

# **Dualee Bualee Bualee Bualee Bualee Bualee Bualee Bualee Bualee Bualee Bualee**

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Courtesy of Steven Engineering, Inc - (800) 258-9200 - sales@steveneng.com - www.stevenengineering.com



# EXPERTLY DESIGNED, DELIVERED TO PERFORM

Powered by over 70 years of relentless problem-solving and steadfast reliability, Bishop-Wisecarver delivers innovative motion solutions around the world that thrive in harsh and extreme conditions. Our linear and rotary motion solutions, custom complex assemblies, and embedded intelligence systems lead the manufacturing industry, and they are backed by The **Signature Experience** promise of expert guidance, confidence and customer satisfaction.

# **EXTENDING ROBOTICS IN CRITICAL APPLICATIONS**

Our solutions use the self-cleaning action of DualVee Motion Technology<sup>®</sup> for maximum environmental and debris resistance. This ability to excel in harsh and extreme conditions is especially crucial for drilling, welding, painting, and more. Many solutions that run on DualVee guide wheels require no maintenance over the planned life of the machine.

# DualVee Guide Wheel Based RTUs Are Ideal For:





HARSH DEBRIS ENVIRONMENTS





LOW TOTAL COST OF OWNERSHIP



HIGH/LOW TEMPERATURE



LOW NOISE

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# **INTRODUCTION**

Both traditional and collaborative robots can benefit from Bishop-Wisecarver 7<sup>th</sup>-Axis Robot Transfer Unit solutionsavailable in light, medium and heavy capacity. Each system is designed for **durability**, **ease of installation**, and **low total cost of ownership**. Our expert application engineers can help you select the complete 7th axis system solution that is right for you, or customize a solution to meet your exact requirements.



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#### **Need Help**

**Application + Design Assistance** 925.439.8272

**3D Modeling + CAD Drawing** BWC.com

# **DUALVEE® RTU OVERVIEW**

#### **Features**

The DualVee<sup>®</sup> RTU is designed from the ground up to provide accurate and durable motion for large robots and cobots. The following features are available on standard systems:

#### **Easily Assembled Modules**

3 meter base module and 2 meter extensions with removable lift points allow for easier assembly of long systems

#### Automatic Lubrication

Auto pinion lubrication system and large track lubrication wells for lower maintenance

Gearbox & Motor Mount

20:1 planetary gearbox; mounting interface to match to your motor

**Travel Bumpers** 

Bumper kits

protect against

impact at the end

of system travel

**Leveling Feet** – Rigid mounting with integrated adjustability

#### Structural Weldment -

Thick-walled rectangular tubing construction, finished with paint

#### Rack & Pinion Drive

Hardened & ground helical gearing for accurate positioning

# **Cable Carrier** & Support Kits Centermounted cable management system

(carrier not shown)

#### DualVee Guide — Wheels and Track

8 large capacity linear guide wheel bearings roll on hardened track to support heavy robots at full reach

#### Robot Carriage \_

Sturdy platform with bolt-on hole pattern matched to your robot

# Travel Limit Sensor(s)

Non-contact inductive switch detects travel limit and assists homing; additional / alternative sensors available

#### **Included Elements:**

- Robust rack-driven module(s)
- Carriage with hole pattern matching your selected robot
- 20:1 planetary gearbox as standard
- · Motor mount matched to your drive motor of choice
- · Homing sensor kit

#### Add-ons:

- Travel bumper kits
- Additional limit sensor kit
- Cable carrier support kits
- Drive motor

#### **Basic Specs:**

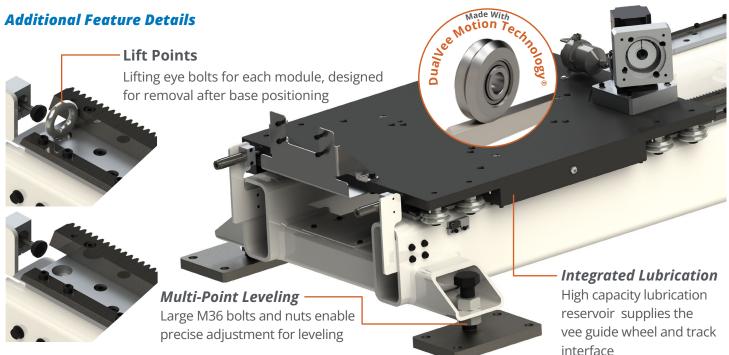
- Accuracy within 0.034 mm / 1 m
- Speeds up to 0.5 m/s [1.64 ft/s]
- Accelerations up to 0.981 m/s<sup>2</sup>
- Max loads of approx. 52.4 kN [11.7 klbf]

# Need Customization? Talk to Us!

- Complete mechatronics solution
- Removing included elements
- Alternate gearbox
- Cable carrier with pre-installed cables
- Custom lengths
- · Additional machining or alternate finishing

# **DUALVEE® RTU OVERVIEW**

#### **Additional Feature Details**



# **Gearbox & Motor Mount Kit**

This kit includes several required elements for driving the DualVee® RTU system. Talk to our Application Engineers to match a gearbox & mount kit to your specified motor. If you require assistance with motor selection, want a customized gearbox, or need a complete mechatronics solution, our experts are here to help!

