Low Profile Slide Table

MXF Series

ø8, ø12, ø16, ø20

Low-profile and compact type, air slide table with the construction of guide and cylinder aligned in parallel.

> Low-profile and compactness have been achieved with the construction of guide and cylinder aligned in parallel.

| Model | Height x Width (mm) | Height comparison to MXS |
|-------|---------------------|--------------------------|
| MXF8 | 16 x 58 | 67% |
| MXF12 | 18.5 x 68 | 59% |
| MXF16 | 21 x 80 | 53% |
| MXF20 | 27 x 92 | 54% |

Auto switch is mountable

Auto switch is recessed in the groove to save space.

Slim body

Low-profile has been achieved with the construction of guide and cylinder aligned in parallel.

RoHS

MXH

MXS

MXO

MXO

MXF

MXW

MXJ MXP MXY

MTS

D-

-X 🗆

Cross roller guide allows smooth operation without vibration.

High rigidity

Body mounting (Body tapped)

top allows precise and easy mounting to change workpiece

a @

Stronger thread for mounting work

Positioning pin holes on table

roducibility for mounting and

Neat appearance

Protecting stopper section

Standard stroke adjustment

Stroke can be adjusted at each

with cover realizes neat

stroke end within 5 mm

each end and 10 mm

appearance.

is total.

dismounting

Insert thread for mounting work

Reproducibility for mounting and dismounting

Optional porting

2 directions is possible

Lateral and axial piping from

Pin holes for positioning on bottom of slide allows precise and accurate mounting of actuator.

Body mounting (Body tapped)

Mounting can be done from 2 directions top side (through-hole) and bottom side (body tapped).

| 1. Body tapped | 2. Body through-hole |
|----------------|----------------------|
| | |

