS					(mm)
Auto switch model	ø8	ø12	ø <b>20</b>	ø <b>25</b>	ø <b>32</b>
D-M9□(V) D-M9□W(V) D-M9□A(V)	3	3.5	4.5	5.5	7

Note) The operating ranges are provided as guidelines including hysteresis and are not guaranteed values (with ±30% variations). Hysteresis may fluctuate due to the operating environments.

													(mm)
		Proper mou	ntin	g position			Proper mou	ntin	g position			Proper moui	nting position
Model		D-M9 D-M9 V D-M9 W D-M9 WV D-M9 A D-M9 AV		Model		D-M9□ D-M9□W D-M9□A	D-	M9□V M9□WV M9□AV				D-M9□V D-M9□WV D-M9□AV	
	Α	10	16.5			Α	18	3.5			Α	7	.5
	В	2	25			В	49		[		3	8	
MIW8-8D	С	4	.5		MIS12-30D	С	6	.5		MIS25-30D	С	2	1
	D					D	-	_			D	-	-
	Ε	6		4		E	3.5		1.5		Ε	-	
	Α	10	6.5			Α	20	).5			Α	7	.5
	В		27			В		1			В		8
MIS8-10D	С	4	.5		MIW20-20D	С	8	.5		MIS25-50D	С	2	1
	D		_				D E	-					
	E	6		4		E	4		2			-	
	Α	-	6.5			Α		).5			Α		.5
	В	(	37		4 F	В	3	1			В		1
MIS8-20D	С	4	.5			С	8	.5		MIW32-32D	С	2	9
	D		_			D	-	_			D	-	-
	Е	6		4		Ε	4		2		E	_	_
	Α	-	8.5			A 20.5			В		.5		
	В		31			В		1					9
MIW12-12D	С	6	5.5		MIS20-20D	С	8	.5		MIS32-30D	С	2	9
	D					D	-	_			D	-	-
	Е	3.5		1.5		Ε	4		2		Е	-	_
	Α		8.5			Α		).5			Α		.5
	В		29			В		1			В		9
MIS12-10D	С	6	5.5		] [	С		.5		MIS32-50D	С		9
	D					D		_			D	-	-
	E	3.5		1.5		E	4		2		E	_	_
	Α		8.5			Α		.5					
	В		39			В		3					
MIS12-20D	С		6.5		MIW25-25D	С		1					
	D		-			D	-	-		Note) Adjus	t th	e auto swi	ch after con

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

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# MIW/MIS Series **Made to Order: Individual Specifications**

Please contact SMC for detailed dimensions, specifications and lead times.



Symbol

-X4

# Heat Resistant (-10 to 100°C)

Change seal material and greases, so that it can be used at an ambient temperature range from -10 °C to up to 100 °C.

## How to Order

MIW Standard model no. Heat resistant Note) Magnets are built-in, but the applicable ambient temperature is from -10 °C to 60 °C when auto switches are used.

### Specifications

Ambient temperature range	-10°C to 100°C
Seal material	Fluororubber
Grease	Heat resistant grease (GR-F)
Bore size (mm)	8, 12, 20, 25, 32

<sup>\*</sup> Dimensions other than the above is the same as the standard type.

Symbol

-X5

# Fluororubber Seal

How to Order

Standard model no. Fluororubber seal Note) Since the same magnets as for the standard type are built-in, contact SMC for the product adaptability to the operating environment before handling.

Specifications

Seal material	Fluororubber
Bore size (mm)	8, 12, 20, 25, 32

<sup>\*</sup> Dimensions other than the above is the same as the standard type.

Symbol

-X63

# How to Order

3 Fluorine Grease

Standard model no.

Fluorine grease

Specifications

Grease	PTFE grease (GR-F)
Bore size (mm)	8, 12, 20, 25, 32

<sup>\*</sup> Dimensions other than the above is the same as the standard type.

Symbol

RS2H RSH

RSQ

RSG

# Grease for Food

How to Order

Standard model no.

Grease for food

## **Specifications**

Grease	se				Grease for food							
Bore size (mm)						8, 12, 20, 25, 32						

<sup>\*</sup> Dimensions other than the above is the same as the standard type

# ♠ Warning

## **Precautions**

Be aware that smoking cigarettes, etc. after your hands have come into contact with the PTFE grease used for -X4 and -X63 may generate gas that is hazardous.



D-



Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

## Selection

# **⚠** Warning

- 1. Design the attachment to be light and short.
  - 1) A long and heavy attachment can cause a large inertia force in operation, sometimes affecting the life time.
  - 2) Design the attachment to be as short and light as possible even within the limitation.

## Mounting

# **⚠** Warning

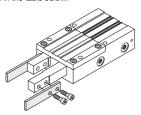
- 1. Do not scratch or gouge the escapement by dropping or bumping it when mounting.
  - Even a slight deformation can cause inaccuracy or malfunction.
- 2. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque beyond the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

## Mounting attachment on finger

When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.