#### Motor Mount & Shaft Coupler Designed to adapt to a variety of

suitable motors

Mounting Base Attachment point to the RTU carriage

#### Helical Pinion -

Minimal backlash drive; distance from the rack adjusts via the mounting base

# **Included Elements:**

- 20:1 planetary gearbox, 90-degree right angle
- Motor mounting flange to fit drive motor
- Shaft coupler to connect to drive motor
- · Helical pinion for rack & pinion system
- Automatic lubricator system (125 cc) with felt gear
- Mounting base with pinion adjustment feature

# Planetary Gearbox

20:1 right angle planetary gearbox as standard; provides low backlash and is lubricated for life

#### Automatic Lubricator and Felt Gear

Provides a steady supply of lubrication to the rack drive assembly

#### **Gearbox Basic Specs:**

Made With

ion

- Backlash: 4 arcmin
- Nominal output torque @ 1500 rpm: 180 Nm
- Max torgue during acceleration: 288 Nm
- Max input speed, continuous: 2500 RPM
- Max input speed, cyclical: 4500 RPM

# **DUALVEE® RTU ACCESSORIES**

# **Cable Carrier**

The DualVee® RTU is designed to use the following cable carrier: IGUS E4-56-12.

This cable carrier can be included on request. Contact our Application Engineers if you require a custom cable carrier system.

#### **Cable Carrier Mounting Kits**

Bishop-Wisecarver offers two mounting kits designed for the IGUS E4-56-12, of varying heights.





DVRTU4CCME4122K Tall Version

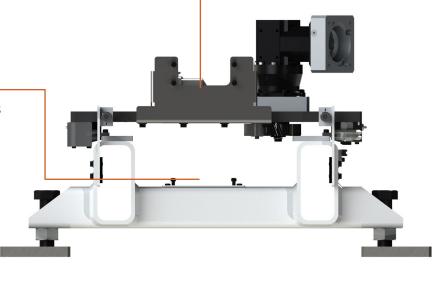
#### Cable Carrier Mounting Kit -

The moveable end of the cable carrier attaches to the cable carrier mounting kit on the carriage.

#### Cable Carrier Support Plate

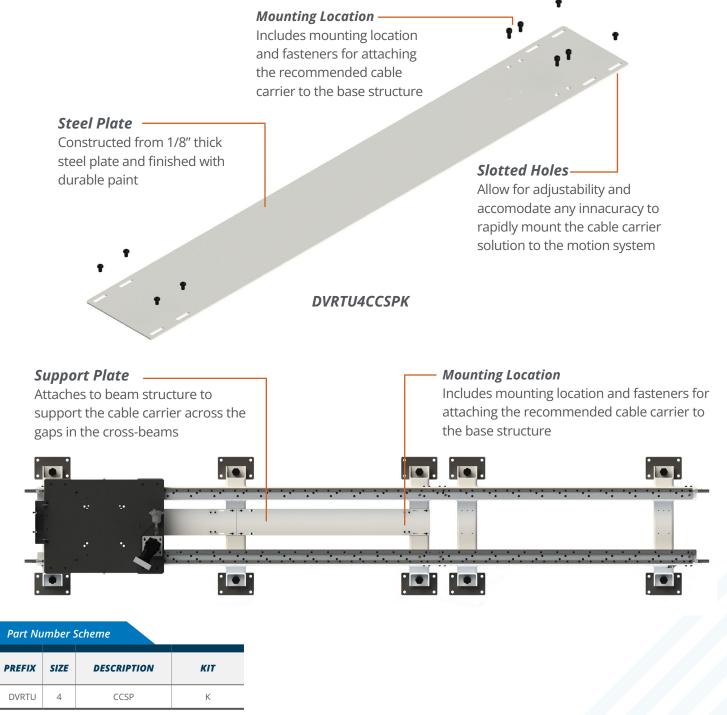
The fixed end of the cable carrier attaches to the cable carrier support plate.

Part Nı	ımber s	Scheme	
PREFIX	SIZE	PLATE TYPE	КІТ
DVRTU	4	CCME412 (Standard)	К
		CCME4122 (Tall)	



# **Cable Carrier Support Plate Kit**

The recommended cable carrier is able to operate unsupported over medium distances, but as an option, provide additional support for the cable carrier in the areas that span between the base structure cross-beams. This kit of parts includes the steel plate finished in matching paint and all necessary fasteners. Use multiple plate kits to span longer travel distances.