Series Variations



SMC

MXF Series Model Selection

| Model Selection Step | Formula/Data | Selection E | xample |
|---|---|--|--|
| Operating Conditions | | | |
| Enumerate the operating conditions considering the mounting position and workpiece configuration. Check that the load weight does not exceed the maximum allowable load weight and that the average operating speed does not exceed the operating speed range. | Model to be used Type of cushion Workpiece mounting position Mounting orientation Average operating speed Va (mm/s) Load mass W (kg): [#[9,(1)] * [mblef(2)] Overhang Ln (mm): [#[9,(2)] | Contraction of the second seco | vlinder: MXF20-50 ushion: Rubber bumper orkpiece table mounting unting: Horizontal wall mounting verage operating speed: = 300 [mm/s] lowable load: W = 0.5 [kg] = 10 mm = 30 mm |
| Kinetic Energy | | | = 30 mm |
| Find the kinetic energy E (J) of the load. Find the allowable kinetic energy Ea (J). Confirm that the kinetic energy of the load does not exceed the allowable kinetic energy. | $\begin{split} E &= \frac{1}{2} \cdot W \left(\frac{V}{1000} \right)^2 \\ \hline Collision speed V &= 1.4 \cdot Va \ast) \text{ Correction factor} \\ Ea &= K \cdot Emax \\ & Workpiece mounting coefficient K: $$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$ | $E = \frac{1}{2} \cdot 0.5 \left(\frac{420}{1000} \right)^2 = 0$ $V = 1.4 \times 300 = 420$ $Ea = 1 \cdot 0.16 = 0.16$ Can be used based on E | .044 = 0.044 ≤ Ea = 0.16 |
| Load Factor | | | |
| B I lead factor of load mana | | | |
| Find the allowable load mass Wa (kg). Note) No need to consider this load factor in the case of using perpendicularly in a vertical position. (Define (X = 0, -)) Find the load factor of the load mass α.1. | $\label{eq:warder} \begin{array}{l} Wa = K \cdot \boldsymbol{\beta} \cdot Wmax \\ Workplece \mbox{ mounting coefficient } K \colon \overline{\texttt{Fig.(3)}} \\ Allowable load mass coefficient \boldsymbol{\beta} \colon \overline{\texttt{Graph (1)}} \\ Max. allowable load mass Wmax \colon \overline{\texttt{Table (2)}} \\ \mathcal{O}_{*} = WWa \end{array}$ | Wa = 1 x 1 x 4 K = 1 β = 1 Wmax = 4 $Q_1 = 0.5/4 = 0$ | l = 4).125 |
| 3-2 Load factor of the static mo | ment | | |
| Find the static moment M (N·m). Find the allowable static moment Ma (N·m). | M = W x 9.8 (Ln + An)/1000 Moment center position distance compensation amount An: [nble(6)] Ma = K-Y-Mmax Workpiece mounting coefficient Y: [Fig.(6) Allowable moment coefficient Y: [Fig.(2)] Maximum allowable moment Mmax: [nble(6)] | Yawing Examine My. Examine My. $My = 0.5 \times 9.8 (10 + 11)/1000 = 0.11$ M $A_3 = 11$ A May = 1 × 1 × 9.14 = 9.14 M Mymax = 9.14 K K = 1 $\gamma = 1$ | Rolling xamine Mr. = 0.5 x 9.8 (30 + 17)/1000 = 0.23 s = 17 ar = 9.14 (Same as May) |
| Find the load factor α_2 of the static moment. | Cl ₂ = M/Ma | C/2 = 0.11/9.14 = 0.012 | 2 = 0.23/9.14 = 0.025 |
| Load factor of dynamic mon | nent | | |
| Find the dynamic moment Me (N-m). | $\begin{split} \text{Me} &= 1/3 \cdot \text{We} \times 9.8 \ \frac{(\text{Ln} + \text{An})}{1000} \\ \text{Collision equivalent to impact We} &= \delta \cdot \text{W} \cdot \text{V} \\ \delta : \text{Bumper coefficient} \\ \text{With urethane bumper (Standard)} &= 4/100 \\ \text{Corrected value for moment} \\ \text{center position distance An: [ADIe(6)]} \end{split}$ | Pitching Examine Mep. Mep = $1/3 \times 8.4 \times 9$ We = $4/100 \times 0.5 \times A_2 = 17$ Meap = $1 \times 0.7 \times 9$. K = 1 $\gamma = 0.7$ Mpmax = 9.14 $(1/2 - 1)^2$ $(1/2 - 1)^2$ | $.8 \times \frac{(30 + 17)}{1000} = 1.3$ 420 = 8.4 14 = 6.40 |
| Find the allowable dynamic moment Mea (N-m). | Mea = K.Ŷ.Mmax Workpiece mounting coefficient K: [364(3) Allowable moment coefficient ?: [379ph(2) Max. allowable moment Mmax: [379ph(4) (/1 = Me/Mea | Yawing Examine Mey. Mey = 1/3 × 8.4 × 9 We = 8.4 A4 = 34 A4 | .8 x <u>(30 + 34)</u> 1000 = 1.8 |
| dynamic moment. | cos - monifica | Meay = 6.40 (Same C/3 = 1.8/6.4 = 0.28 | e value as Meap) |
| 3-4 Sum of the load factors | | 0.0 - 10,014 - 0.20 | |
| Use is possible if the sum of the load factors does not exceed 1. | $\Sigma \alpha n = \alpha_1 + \alpha_2 + \alpha_3 \leq 1$ | $\sum \Omega n = \Omega_1 + \Omega_2 + \Omega_2' + \Omega_3 + 0.125 + 0.012 + 0.025 + 0.002 + 0.025 + 0.0025 + $ | + 0.23 .20 + 0.28 = 0.642 ≤ 1 |

SMC

Model Selection MXF Series

Fig. (1) Load Mass: W (kg)



the case of using perpendicularly in a vertical position.

Fig. (3) Workpiece Mounting Coefficient: K



Table (2) Maximum Allowable Load Mass: Wmax (kg)

| Model | Maximum allowable load mass |
|-------|-----------------------------|
| MXF8 | 0.6 |
| MXF12 | 1 |
| MXF16 | 2 |
| MXF20 | 4 |



Note) Static moment: Moment generated by gravity Dynamic moment: Moment generated by impact when colliding with stopper

Table (1) Maximum Allowable Kinetic Energy: Emax (J)

| | •• •• |
|-------|--------------------------|
| Model | Allowable kinetic energy |
| Model | Rubber bumper |
| MXF8 | 0.027 |
| MXF12 | 0.055 |
| MXF16 | 0.11 |
| MXF20 | 0.16 |

Table (3) Moment Center Position Distance Compensation Amount: An (mm)

| | Moment center position distance compensation amount (Refer to Fig | | | | | | | |
|-------|---|------------|--------------------|------------|----|----|--|--|
| Model | A 1 | A 2 | A 4 | A 5 | A6 | | | |
| MXF8 | 6 ^{Note)} | 10 | 6 ^{Note)} | 21 | 21 | 10 | | |
| MXF12 | 10 | 11 | 10 | 23 | 23 | 11 | | |
| MXF16 | 10 | 12 | 10 | 28 | 28 | 12 | | |
| MXF20 | 11 | 17 | 11 | 34 | 34 | 17 | | |

Note) 16 mm for MXF8-10 only.