Mount attachments by inserting bolts, etc. into the female mounting threads on the fingers and tightening with the torque shown in the table below.



Model	Bolt	Max tightening torque (N·m)		
MIW8	M3 x 0.5	0.88		
MIS8	IVIO X 0.5	0.00		
MIW12	M3 x 0.5	0.88		
MIS12	IVIO X U.S	0.00		
MIW20	M5 x 0.8	4.3		
MIS20	IVIO X U.O	4.3		
MIW25	M6 x 1	7.3		
MIS25	IVIO X I	7.3		
MIW32	M8 x 1.25	17.5		
MIS32	IVIO X 1.25	17.5		

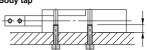
3. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque above the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

## Mounting

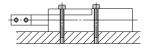
## Mounting

## Body tap



Model	Bolt	Max tightening torque (N·m)	Max screw-in depth (mm)	
MIW8	M3 x 0.5	0.88	6	
MIS8	IVIO X U.S	0.63	4.5	
MIW12	M4 x 0.7	1.5	6	
MIS12	IVI4 X U.7	1.5	0	
MIW20	M6 x 1	5.2	9	
MIS20	IVIO X I	5.2	9	
MIW25	M8 x 1.25	12.5	12	
MIS25	IVIO X 1.23	12.5	12	
MIW32	M10 x 1.5	04.5	45	
MIS32	IVIIU X 1.5	24.5	15	

## Body through hole



Model	Bolt	Max tightening torque (N·m)		
MIW8	M2.5 x 0.45	0.5		
MIS8	IVIZ.3 X 0.43	0.5		
MIW12	M3 x 0.5	0.88		
MIS12	IVIO X U.S	0.00		
MIW20	M5 x 0.8	4.3		
MIS20	IVID X U.O	4.3		
MIW25	M6 x 1	7.3		
MIS25	IVIOXI	7.3		
MIW32	M8 x 1.25	17.5		
MIS32	IVIO X 1.25	17.5		

# 

1. When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.

Otherwise malfunction may result.

2. Please do not scratch or gouge the sliding part of

It may increase the sliding resistance or cause abrasion.

3. Use a speed controller, etc. to keep the operating speed of the finger within the proper range.

Otherwise the life time may be adversely affected by inertia force of the attachment.

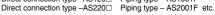
4. Conduct meter-out control to throttle down the speed.

Applicable speed controller

Direct connection type -AS120□ Piping type - AS1001F

**SMC** 

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Be sure to read this before handling the products.

Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

# **Changing of Piping Directions**

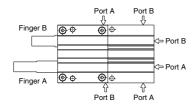
# **⚠** Caution

 Please observe the specified torque limits when tightening a plug to change the piping directions.

A tightening torque above the specified limits can cause a damage to the plug, while tightening torque below the specified limits can cause a damage to seal or the screw come loose during the operation.

Model	Port size	How to tight	
MIW8 MIS8	M3 x 0.5 (Plug part no: M-3P	Turn another 1/4 turn with a tool after manual tightening.	
MIW12 MIS12			
MIW20	M5 x 0.8 / Plug part no: \	Turn another 1/6 turn with a tool after manual tightening.	
MIS20	\ M-5P /		
MIW25			
MIS25			
MIW32	D-4/0	T	
MIS32	Rc1/8	Tightening torque 7 to 9 N·m	

### Supply port operation



Pressured from A port  $\to$  Finger A extends, finger B retracts Pressure from B port  $\to$  Finger B extends, finger A retracts

## **Handling of Adjuster Options**

## Stroke adjuster

# **⚠** Warning

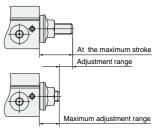
1. Observe the specified adjustment range as shown on right when adjusting with a stroke adjuster.

Bolts may shoot out when adjusting stroke adjuster over the maximum stroke as shown on right. Be sure to observe the specified adjustment range, otherwise malfunction may results.

## **Handling of Adjuster Options**

**⚠** Warning

Model	At the maximum stroke (mm)	At the maximum adjustment (mm)	Adjustment range (mm)
MIW8	12.5	8.4	4
MIS8	12.5	0.4	
MIW12	14	8	6
MIS12	14		
MIW20		10.5	12
MIS20	22.5	10.5	
MIW25		44	45
MIS25	26	11	15
MIW32		13	20
MIS32	33		



- 2. Be sure to use specified adjuster bolts for replacement.

  Otherwise, fracture may be caused by an impact etc.
- 3. Refer to the table below for the lock nut tightening torque.

Insufficient tightening can cause air leakage.

