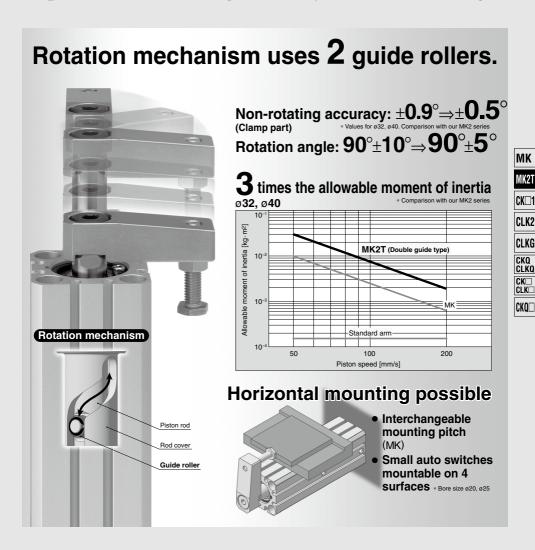
Rotary Clamp Cylinder

MK2T Series

Double Guide Type

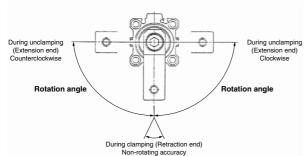
Improved non-rotating accuracy and rotation angle!



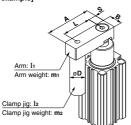
Model Selection

Item	Series	MK2T
	ø12, ø16	_
Max. piston speed Note) [mm/s]	ø 20 , ø 25	200
	ø32 to ø63	200
	ø12	_
	ø 16	_
Non-rotationg accuracy (Clamp part)	ø 20 , ø 25	±1.0°
(Champ party	ø 32 , ø 40	±0.5°
	ø 50 , ø 63	±0.5°
Rotation angle		90°±5°
Horizontal mounting		Allowed

Note) "Maximum piston speed" indicates the maximum speed possible when employing a standard arm.



[Actual calculation example]



Example) Find the moment of inertia of the arm.

$$I_1 = m_1 \cdot \frac{\textbf{A}^2 + \textbf{B}^2}{12} + m_1 \cdot \left[\frac{\textbf{A}}{2} - \textbf{S}\right]^2$$

Find the moment of inertia of the clamp jig.

$$I_2 = \mathbf{m}_2 \cdot \frac{\mathbf{D}^2}{8} + \mathbf{m}_2 \cdot \mathbf{L}^2$$

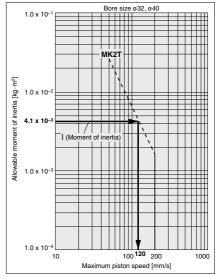
(Calculation example) Cylinder bore size ø32

A = 0.1 m, **B** = 0.035 m, **S** = 0.012 m, **L** = 0.075 m, **D** = 0.024 m m_1 = 0.96 kg, m_2 = 0.32 kg m_2 = 0.00 m_1 = 0.0035² = 0.00 m_2 = 0.004 m_2 = 0.004 m_3 = 0.004 m_2 = 0.004 m_3 = 0.

$$\begin{split} I_1 &= 0.96 \times \frac{0.1^2 + 0.035^2}{12} + 0.96 \times \left[\frac{0.1}{2} - 0.012 \right]^2 = 2.3 \times 10^{-3} \text{ kg} \cdot \text{m}^2 \\ I_2 &= 0.32 \times \frac{0.024^2}{8} + 0.32 \times 0.075^2 = 1.8 \times 10^{-3} \text{ kg} \cdot \text{m}^2 \end{split}$$

Find the actual moment of inertia.

$$I = I_1 + I_2 = (2.3 + 1.8) \times 10^{-3} = 4.1 \times 10^{-3} \text{ kg} \cdot \text{m}^2$$



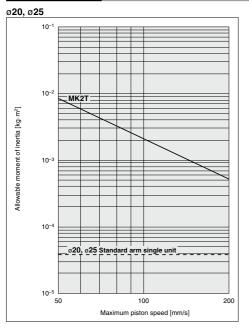
Calculation Example (ø32, clamp stroke 10 mm)

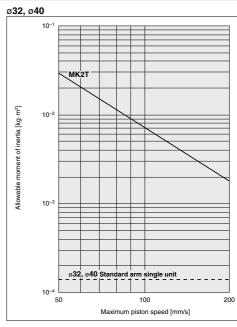
Max. piston speed	Average piston speed Note 1)	Stroke total	Stroke time Note 2)
120 mm/s	75 mm/s	39 mm	0.52 sec.

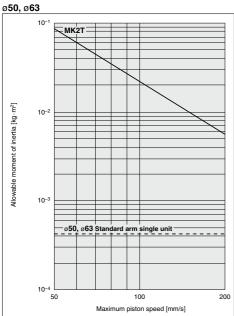
Note 1) Average piston speed = Maximum piston speed + 1.6. Note 2) Please use the stroke speeds indicated above.