Table (4) Maximum Allowable Moment: Mmax (N·m)

| Madal | Stroke (mm) | | | | | | | | |
|-------|-------------|------|----------|------|-------|-------|--|--|--|
| woder | 10 | 20 | 20 30 50 | | 75 | 100 | | | |
| MXF8 | 0.56 | 0.78 | 0.98 | | | | | | |
| MXF12 | | 1.65 | 2.22 | 3.34 | | | | | |
| MXF16 | | | 3.41 | 5.69 | 7.96 | | | | |
| MXF20 | | | 6.66 | 9.14 | 13.70 | 18.27 | | | |

Symbol

| Symbol | Definition | Unit | Symbol | Definition | Unit |
|----------------------------|--|------|--------|---------------------------------|------|
| An (n = 1 to 6) | Correction values of moment center position distance | mm | Va | Average operating speed | mm/s |
| E | Kinetic energy | J | w | Load mass | kg |
| Ea | Allowable kinetic energy | J | Wa | Allowable load mass | kg |
| Emax | Max. allowable kinetic energy | J | We | Mass equivalent to impact | kg |
| Ln (n = 1 to 3) | Overhang | mm | Wmax | Max. allowable load mass | kg |
| M (Mp, My, Mr) | Static moment (pitch, yaw, roll) | N⋅m | α | Load factor | |
| Ma (Map, May, Mar) | Allowable static moment (pitch, yaw, roll) | N⋅m | β | Allowable load mass coefficient | |
| Me (Mep, Mey) | Dynamic moment (pitch, yaw) | N⋅m | γ | Allowable moment coefficient | |
| Mea (Meap, Meay) | Allowable dynamic moment (pitch, yaw) | N⋅m | δ | Damper coeficient | |
| Mmax (Mpmax, Mymax, Mrmax) | Maximum allowable moment (pitch, yaw, roll) | N⋅m | к | Workpiece mounting coefficient | |
| V | Collision speed | mm/s | | | |



MTS

Graph (1) Allowable Load Mass Coefficient: β



Graph (2) Allowable Moment Coefficient: γ



Note) Use the average operating speed when calculating static moment. Use the collision speed when calculating dynamic moment.

> D-□ -X□

Low Profile Slide Table

How to Order



* For the applicable auto switch model, refer to the table below.

* Solid state auto switches marked with " " are produced upon receipt of order.

RoHS

How to Order Stroke Adjusting Bolt (Accessory)



* -X12 (adjustable range 25 mm) is not available in the MXF8/MXF12 series.

Applicable Auto Switches/Refer to pages 1119 to 1245 for the detailed specifications of auto switches.

| | | | light | | L | oad volta | age | Auto swit | ch model | Lead | wire I | ength | n (m) | | | | | | | | | |
|-------------|----------------------------|---------------------|-----------|---------------------------|------------|-----------|--------------|---------------|----------|--------------|----------|----------|----------|---------------------|------------|------------|--------|---|---|---|------------|--|
| Туре | Special function | Electrical entry | Indicator | (Output) | I | DC | AC | Perpendicular | In-line | 0.5 (Nil) | 1 (M) | 3 (L) | 5 (Z) | Pre-wired connector | Applic | able Id | | | | | | |
| £ | | | | 3-wire (NPN) | | EV 10V | | M9NV | M9N | • | • | • | 0 | 0 | | | | | | | | |
| j | | | | 3-wire (PNP) | | 50,120 | 50,120 | | M9PV | M9P | • | • | • | 0 | 0 | IC CITCUIL | | | | | | |
| sv | | | | 2-wire | | 12V | 1 | M9BV | M9B | • | • | ٠ | 0 | 0 | - | | | | | | | |
| 육 | Discussed in disation | | | 3-wire (NPN) | | EV 10V | 1 | M9NWV | M9NW | • | • | • | 0 | 0 | | Deleu | | | | | | |
| a | (2-color indication) Gromm | Grommet Yes | Yes | 3-wire (PNP) | 24V 5V,12V | 24V | 24V 5V,12V | - | M9PWV | M9PW | • | • | • | 0 | 0 | IC CITCUIL | Relay, | | | | | |
| ate | | | | 2-wire | | 12V | 1 | M9BWV | M9BW | • | • | ٠ | 0 | 0 | - | FLC | | | | | | |
| s | | | | 3-wire (NPN) | | EV 10V | 1 | M9NAV*1 | M9NA*1 | 0 | 0 | • | 0 | 0 | | | | | | | | |
| ie i | Water resistant | | | 3-wire (PNP) | 5 | | 50,120 | 50,120 | 50,120 | 50,120 | 50,120 | 50,120 | | M9PAV*1 | M9PA*1 | 0 | 0 | ۰ | 0 | 0 | IC CIrcuit | |
| Ň | | | | 2-wire | | 12V | 1 | M9BAV*1 | M9BA*1 | 0 | 0 | ٠ | 0 | 0 | - | | | | | | | |
| ed witch | | 0 | Yes | 3-wire (Equiv. to NPN) | _ | 5V | - | A96V | A96 | • | - | • | - | - | IC circuit | _ | | | | | | |
| to s | | Grommet | | 2 wire | 2414 | 101/ | 100V | A93V*2 | A93 | • | • | ٠ | • | - | - | Relay, | | | | | | |
| au | | | None | 2-wire | 241 | 120 | 100V or less | A90V | A90 | | - | • | - | _ | IC circuit | PLC | | | | | | |