Tightening torque (N·m)	
1.2 to 1.5	
2.5 to 3.0	
10.5 to 12.5	
10.5 to 12.5	
34 to 42	
34 10 42	

## **Operating Environment**

# 

- Do not use in an environment where the product is directly exposed to liquid such as cutting lubricant.
  - Avoid use in an environment where the product is exposed to cutting lubricant, liquid coolant or oil mist. It can cause rattles, increase in sliding resistance and air leakage.
- Do not use in an environment where the product is directly exposed to foreign matter such as dust, coarse particular, chips and polishing powder from a spatter grinder, etc.
   It can cause rattles, increase in sliding resistance and air leakage.

, D-□ -x□

RSQ

RSG

RS2H

**RSH** 





Be sure to read this before handling the products.

Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

## **Operating Environment**

# **⚠** Caution

- Provide shading in an environment where the product is exposed to the sunlight.
- 4. Block off heat radiation in an environment where a heat source is at a close distance.

Block off heat radiation with a cover if a heat source is at a close distance because the temperature of the product can rise to exceed the operating temperature range due to radiation.

Do not use in an environment where vibration or impact occurs.

Contact SMC about use under such conditions because it can cause fracture or malfunction.

## Lubrication

# 

 The non-lubricant type escapement is lubricated at the factory and does not need further lubrication for use.

In case the product is lubricated by the customer, apply class 1 turbin oil (non additive) ISO VG32.

In case the product is lubricated by the customer, be sure to continue lubrication.

If it is discontinued, malfunction may result due to loss of initial lubricant.

## Maintenance

# **⚠** Warning

 Keep away hands and other body parts from the fingers of the escapement or movement range of the attachment.

It can lead to an injury or accident.

When removing the escapement, first block off or remove the workpiece on the primary side of the escapement, release compressed air and remove it. If the work piece remains, it can be transferred by mistake and cause failure to the equipment on the secondary side.

## Finger replacement

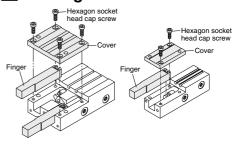
- 1. Remove the hexagon socket head screws.
- 2. Remove the cover.
- 3. Replace the finger.
  - a Apply the specified grease to the finger, body, cover and T groove part of the finger.
  - b Insert the piston in the T groove so that it will be hooked
- Fix the cover and tighten the hexagon socket head cap screws.

Bore	size	Hexagon socket head cap screw	Hexagon width across flats	Tightening torque (N·m)
8	}	M2 x 6	1.5	0.24
12	2	M2.5 x 6	2	0.36
20	0	M4 x 10	3	1.5
2	5	M5 x 14	4	3.0
32	2	M6 x 15	5	5.2

Note) For assembly, apply Henkel Japan Loctite No.243 or equivalent adhesive and tighten with the specified tightening torque.

## Maintenance

# **⚠** Warning



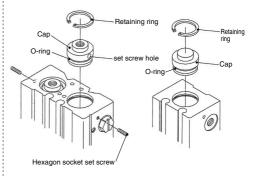
## Finger and position connection



## Replacement Procedure of Seal

- Remove the cover and the finger. (Refer to Replacement Procedure of Finger)
- Loosen the hexagon socket set screws. (Refer to the table of hexagon socket set screw size).
  - $\ast$  For MIS, hexagon socket set screw is not included except for the stroke adjusting type.
- Remove the retaining ring with spring pliers to remove the cap.
  - \* If there are any questions for ø8, please consult SMC.

Bore size	Hexagon socket set screw	Hexagon width across flats	Tightening torque (N·m)
8	M2 x 6	0.9	0.176
12	M2 x 6	0.9	0.176
20	M3 x 8	1.5	0.63
25	M4 x 8	2	1.5
32	M4 x 8	2	1.5





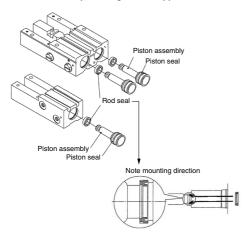
Be sure to read this before handling the products.

Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

## Maintenance

# 

Take out the piston assembly and replace the seal, to which the specified grease is applied.



Apply the specified grease lightly to the sliding interface between the outer periphery and the body of the piston, and assemble them in the reversed order.

## **Scraper Option**

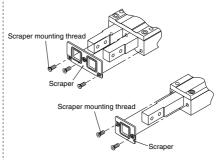
# **⚠** Caution

 Please observe the specified torque limits when mounting a scraper.

A tightening torque above the specified limits can cause a damage, while tightening torque below the specified limits can cause a dislocation or drop off.

## **Tightening torque**

Model	Bolt (N·m)	
MIW8	0.176	
MIS8		
MIW12	0.36	
MIS12		
MIW20	0.63	
MIS20	0.63	
MIW25	0.63	
MIS25	0.63	
MIW32	1.5	
MIS32	1.5	



RSQ

RSG RS2H

RSH

MIW

D-□ -X□