Model Selection **MK2T Series**

Moment of Inertia







Note) Maximum piston speed is equivalent to approximately 1.6x the average piston speed. (Rough indication)



-X□

MK MK2T

> CK□1 CLK2

CLKG

CKQ CLKQ

CK.

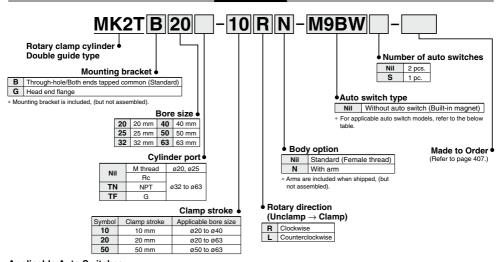
|CKQ□

Rotary Clamp Cylinder: Double Guide Type

MK2T Series

Ø20, Ø25, Ø32, Ø40, Ø50, Ø63

How to Order



Applicable Auto Switches/Refer to pages 941 to 1067 for further information on auto switches.

		Electrical	ight	Wiring	L	Load voltage Auto switch model			Lea	d wir	e len	igth	(m)	Pre-wired	A 1								
Туре	Special function	entry	Indicator light	(Output)	D	С	AC		odicular ø32 to ø63	In- ø20 ø25		0.5 (Nil)	1 (M)	3 (L)		None (N)	connector		cable ad				
			_	3-wire (NPN)		5 V,			NV		N N	•	_	•	0	_	0	10					
		Grommet		3-wire (PNP)		12 V		M9	PV	M	9P	•	-	•	0	_	0	IC circuit					
동				2-wire		12 V		M9	BV	M	9B	•	_	•	0	_	0	_					
switch		Connector		Z-WIIE		12 V		_	J79C	-	-	•	_	•	•	•	_						
0.0	Diagnostic indication			3-wire (NPN)		5 V,			/WV	M9		•	•	•	0	_	0	IC circuit					
anto	(2-color indicator)			3-wire (PNP)		12 V			PWV	M9		•	•	•	0	_	0	10 circuit	Relay,				
Solid state	(=,		Yes		24 V	12 V	_		3WV	M9		•	•	•	0	_	0	_	PLC				
St	Water resistant			3-wire (NPN)		5 V,			AV*1	M9N		0	0	•	0	_	0	IC circuit					
흗	(2-color indicator) Grommet		3-wire (PNP)		12 V			AV*1	M9F		0	0	•	0	_	0							
ŭ	Diameter and a			2-wire		12 V		M9B	AV*1	M9E		0	0	•	0	_	0	_					
	Diagnostic output (2-color indicator)			4-wire		5 V, 12 V	5 V, 12 V	5 V, 12 V	5 V, 12 V	5 V, 12 V	1	-	_		F79F	•	<u> </u>	•	0	_	0	IC circuit	
	Magnetic field resistant			2-wire		_		_	-		_ P3I	OWA***	•	_	•	•	_	•	_				
	(2-color indicator)			(No polarity)				-			P4DW**	_	_	•	•	_	0						
당			V	3-wire (NPN equivalent)	_	5 V	_	A9	6V	A	96	•	-	•	_	_	_	IC circuit	_				
switch			200 V	_	A72		A72H	•	_	•	_	_	_										
						12 V	100 V	A93	8V*2	A	93	•	•	•	•	_	_	_					
arı			No 2-wire 5 V, 12 V	100 V or less	A9	OV VO	A	90	•	_	•	_	_	_	IC circuit	Relay,							
Reed auto		Connector	Yes	2 10116	24 V	12 V	_	_	A73C	_	-	•	_	•	•	•		_	PLC				
æ			No	1		5 V, 12 V	24 V or less	_	A80C	-	-	•	-	•	•	•	_	IC circuit					
	Diagnostic indication (2-color indicator)	Grommet	Yes				_	_	A79W	_	-	•	_	•	_	_		_					

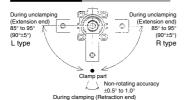
- *1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
- Consult with SMC regarding water resistant types with the above model numbers.
- *2 1 m type lead wire is only applicable to D-A93.
- * Lead wire length symbols: 0.5 m ········ Nil (Example) M9NW * Solid state auto switches marked with "O" are produced upon receipt of order.
 - 1 m M (Example) M9NWM ** For D-P4DW, ø40 to ø63 are available.
 3 m L (Example) M9NWL ** Only D-P4DW type is assembled at the time of shipment.
 - 5 m ········ Z (Example) MSNWZ *** The D-P3DWA□ is mountable on bore size ø25 to ø63. None ········· N (Example) J79CN
- * Since there are other applicable auto switches than listed, refer to page 413 for details.
- * For details about auto switches with pre-wired connector, refer to pages 1014 and 1015.

 * When D-M9□(V)/M9□A(V)/A9□(V) types with ø32 to ø50 are mounted on a side other than the port side, order auto switch mounting brackets separately. Refer to page 414 for details.
- * Auto switches are shipped together (not assembled).