*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

*2 1 m type lead wire is only applicable to D-A93.

* Lead wire length symbols: 0.5 m Nil (Example) M9NW

- 1 m ······ M (Example) M9NWM
- 3 m ······ L (Example) M9NWL

5 m ······ Z (Example) M9NWZ

* Since there are other applicable auto switches than listed, refer to page 277 for details.

* For details about auto switches with pre-wired connector, refer to pages 1192 and 1193

* Auto switches are shipped together (not assembled).







| Bore size (mm) | 8 | 12 | 16 20 | | | | | |
|--|--|---------------|-----------------|--|--|--|--|--|
| Piping port size | M3 x 0.5 | | M5 x 0.8 | | | | | |
| Fluid | | Ai | r | | | | | |
| Action | | Double | acting | | | | | |
| Operating pressure | | 0.15 to 0 |).7 MPa | | | | | |
| Proof pressure | 1.05 MPa | | | | | | | |
| Ambient and fluid temperature | -10 to 60 °C | | | | | | | |
| Operating speed range (Average operating speed) Note) | 50 to 500 mm/s | | | | | | | |
| Cushion | | Rubber bumper | r on both sides | | | | | |
| Lubrication | | Non- | lube | | | | | |
| Auto switch (Option) | Reed auto switch Solid state auto switch (2-wire, 3-wire) 2-color indicator solid state auto switch (2-wire, 3-wire) | | | | | | | |
| Stroke length tolerance | +1 mm | | | | | | | |
| Stroke adjustment range | Extension end 5 mm/Retraction end 5 mm | | | | | | | |
| ote) Average operating speed. Speed that the stroke is divided by a period of time from starting the | | | | | | | | |

Note) Average operating speed: Speed that the stroke is divided by a period of time from starting th operation to reaching the end.

| Theoretica | O | | | | | | | | | |
|------------|----------|-----------|--|-----|-----|-----|-----|-----|-----|--|
| Bore size | Rod size | Operating | Operating Piston area Operating pressure (MP | | | | | | | |
| (mm) | (mm) | direction | (mm ²) | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | |
| | 4 | OUT | 50 | 10 | 15 | 20 | 25 | 30 | 35 | |
| 0 | 4 | IN | 38 | 8 | 11 | 15 | 19 | 23 | 27 | |
| 10 | | OUT | 113 | 23 | 34 | 45 | 57 | 68 | 79 | |
| 12 | 0 | IN | 85 | 17 | 26 | 34 | 43 | 51 | 60 | |
| 16 | 0 | OUT | 201 | 40 | 60 | 80 | 101 | 121 | 141 | |
| 10 | 0 | IN | 151 | 30 | 45 | 60 | 76 | 91 | 106 | |
| | 10 | OUT | 314 | 63 | 94 | 126 | 157 | 188 | 220 | |
| 20 10 | IN | 236 | 47 | 71 | 94 | 118 | 142 | 165 | | |

Made to Order: Individual Specifications (For details, refer to pages 278 and 279.)

| Symbol | Specifications |
|--------|--|
| -X7 | PTFE grease |
| -X9 | Grease for food processing machines |
| -X11 | Adjusting bolt, long specification (Adjustment range: 15 mm) |
| -X33 | Without built-in auto switch magnet |
| -X39 | Fluororubber seal |
| -X42 | Anti-corrosive specifications for guide unit |
| -X45 | EPDM seal |

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Standard Stroke

| Model | Standard stroke (mm) |
|-------|----------------------|
| MXF8 | 10, 20, 30 |
| MXF12 | 20, 30, 50 |
| MXF16 | 30, 50,7 5 |
| MXF20 | 30, 50, 75, 100 |