Rotary Clamp Cylinder: Double Guide Type **MK2T** Series



Rotary Angle





Made to Order: Individual Specifications (For details, refer to page 415.)

Symbol	Description
-X1859	With head end pin hole

Made to Order (Refer to pages 1069 to 1262 for details.)

Symbol	Specifications
-XC89	Spatter resistant coil scraper, Lube-retainer, Grease for welding (Piston rod: S45C)
-XC91	Spatter resistant coil scraper, Grease for welding (Piston rod: S45C)

Option/Arm

Bore size (mm)	Part no.	Accessories
20	MK-A020Z	Clamp bolt,
25	WIK-AUZUZ	Hexagon socket
32	MK-A032Z	head cap screw,
40	WIK-AU322	Hexagon nut,
50	MK-A050Z	Spring washer
63	MK2T-A063	Opring washer

Mounting Bracket/Flange

Bore size (mm)	Part no.	Accessories
20	CQS-F020	
25	CQS-F025	
32	MK2T-F032	Hexagon socket
40	MK2T-F040	head cap screw
50	MK2T-F050	
63	MK2T-F063	

Specifications

Bore size (mm)	20	25	32	40	50	63		
Action	Double acting							
Rotation angle Note 1)			90	° ±5°				
Rotary direction Note 2)		CI	ockwise, Co	ounterclock	wise			
Rotary stroke (mm)	1	9	2	9	3	3		
Clamp stroke (mm)		10	20		20	, 50		
Theoretical clamp force (N) Note 3)	100	185	300	525	825	1300		
Fluid				Air				
Proof pressure	1.5 MPa							
Operating pressure range			0.1 to	1 MPa				
A bit	Without auto switch: -10 to 70°C (No freezing)							
Ambient and fluid temperature	With auto switch: -10 to 60°C (No freezing)							
Lubrication			Nor	n-lube				
Piping port size	M5 :	x 0.8	Rc1/8, NP	T1/8, G1/8	Rc1/4, NP	T1/4, G1/4		
Mounting	Throu	gh-hole/Bot	h ends tap	oed commo	n, Head er	d flange		
Cushion	Rubber bumper							
Stroke length tolerance	+1.0 0							
Piston speed	50 to 200 mm/s							
Non-rotating accuracy (Clamp part)	±1	.0°		±0	.5°			

Note 1) Refer to "Rotary Angle" figure.

Note 2) Direction of rotation viewed from the rod end when the piston rod is retracting. Note 3) At 0.5 MPa.

Theoretical Output

							Unit: N
Bore size	Rod size	Operating			Operating pre	essure (MPa)	
(mm)	(mm)	direction	(cm²)	0.3	0.5	0.7	1.0
20	12	R	2	60.8	100	139	200
20	12	Н	3	90.2	149	208	298
25	12	R	3.7	112	185	258	370
	12	Н	4.9	149	245	341	490
32	16	R	6	182	300	418	600
		Н	8	243	400	557	800
40	16	R	10.5	319	525	731	1050
40	10	Н	12.5	380	625	870	1250
50	20	R	16.5	502	825	1149	1648
30	20	Н	19.6	596	980	1365	1961
63	25	R	26	780	1300	1820	2600
	25	Н	31.2	948	1560	2172	3121

Note) Theoretical output (N) = Pressure (MPa) x Piston area (cm²) x 100

Operating direction R: Rod end (Clamp) H: Head end (Unclamp)

Unit: o

Weight/Through-hole Mounting

Clamp stroke	Bore size (mm)								
(mm)	20	25	32	40	50	63			
10	367	448	806	1008	_	_			
20	433	520	914	1127	2049	2609			
50	_	_	_	_	2672	3354			

Additional Weight

						Unit: g
Bore size (mm)	20	25	32	40	50	63
With arm	100	100	200	200	350	600
Head end flange (including mounting bolt)	133	153	166	198	345	531

Calculation: (Example) MK2TG20-10RN

 Standard calculation: 	MK2TB20-10R	367 g
 Extra weight calculation: 	Head end flange	133 g
_	With arm	100 g
_		600 g

D--X□

MK

MK2T

CK□1

CLK2

CLKG

CKQ

CLKQ CK□ CLK

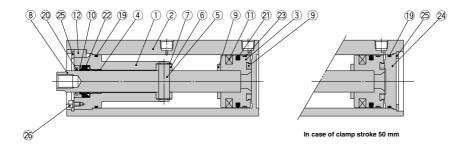
|CKQ□



Construction

MK2T□20 to 63

With arm (N) Head end flange (G) (15)