Weight

| Madal | Standard stroke (mm) | | | | | | | | | | | |
|-------|----------------------|-----|-----|-----|------|------|--|--|--|--|--|--|
| Model | 10 | 20 | 30 | 50 | 75 | 100 | | | | | | |
| MXF8 | 120 | 130 | 170 | _ | | - | | | | | | |
| MXF12 | _ | 210 | 250 | 360 | | - | | | | | | |
| MXF16 | _ | _ | 360 | 500 | 690 | - | | | | | | |
| MXF20 | _ | _ | 600 | 750 | 1060 | 1370 | | | | | | |

Moisture Control Tube IDK Series

When operating an actuator with a small diameter and a short stroke at a high frequency, the dew condensation (water droplet) may occur inside the piping depending on the conditions. Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to <u>the IDK se-</u> <u>rise in the Best Pneumatics No. 6.</u>



MXH MXS MXQ MXQ MXF MXW MXJ

MXP MXY MTS

► IN

(a)

Table Deflection (Reference Values)

Table displacement due to

pitch moment load

(mm)

Table displacement amount

Table displacement when loads are applied to the section marked with the arrow at the full stroke.

Table displacement due to yaw moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.

Table displacement due to roll moment load

Table displacement of section A when loads are applied to the section F with the slide table retracted.









Low Profile Slide Table **MXF** Series

The graphs below show the table displacement when the static moment load is applied to the table. The graphs do not show the loadable mass. Refer to the Model Selection for the loadable mass.

Table displacement due to

Table displacement due to pitch moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.

Table displacement due to yaw moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke. roll moment load Table displacement of section A when loads are applied to the section F with the slide table retracted.





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MXF Series

Construction



Component Parts

| No. | Description | Material | Note |
|-----|--------------------|----------------------------------|---------------------------|
| 1 | Body | Aluminum alloy | Hard anodized |
| 2 | Table | Aluminum alloy | Hard anodized |
| 3 | End plate | Aluminum alloy | Hard anodized |
| 4 | Rail | Carbon tool steel | Heat treated |
| 5 | Guide | Carbon tool steel | Heat treated |
| 6 | Rod | Stainless steel | |
| 7 | Piston assembly | — | With magnet |
| 8 | Seal support | Brass | Electroless nickel plated |
| 9 | Head cap | Resin | |
| 10 | Floating bushing | Stainless steel | |
| 11 | Orifice | Brass | Electroless nickel plated |
| 12 | Roller stopper | Stainless steel | |
| 13 | Cylindrical roller | High carbon chrome bearing steel | |
| 14 | Roller spacer | Resin | |
| 15 | Rod bumper | Polyurethane | |

Component Parts

| No. | Description | Material | Note |
|-----|---------------|--------------|------|
| 16 | Adjust bumper | Polyurethane | |
| 17 | Piston seal | NBR | |
| 18 | Rod seal | NBR | |
| 19 | O-ring | NBR | |

Replacement Parts: Seal Kit

| Bore size (mm) | Kit no. | Contents |
|----------------|----------|------------------------------|
| 8 | MXF8-PS | |
| 12 | MXF12-PS | |
| 16 | MXF16-PS | Set of nos. above (1) to (19 |
| 20 | MXF20-PS | |

* Seal kit includes (1), (18, (19. Order the seal kit, based on each bore size.

Replacement Part: Grease Pack

| Applied part | Grease pack part no. |
|--------------|----------------------------------|
| Guide | GR-S-010 (10g) GR-S-020 (20g) |
| Cylinder | GR-L-005 (5g) GR-L-010 (10g) |

Dimensions: Stroke Adjustment Bolt



| Applicable size | Model | Stroke adjustment range (mm) | Α | в | с | м | |
|-----------------|-------------------------|------------------------------------|------|----------|--------|------------|--|
| MYEO | MXF-A827 | 5 | 17 | 6 | 2 | M4 x 0.7 | |
| WAFO | MXF-A827-X11 | 15 | 27 | | - | WI4 X 0.7 | |
| MYE10 | MXF-A1227 | 5 | 23.5 | 7 | 25 | MEVOR | |
| MAF12 | MXF-A1227-X11 | 15 | 33.5 | <i>'</i> | 2.5 | IVIS X 0.0 | |
| | MXF-A1627 | 5 | 26.5 | | | | |
| MXF16 | MXF-A1627-X11 15 36.5 8 | | 8 | 3 | M6 x 1 | | |
| | MXF-A1627-X12 | 25 | 46.5 |] | | | |
| | MXF-A2027 | 5 | 30 | | | | |
| MXF20 | MXF-A2027-X11 | 15 | 40 | 12 | 4 | M8 x 1 | |
| | MXF-A2027-X12 | 25 | 50 |] | | | |