Component Parts

No.	Description	Material	Note
1	Rod cover	Structural steel	
2	Cylinder tube	Aluminum alloy	
3	Piston	Aluminum alloy	
4	Bushing	Oil-impregnated sintered alloy	ø20, 25
4	busning	Bronze casted	ø32 to 63
5	Guide shaft	Stainless steel	ø20, 25
3	Guide Shart	Structural steel	ø32 to 63
6	Guide roller	Structural steel	
7	Retaining ring	Steel for special applications	ø20, 25
,	netalling fing	Steel for special applications	ø32 to 63
8	Piston rod	Stainless steel	ø20, 25
•	Piston roa	Structural steel	ø32 to 63
9	Bumper	Urethane	
10	Seal retainer	Aluminum alloy	
11	Magnet	_	
12	Key	Structural steel	

Component Parts

No. Description Material Note 13 Arm Structural steel	
13 Arm Structural steel	
14 Clamp bolt Structural steel	
15 Hexagon nut Structural steel	
16 Hexagon socket head cap screw Structural steel	
17 Spring washer Steel wire	
18 Flange Structural steel	
19 Gasket NBR	
20 Coil scraper Bronze	
21 Piston seal NBR	
22 Rod seal NBR	
23 Wear ring Resin	
24 Bottom plate Aluminum alloy	
25 Retaining ring Steel for special applications	
Hexagon socket head cap screw (with SW) Structural steel	
Washer Stainless steel ø25, ø32 on	у
Hexagon socket head cap screw Structural steel	

(18) (16)

Replacement Parts: Seal Kit

Bore size (mm)	20	25	32	40	50	63		
Kit no.	MK2T20-PS	MK2T25-PS	MK2T32-PS	MK2T40-PS	MK2T50-PS	MK2T63-PS		
Content	Set of nos. above (9 @ 2) @							

^{*} Seal kit includes (9, 20, 2), (2). Order the seal kit, based on each bore size.



Rotary Clamp Cylinder: Double Guide Type **MK2T** Series

↑ Precautions

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Clamp Arm Mounting

1. Use a clamp arm that is available as an option. To fabricate a clamp arm, make sure that the allowable bending moment and the inertial moment will be within the specified range. If a clamp arm that exceeds the specified value is installed, the internal mechanism in the cylinder could become damaged.

Ensuring Safety

1. If one side of the piston is pressurized by supplying air with the clamp arm attached, the piston will move vertically while the clamp arm rotates. This operation could be hazardous to personnel, as their hands or feet could get caught by the clamp arm, or could lead to equipment damage. Therefore, it is important to secure as a danger zone a cylindrical area with the length of the clamp arm as its radius, and the stroke plus 20 mm as its height.

Installation and Adjustment/ Clamp Arm Removal and Reinstallation

 During the removal or reinstallation of the clamp arm, make sure to use a wrench or a vise to secure the clamp arm before removing or tightening the bolt.

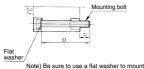
This is to prevent the bolt tightening torque from being applied to the piston rod, which could damage the cylinder's internal mechanism.

Mounting Bolt for MK2TB

Mounting: Mounting bolt for through-hole type is available.

Refer to the following for ordering procedures. Order the actual number of bolts that will be used.

Example) CQ-M5 x 115 L 4 pcs.



Note) Be sure to use a flat washer to mou cylinders via through-holes.

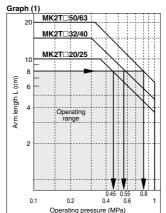
Cylinder model	С	D	Mounting bolt part no.
MK2TB20-10	11	115	CQ-M5 x 115 L
MK2TB20-20	11	135	CQ-M5 x 135 L
MK2TB25-10	8.5	115	CQ-M5 x 115 L
MK2TB25-20	8.5	135	CQ-M5 x 135 L
MK2TB32-10	11.5	145	CQ-M5 x 145 L
MK2TB32-20	11.5	165	CQ-M5 x 165 L
MK2TB40-10	7.5	145	CQ-M5 x 145 L
MK2TB40-20	7.5	165	CQ-M5 x 165 L
MK2TB50-20	13.5	185	CQ-M6 x 185 L
MK2TB50-50	10	245	CQ-M6 x 245 L
MK2TB63-20	13	185	CQ-M8 x 185 L
MK2TB63-50	14	250	CQ-M8 x 250 L

Precautions for Designing and Mounting Arms

When arms are to be made separately, their length and weight should be within the following range. When mounting the cylinder horizontally, also select within the same operating range as the following items.

1. Allowable bending moment

Use the arm length and operating pressure within Graph (1) for allowable bending moment loaded piston rod.



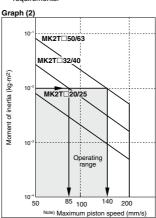


When arm length is 8 cm, pressure should be less than

MK2T□20/25: 0.45 MPa MK2T□32/40: 0.55 MPa MK2T□50/63: 0.8 MPa.

2. Moment of inertia

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within Graph (2) based on arm requirements.



speed. (Rough indication)

When arm's moment of inertia is 1 x 10⁻² kg·m², cylinder speed should be less than MK2T□32/40: 85 mm/s MK2T□50/63: 140 mm/s. For calculating moment of inertia, refer to

pages 404, 405 and 418.