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Dimensions: MXF8



| | | | | | | | | (mm) |
|---------|----|---|------|----|----|----|------|------|
| Model | F | N | G | н | J | М | Z | ZZ |
| MXF8-10 | 20 | 4 | 13.5 | 22 | 21 | 49 | 49.5 | 58 |
| MXF8-20 | 26 | 4 | 14.5 | 26 | 26 | 54 | 54.5 | 63 |
| MXF8-30 | 26 | 6 | 14.5 | 40 | 41 | 69 | 69.5 | 78 |
| | | | | | | | | |



MXF Series

Dimensions: MXF 12



SMC

Dimensions: MXF16





-X□

MXF Series

Dimensions: MXF20



SMC

MXF Series **Auto Switch Mounting**

Auto Switch Proper Mounting Position (Detection at Stroke End)



| ieed Auto Sw | itcn: | D-A | 90, L | -A93 | 5, D-A | 196, | D-A9 | UV, I | J-A9 | 3V, L | J-A9 | 5V (| mm) | |
|--------------|-------|--------|-------|------|--------|------|------|------------|---------------|----------------|----------------|----------------|----------------|--|
| | | | | В | | | | E | | | | | | |
| Model | A | Stroke | | | | | | | Stroke | | | | | |
| | | 10 | 20 | 30 | 50 | 75 | 100 | 10 | 20 | 30 | 50 | 75 | 100 | |
| MXF8 | 9.5 | 10 | 5 | 10 | — | | Ι | 8 (5.5) | 3 (0.5) | 8 (5.5) | | - | — | |
| MXF12 | 12 | - | 13.1 | 13.1 | 29.1 | Ι | I | - | 11.1 (8.6) | 11.1 (8.6) | 27.1 (24.6) | _ | — | |
| MXF16 | 17.2 | _ | — | 15.8 | 25.8 | 46.8 | _ | _ | — | 13.8 (11.3) | 23.8 (21.3) | 44.8 (42.3) | — | |
| MXF20 | 19.4 | _ | _ | 20.7 | 22.7 | 46.2 | 70.7 | _ | _ | 18.7 (16.2) | 20.7 (18.2) | 44.2 (41.7) | 68.7 (66.2) | |

Solid State Auto Switch: D-M9B, D-M9N, D-M9P, D-M9BW, D-M9NW, D-M9PW, D-M9DA (mm)

| | | | | E | 3 | | | | | E | E | | | | E | E (D-M | /I9⊡A | I) | | N | /IXW |
|-------|------|----|------|------|------|------|------|----|-----|------|------|------|------|----|-----|--------|-------|------------|------|---|------|
| Model | A | | | Str | oke | | | | | Str | oke | | | | | Str | oke | | | Ē | |
| | | 10 | 20 | 30 | 50 | 75 | 100 | 10 | 20 | 30 | 50 | 75 | 100 | 10 | 20 | 30 | 50 | 75 | 100 | N | VIXJ |
| MXF8 | 13.5 | 14 | 9 | 14 | — | — | — | 4 | -1 | 4 | - | - | - | 2 | -3 | 2 | - | - | — | | |
| MXF12 | 16 | _ | 17.1 | 17.1 | 33.1 | - | — | - | 7.1 | 7.1 | 23.1 | - | — | _ | 5.1 | 5.1 | 21.1 | - | — | 1 | ΊΛΓ |
| MXF16 | 21.2 | _ | _ | 19.8 | 29.8 | 50.8 | — | _ | _ | 9.8 | 19.8 | 40.8 | — | _ | - | 7.8 | 17.8 | 38.8 | — | | NXY |
| MXF20 | 23.4 | _ | _ | 24.7 | 26.7 | 50.2 | 74.7 | _ | _ | 14.7 | 16.7 | 40.2 | 64.7 | _ | - | 12.7 | 14.7 | 38.2 | 62.7 | Ľ | |