Note) Maximum piston speed is equivalent to approximately 1.6x the average piston speed (Pounth indirection).

 To attach and detach the arm to and from the piston rod, fix the arm with a wrench or vise and then tighten the bolt.

(If an excessive force is applied in the rotary direction, it may bring about the damage to the internal mechanism.)

Refer to the following table for the tightening torque for mounting.

-	(N-m)
Bore size (mm)	Proper tightening torque
20, 25	11.5 to 14.0
32, 40	24 to 30
50	75 to 90
63	106 to 127





MK

NK2T

CK□1

CLK2

CLKG

CKQ

CLKQ

CK

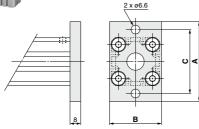
CLK

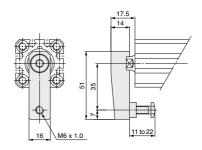
CKQ□



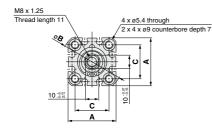


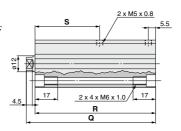
Dimensions: Ø20, Ø25





Head End	(mm)				
Model	Α	В	С		
MK2TG20	60	39	48		
MK2TG25	64	42	52		

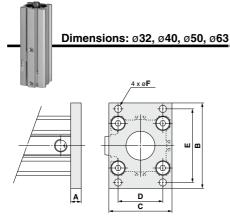


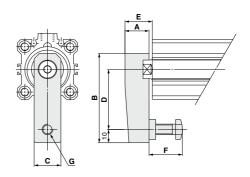


Through-hole/Both Ends Tapped Common (Standard)

· · · · · · · · · · · · · · · ·	mough noise zour zines reppos common (otanias s) (min)											
Bore size		øВ	•	Clam	p stroke 1	0 mm	Clamp stroke 20 mm					
Bore size	Dore Size A		C	Q	R	S	Q	R	S			
20	36	47	25.5	116.5	110.5	59	136.5	130.5	69			
25	40	52	28	119	113	59	139	133	69			

Rotary Clamp Cylinder: Double Guide Type **MK2T Series**





Head End Flange

	rioda Eria i lango									
Model	Α	В	С	D	E	ø F				
MK2TG32	8	65	48	34	56	5.5				
MK2TG40	8	72	54	40	62	5.5				
MK2TG50	9	89	67	50	76	6.6				
MK2TG63	9	108	80	60	92	9				

With Arm

***************************************							(mm)
Model	Α	В	С	D	Е	F	G
MK2T□32□-□□N	18	67	20	45	21.5	15 to 25	M8 x 1.25
MK2T□40□-□□N	18	67	20	45	21	15 to 25	M8 x 1.25
MK2T□50□-□□N	22	88	22	65	29.5	20 to 40	M10 x 1.5
MK2T□63□-□□N	32	91	32	65	34.5	20 to 40	M10 x 1.5

MK2T

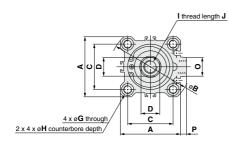
CK□1

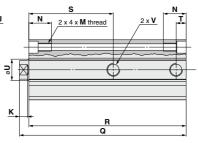
CLK2

CKQ CKQ

CK□ CLK□

CKQ□





Through-hole/Both Ends Tapped Common (Standard)

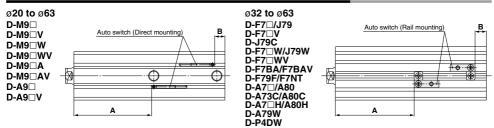
ı nrougn-ı	nrough-hole/Both Ends Tapped Common (Standard) (mm														(mm)		
Bore size	Α	øВ	С	D	G	н			v	М	Z	0	Р	øU		٧	
Bore size	^	νь	٥	U	u	п		,	~	IVI	IN	U	F	٥٥	Nil	TN	TF
32	45	60	34	14 -0.07	5.5	9 depth 7	M10 x 1.5	12	6	M6 x 1.0	17	14	4.5	16	Rc 1/8	NPT 1/8	G 1/8
40	52	69	40	14 -0.15	5.5	9 depth 7	M10 x 1.5	12	6	M6 x 1.0	17	14	5	16	Rc 1/8	NPT 1/8	G 1/8
50	64	86	50	17 -0.07	6.6	11 depth 8	M12 x 1.75	15	7	M8 x 1.25	22	19	7	20	Rc 1/4	NPT 1/4	G 1/4
63	77	103	60	22 -0.07	9	14 depth 10.5	M16 x 2	21	8	M10 x 1.5	28.5	19	7	25	Rc 1/4	NPT 1/4	G 1/4

Bore size	С	amp stro	ke 10 m	m	С	lamp stro	ke 20 m	m	Clamp stroke 50 mm			
Bore Size	Q	R	S	Т	Q	R	S	Т	Q	R	S	Т
32	148	140	74	7.5	168	160	84	7.5	_	_	_	_
40	151.5	144	75	8	171.5	164	85	8	_	_	_	_
50	_	_	_	_	191	179	91.5	12.5	254.5	242.5	121.5	14
63	_	_	_	_	192	182	93	10.5	256	246	123	15

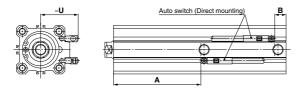
D-□ -X□

Auto Switch Mounting

Auto Switch Proper Mounting Position (Detection at Stroke End)



ø25 to ø63 D-P3DWA



Auto switch	D-P3DWA							
Bore size model	Α	В	U					
25	56.5	6.5	33					
32	71.5	9	35.5					
40	72.5	11.5	39					
50-20st	88	17	45					
50-50st	118	20.5	45					
63-20st	90	18	48.5					
63-50st	120	22	48.5					

Note) For bore sizes ø32 to ø50, the D-P3DWA is mountable only on the port side.

Mounting		Rail mounting					Direct mounting							
Model	D-A7 del D-A8		D-A7□H D-A73C/ D-F7□/F D-F7□V/ D-F7BA D-J79W/	A80C 79F/J79 /J79C □/F7□W	C /J79 C C 7□W		D-P4DW		D-M9□ D-M9□V D-M9□W D-M9□WV D-M9□A		D-A9□ D-A9□V		D-F7NT	
	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В
MK2T20	_	_	_	_	_	_	_	_	60.5	9	56.5	5	63	11.5
MK2T25	_	_	_	_	_	_	_	_	61	11	57	7	63.5	13.5
MK2T32	73 (73.5)	10.5 (11)	73.5	11	70.5	8	_	_	76	13.5	72	9.5	78.5	16
MK2T40	74 (74.5)	13 (13.5)	74.5	13.5	71.5	10.5	70	9	77	16	73	12	79.5	18.5
MK2T50-20st	89.5 (90)	18.5 (19)	90	19	87	16	85.5	14.5	92.5	21.5	88.5	17.5	95	24
MK2T50-50st	119.5 (120)	22 (22.5)	120	22.5	117	19.5	115.5	18	122.5	25	118.5	21	125	27.5
MK2T63-20st	91.5 (92)	19.5 (20)	92	20	89	17	87.5	15.5	94.5	22.5	90.5	18.5	97	25
MK2T63-50st	121.5 (122)	23.5 (24)	122	24	119	21	117.5	19.5	124.5	26.5	120.5	22.5	127	29

^{* ():} D-A72

Note) When setting an auto switch, confirm the operation and adjust its mounting position.

Auto Switch Mounting MK2T Series

Operating Range

Operating Range (Dimensions) (mm)						(mm)	
Auto switch model		Bore size					
Auto switch model	20	25	32	40	50	63	
D-M9□/M9□V	3	3.5	4.5	4.5	5	5	
D-M9□W/M9□WV D-M9□A/M9□AV	5.5	5.5	6.5	5.5	6.5	6.5	
D-A9□/A9□V	9	9.5	9	9.5	9.5	11	
D-F7□/J79 D-F7□V/F79F/J79C D-F7□W/F7□WV D-F79F/F7BA/F7BAV/F7NT	-	_	6	6	6	6.5	
D-A7□/A80 D-A7H/A80H D-A73C/A80C	-	_	9.5	11.5	11	13.5	
D-A79W		_	6	7	7	9.5	
D-P3DWA	_	5.5	6	6	6.5	6.5	
D-P4DW	_	_	_	5	5	5	

* Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion.)

There may be the case it will vary substantially depending on an ambient environment.

* Figures for models D-M9□(V), M9□W(V), M9□A(V), and A9□(V) with ø32 or more indicate the operating range when using the current auto switchmounting groove, without using auto switch mounting bracket (BQ2-012).

Other than the models listed in "How to Order", the following auto switches are applicable. For detailed specifications, refer to pages 941 to 1067.

Auto switch type	Model	Electrical entry	Features	Applicable bore size	
	D-F7NV, F7PV, F7BV		_		
	D-F7NWV, F7BWV	Grommet (Perpendicular)	Diagnostic indication (2-color indicator)		
	D-F7BAV		Water resistant		
Solid state	D-F79, F7P, J79		_	ø32 to ø63	
Solid State	D-F79W, F7PW, J79W		Diagnostic indication (2-color indicator)		
	D-F7BA	Grommet (In-line)	Water resistant (2-color indicator)		
	D-F7NT		With timer		
	D-P5DW		Magnetic field resistant	ø40 to ø63	
	D-A73	Grommet (Perpendicular)	_	ø32 to ø63	
Reed	D-A80	Grommet (Ferpendicular)	Without indicator light		
neea	D-A73H, A76H	Grommet (In-line)	_		
	D-A80H	Grommet (in-line)	Without indicator light]	

* With pre-wired connector is available for solid state auto switches, too. For details, refer to pages 1014 and 1015.

will pre-wired connector is available for solid state auto switches, too. For details, refer to pages 1014 and 1015.
 Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 959.