MTS

MXH MXS MXO

MXQ

MXF

Solid State Auto Switch: D-M9BV, D-M9NV, D-M9PV, D-M9BWV, D-M9NWV, D-M9PWV, D-M9DAV (mm)

| | | | | E | 3 | | | | E | | | | | E (D-M9⊡AV) | | | | | |
|-------|------|----|------|------|------|------|------|--------|-----|------|------|------|--------|-------------|-----|------|------|------|------|
| Model | Α | | | Str | oke | | | Stroke | | | | | Stroke | | | | | | |
| | | 10 | 20 | 30 | 50 | 75 | 100 | 10 | 20 | 30 | 50 | 75 | 100 | 10 | 20 | 30 | 50 | 75 | 100 |
| MXF8 | 13.5 | 14 | 9 | 14 | — | - | - | 6 | 1 | 6 | - | - | - | 4 | -1 | 4 | - | - | _ |
| MXF12 | 16 | _ | 17.1 | 17.1 | 33.1 | - | - | _ | 9.1 | 9.1 | 25.1 | - | - | _ | 7.1 | 7.1 | 23.1 | - | _ |
| MXF16 | 21.2 | _ | — | 19.8 | 29.8 | 50.8 | - | _ | - | 11.8 | 21.8 | 42.3 | - | _ | - | 9.8 | 19.8 | 40.3 | _ |
| MXF20 | 23.4 | _ | — | 24.7 | 26.7 | 50.2 | 74.7 | _ | _ | 16.7 | 18.7 | 42.2 | 66.7 | _ | - | 14.7 | 16.7 | 40.2 | 64.7 |

* (): Denotes the values of D-A93.

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Auto Switch Mounting

Auto switch mounting screw (included with auto switch) Watchmaker's screwdrive

Auto Switch Mounting Tool

Caution When adjusting the auto switch mounting screw (included with auto switch), use a watchmaker's screwdriver with a handle about 5 to 6 mm in diameter.

Tightening Torque

| Tiahtenina | Torque | of Auto | Switch | Mounting | Screw | (N·m) |
|------------|--------|---------|--------|----------|-------|-------|
| | | | | | | |



Operating Range

| Auto avvitals model | Applicable bore size (mm) | | | | |
|------------------------------|---------------------------|----|-----|----|--|
| Auto switch model | 8 | 12 | 16 | 20 | |
| D-A9□(V) | 4.5 | 5 | 6 | 7 | |
| D-M9□, M9□V D-M9□W, M9□WV | 3 | 3 | 4.5 | 5 | |
| D-M9□A, M9□AV | | | | | |

* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.



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SMC

MXF series Made to Order: Individual Specifications 1



Please contact SMC for detailed dimensions, specifications and lead times.



• PTFE grease

PTFE grease is used for all parts that grease is applied.

Specifications

 Type
 PTFE grease

 Bore size (mm)
 8, 12, 16, 20

* Dimensions other than the above is the same as the standard type.

A Warning

Precautions

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.



 Grease for food processing machines

Grease for food processing machines is used for all parts that grease is applied.

Specifications

| Туре | Grease for food processing machines (NSF-H1 certified)/Aluminum complex soap base grease |
|----------------|--|
| Bore size (mm) | 8, 12, 16, 20 |

* Dimensions other than the above is the same as the standard type.

Caution Do not use this cylinder in a food-related environment. Solish zore

<Cannot be mounted> Food zone---Food may directly contact with this cylinder, and is treated as food products.

- -Can be mounted>
- Splash zone---Food may directly contact with this cylinder, but is not treated as food products.
- Non-food zone...This cylinder do not directly contact food.



Food zone

Cannot be mounted





Auto switch magnet is not built in.

Specifications

| hout built-in auto switch magnet |
|----------------------------------|
| 8, 12, 16, 20 |
| Not mountable |
| |

* Dimensions other than the above is the same as the standard type.

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Change the materials for the piston seal, rod seal and O-rings to fluororubber.

Specifications

| Туре | Fluororubber seal |
|----------------|-------------------|
| Bore size (mm) | 8, 12, 16, 20 |
| Seal material | Fluororubber |

* Dimensions other than the above is the same as the standard type.



Rail and guide are given anti-corrosive treatment.

Specifications

| Туре | Anti-corrosive guide unit | |
|-------------------|--------------------------------------|--|
| Bore size (mm) | 8, 12, 16, 20 | |
| Surface treatment | Special anti-corrosive treatment (2) | |

* 1 Dimensions other than the above is the same as the standard type.

* 2 Special anti-corrosive treatment makes the rail and the guide black.



MXF Standard model no. - X45

• EPDM seal

Change the materials for the piston seal, rod seal and O-rings to EPDM.

Specifications

| Туре | EPDM seal |
|----------------|---------------|
| Bore size (mm) | 8, 12, 16, 20 |
| Seal material | EPDM |
| Grease | PTFE grease |

* Dimensions other than the above is the same as the standard type.

Marning Precautions

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.