MK21

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CK□1

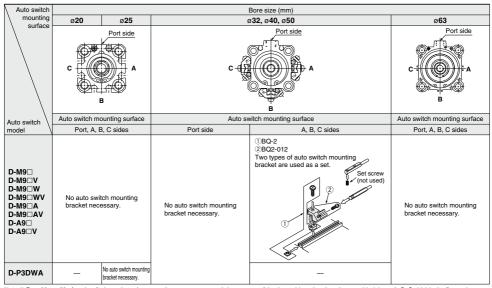
CLK2 CLKG

CKQ CLKQ

CK□ CLK□

CKQ□

Auto Switch Mounting Bracket/Part No.



Note 1) For e32 to e50 of each cylinder series, when mounting compact auto switches on one of the three sides other than the port side (above A, B, C side) in the figure above, a separate auto switch mounting bracket is necessary as shown in the table above, so please order one separately from the cylinder.

(The same is true when mounting compact auto switches with the auto switch mounting rail, not using the compact auto switch mounting groove, for diameters e63.) Example

MK2TB32-10R-M9BW ---- 1 unit

BQ-2 ····· 2 pcs. BQ2-012 ····· 2 pcs

Note 2) When the cylinder is shipped, an auto switch mounting bracket and auto switch are included in the shipment.

	Bore size (mm)				
Auto switch model	32	40	50	63	
D-F7□/J79 D-F7□V D-F7□W/J79W D-F7□W/J79W D-F7BA/F7BAV D-F79F/F7NT D-A7□/J880 D-A73□/J880H D-A79W		во) -2		
D-P4DW	_		BQP1-050		

Note 3) When the cylinder is shipped, an auto switch mounting bracket and auto switch are included in the shipment. However, ø40 to ø63 with the D-P4DW are assembled at the time of shipment.

[Mounting screw set made of stainless steel]

The set of stainless steel mounting screws (with nuts) described below is available and can be used depending on

the operating environment. (Please order the auto switch spacer BQ-2, since it is not included.)
The "D-F7BA/F7BAV" switch is set on the cylinder with the stainless steel screws above when shipped.

When only a switch is shipped independently, "BBA2" screw set is attached.

Note 4) When mounting D-M9□A(V) anywhere other than the port side of ø32, ø40, ø50, please order auto switch mounting brackets BQ2-012S, BQ-2, and the stainless steel screw set BBA2 separately.

Detailed Contents of Stainless Steel Mounting Screw Set

Part	Part Content			Applicable auto switch mounting	Applicable				
no.	Description	Size	No.	bracket part no.	auto switch				
	Auto switch mounting screw	M3 x 0.5 x 8 L	1	BQ-1	D-A7				
BBA2	Auto switch mounting screw	M3 x 0.5 x 10 L	1	BQ-2	D-A8				
DDAZ	Auto switch mounting nut (Square nut)	M3 x 0.5	1	BQ-1	D-F7				
	Auto switch mounting nut (Convex type)	M3 x 0.5	1	BQ-2	D-J7				

Note 5) When using BQ-1, BBA2 may be used by itself.

When using BQ-2, BQ-2 and BBA2 should be used together as a set, and used in combination with the auto switch spacer (black resin material) and stainless steel screws.

spacer (black resin material) and stainless steel screws



Auto Switch Mounting Bracket Weight

Mounting bracket part no.	Weight (g)
BQ-1	1.5
BQ-2	1.5
BQ2-012	5
BQP1-050	16

MK2T Series Made to Order: Individual Specifications

Please contact SMC for detailed dimensions, specifications and lead times.



1 With Head End Pin Hole

Symbol -X1859

How to Order

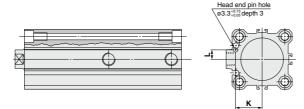
MK2T Standard model no. - X1859

With head end pin hole

Specifications

Applicable series	MK2T		
Bore size	ø32, ø40, ø50, ø63		
Specifications other than above	Same as standard product		

Dimensions



Bore size (mm)	к	L		
32	20±0.15	7±0.15		
40	24±0.15	7±0.15		
50	30 ±0.15	8±0.15		
63	35±0.15	9±0.15		

^{*} Dimensions other than above are same as basic type.

MK

MK2T CK□1

CLK2

CLKG

CKQ CLKQ

CK =

CKQ□





MK2T Series Specific Product Precautions 1

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Operating Environment

⚠ Warning

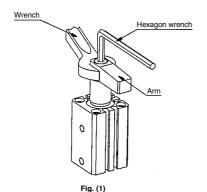
- Do not use the cylinder under following environments:
 - An area in which fluids such as cutting oil splash on the piston rod.
 - An area in which foreign matter such as particles, cutting chips, dust, or spatter is present.
 - An area in which the ambient temperature exceeds the operating range.
 - 4) An area exposed to direct sunlight.
 - 5) An environment that poses the risk of corrosion.

Clamp Arm Removal and Reinstallation

 To remove and reinstall the arm on the piston rod, instead of securing the cylinder body, use a wrench to secure the arm to loosen or to tighten the bolt (Fig. (1)).

An excessive amount of rotational force will be applied to the piston rod if the bolt is tightened by securing the cylinder body, which could damage the internal parts.

To fabricate an arm, make sure to machine a detect portion that corresponds to the parallel section at the rod end.



Speed Adjustment

⚠ Warning

 Make sure to connect a speed controller to the cylinder and adjust it so that the cylinder speed will be within a range of 50 to 200 mm/s.

If a clamp arm other than the available option is used, make sure to select an appropriate arm after calculating the inertial moment of the arm.

To operate a speed controller, make sure that the valve is fully closed, and gradually open the valve to adjust the speed.



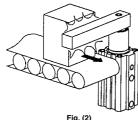
MK2T Series **Specific Product Precautions 2**

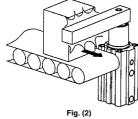
Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

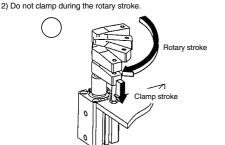
Operating Environment

⚠ Warning

- 1. A cylinder could malfunction or the non-rotating accuracy could be affected if a rotational force is applied to the piston rod. Therefore, observe the particulars given below before operating the cylinder.
 - 1) Do not absolutely perform any work (such as clamping or acting as a stopper, etc.) in the rotary direction (Fig. (2)).
 - 2) To clamp, make sure to do so within the clamp stroke (straight-line stroke) range (Fig. (3)).
 - 3) Make sure that the clamping surface of the workpiece is perpendicular to the cylinder's axial line (Fig. (4)).
 - 4) Do not operate the cylinder in such a way that an external force causes the workpiece to move while being clamped (Fig. (5)).
 - 5) Furthermore, do not operate the cylinder in an application in which a rotational force will be applied to the piston rod.
- 1) Do not perform any work in the rotary direction.







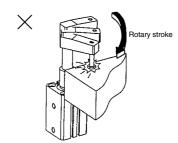
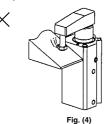
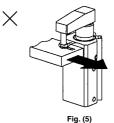


Fig. (3)

3) Do not clamp on a slanted surface.



4) Make sure that the workpiece does not move during clamping.



D- \square -X□

MK MK2T CK□1 CLK₂

CI KG CKQ CLKQ

CK□ CLK CKQ□





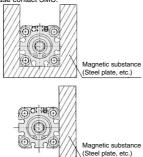
MK2T Series Specific Product Precautions 3

Be sure to read this before handling the products.

Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Mounting

 When a magnetic substrate surrounds the cylinder as shown in the figure below (including when the magnetic substrate is only on one side of the cylinder), the movement of the auto switch may become unstable, so please contact SMC.



With Magnetic Field Resistant Auto Switch D-P3DWA, P4DWL

• If welding cables or welding gun electrodes are in the vicinity of the cylinder, the magnets in the cylinder could be affected by the external magnetic fields. (Contact SMC if the welding amperage exceeds 16000 A.) If the source of strong magnetism comes in contact with the cylinder or an auto switch, make sure to install the cylinder away from the source of the magnetism.

If the cylinder is to be used in an environment in which spatter will come in direct contact with the lead wires, cover the lead wires with a protective tube. For the protective tube, use a tube I.D. ø7 or more, which excels in heat resistance and flexibility.

Contact SMC if an inverter welder or a DC welder will be used.

Calculation of Moment of Inertia

I: Moment of inertia (kg·m²) m: Load mass (kg)

1. Thin shaft

Position of rotational axis:

Vertical to the bar and through the end



$$I = m_1 \cdot \frac{a_1^2}{3} + m_2 \cdot \frac{a_2^2}{3}$$

4. Thin rectangular plate (Rectangular parallelopiped)

Position of rotational axis:

Vertical to the plate and through the end



$$I = m_1 \cdot \frac{4a_1^2 + b^2}{12} + m_2 \cdot \frac{4a_2^2 + b^2}{12}$$

2. Thin shaft

Position of rotational axis:

Perpendicular to the shaft through the center of gravity



$$I = m \cdot \frac{a^2}{12}$$

5. Thin rectangular plate (Rectangular parallelopiped)

Position of rotational axis:

Through the center of gravity and vertical to the plate (Same as also thick rectangular plate)



$$I = m \cdot \frac{a^2 + b^2}{12}$$

3. Thin rectangular plate (Rectangular parallelopiped)

Position of rotational axis:

Parallel to side b through the center of gravity



$$I = m \cdot \frac{a^2}{12}$$

6. Load at the end of lever arm



$$I = m_1 \cdot \frac{a_1^2}{3} + m_2 \cdot a_2^2 + K$$

$$k = m_2 \cdot \frac{2r^2}{5}$$