MXF Series Made to Order: Individual Specifications 2

| | | Symb | ol | |
|--|---------|------|------|-----|
| 7 Adjusting Bolt, Long Specification (Adjustment range: 15 mm) | | -X1 | 1 | |
| NVE Standard model no - V11 | | | | MXH |
| | | | | MXS |
| (Adjustment range: 15 mm) | | | | MXO |
| The average adjusting stroke range was extended from 5 mm to 15 mm with a long adjusting bolt. | | | | MVO |
| Dimensions | | | | WXU |
| | | | | MXF |
| For backward-facing end | | | | MXW |
| | | | | MXJ |
| | | | | MXP |
| | | | | MXY |
| • | | | | MTS |
| Max. A | | | | |
| | | | | |
| | | | (mm) | |
| | Model | Α | В | |
| | MXF8 | 10 | 19 | |
| | MXF12 | 10 | 20.5 | |
| | MYEOD | 10 | 10 5 | |
| ¥¥ | IVIAF20 | 10 | 19.0 | |



MXF Series Specific Product Precautions

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Mounting

Mounting of Body

A Caution

- Do not scratch or dent the mounting side of the body, table or end plate. It causes play in the guide section and increases sliding resistance.
- Do not scratch or dent on the forward side of the rail or guide. It will result in looseness of the guide section and increased sliding resistance.
- Keep away from objects which are influenced by magnets.

As the piston part has magnets built-in, do not allow close contact with magnetic disks, magnetic cards or magnetic tapes. Data may be erased.

- 4. When mounting the body, use screws with appropriate length and do not exceed the maximum tightening torque. Tightening with a torque above the limit could malfunction. Whereas tightening insufficiently could result in misalignment or come to a drop.
- Be careful when adjusting stroke not to allow cylinder end plate to bottom out against cylinder body.

Positioning

A Caution

 The positioning hole on the table and on the bottom of the body does not have the same center. Positioning hole is meant to be for reproducibility for mounting and dismounting.



▲ Caution

1. If intermediate stop by external stopper is done, avoid ejection.

If ejection occurs, it may cause damage. In the case the slide table is stopped at an intermediate position by an external stopper then forwarded to the front, return the slide table to the back for just a moment to retract the stopper, then supply pressure to the opposite port to operate slide table.

2. Do not use it in such a way that excessive external force or impact force could work on it.

This could result in damage.

The slide table can be mounted from 2 directions. Select the best direction according to your application.



| Model | Bolt | Maximum tightening torque (N·m) | Maximum screw-in depth L (mm) |
|-------|----------|---------------------------------------|----------------------------------|
| MXF8 | M4 x 0.7 | 2.1 | 4.7 |
| MXF12 | M4 x 0.7 | 2.1 | 6.5 |
| MXF16 | M5 x 0.8 | 4.4 | 6.7 |
| MXF20 | M5 x 0.8 | 4.4 | 8.5 |

| 2. Body Through-hole | | | | | |
|----------------------|----------|---------------------------------------|----------------------------------|--|--|
| | | | | | |
| Model | Bolt | Maximum tightening torque (N·m) | Maximum screw-in depth L (mm) | | |
| MXF8 | M3 x 0.5 | 1.2 | 4.7 | | |

12

2.8

2.8

65

6.7

8.5

| <u>∧</u> Cau | tion |).02 mm or less An uneven mour ncrease sliding | of flatness is re nting surface of resistance. | ecommended a workpiece | for the boo | dy mounting su may cause vibr | ırface. ration or |
|--------------|------|--|--|---------------------------|-------------|----------------------------------|----------------------|

MXF12

Mounting of Workpiece

Work can be mounted on two sides of the body



| Model | Bolt | Maximum tightening torque (N·m) | Maximum screw-in depth L (mm) |
|-------|----------|---------------------------------------|----------------------------------|
| MXF8 | M3 x 0.5 | 0.9 | 6 |
| MXF12 | M3 x 0.5 | 0.9 | 6 |
| MXF16 | M4 x 0.7 | 2.1 | 10 |
| MXF20 | M5 x 0.8 | 4.4 | 12 |

2. Top Mounting

M3 x 0 5

MXF16 M4 x 0.7

MXF20 M4 x 0.7



| Model | Bolt | tightening torque (N·m) | depth L (mm) |
|-------|----------|----------------------------|--------------|
| MXF8 | M3 x 0.5 | 0.9 | 6.5 |
| MXF12 | M3 x 0.5 | 0.9 | 5.5 |
| MXF16 | M4 x 0.7 | 2.1 | 6.5 |
| MXF20 | M5 x 0.8 | 4.4 | 9.5 |

A Caution

To prevent the workpiece holding bolts from touching the guide holding bolts, use bolts that are 0.5 mm or more shorter than the maximum screw-in depth.

If the bolts are too long, they hit the end plate and may cause malfunctions.

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⊘SMC