Longer travel RTU systems will require multiple cable carrier support kits.

### **Travel Bumper Mounting Kits**

Optional bumpers absorb impact energy at the end of travel in emergency situations to hep prevent damage and improve safety. Mounting kits attach to the base structure using carbon steel fasteners and can be attached in a variety of locations including to the inside of the beam as shown below, or to the outisde of the beam. Bishop-Wisecarver recommends the use of two bumper kits at each end of travel.



#### **Included Elements:**

- Steel bracket with painted finish
- Mounting hardware
- Shock absorber with mount block

# Part Number Scheme

PREFIX	SHOCK ABSORBER	DESCRIPTION	КІТ
DVRTU	MC600	MNT	К

Not included on RTU system assembly as standard. Add option to order. Each kit contains one shock absorber. Recommended to add four kits per RTU system.

# **Basic Specs:**

- Energycapacity of 134 Nm per cycle
- Lifetime use up to 25 million cycles
- Oil dampening with spring return

# **Travel Limit Sensor Kits**

Non-contact inductive proximity sensors are an important option for enhancing the safe operation of any motion system. The standard RTU motion system includes one (1) travel limit sensor (LP4SNSRINDWPOK) mouted on the starting end and is useful for position homing and for end of travel sensing. Add an additional optional sensor at the opposite end of travel to detect overtravel conditions and trigger an emergency stop condition that could prevent damage or injury. Choose from a variety of sensor specifications to suit your application.



# **Included Elements:**

- Proximity sensor with 2 meter cable
- Mounting hardware
- Adjustable mounting plate

#### **Basic Specs:**

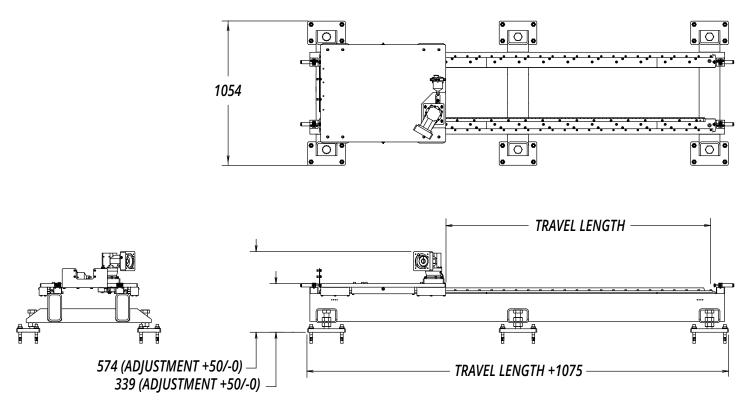
- Operating voltage: 6-30 VDC
- Repeatability: ≤3% sensing dist. (~0.03 mm)
- Hysteresis: <10% sensing dist. (~0.1 mm)
- Voltage drop (sensor on): <1.8 V
- Max output current: 200 mA
- Switching frequency: 1 kHz
- Absorption at 24 VDC: <12 mA
- Temp. range: -13 to 158 °F (-25 to 70 °C)
- Ingress protection: IP67

Sensor Kits	
SENSOR TYPE	SENSOR KIT STOCK CODE
PNP Normally Open	LP4SNSRINDWPOK (default)
PNP Normally Closed	LP4SNSRINDWPCK
NPN Normally Open	LP4SNSRINDWNOK
NPN Normally Closed	LP4SNSRINDWNCK

Bumper Kit and Travel Limit Sensor Kit on RTU Assembly

# **DIMENSIONS AND PART NUMBERS**

#### **Overall Dimensions**



All values in mm unless specified.

Foot number and spacing varies with travel length. Contact BW for your specific floor mounting pattern.

Actual robot mounting hole pattern will match specified robot, which may impact plate dimensions and overall dimensions; Contact BW for details and updated drawings.

### **Base System Part Numbers**

Part Nu	mber Scheme					
PREFIX	TRACK / WHEEL MATERIAL	ROBOT	<b>PEDESTAL</b> (COMING SOON)	-	TRAVEL LENGTH	LENGTH UNIT
DVRTU	4C (Size 4 carbon steel as standard)	Enter letter from Example Robots table; contact us for other robots	N0 (No pedestal)	_	Enter value 2 to 8 (1 meter increments, except 3 m, are standard)	М

#### Part Number Example:

**DVRTU4CFN0-4M** = DualVee RTU, size 4 carbon steel, Fanuc M-20iD compatible, no pedestal, 4 meter travel length.

\*Robots listed here are for example only; many more robots are compatible with DualVee RTU. Contact us to specify robots not listed here.

Disclaimer: All trademarks, logos and brand names are the property of their respective owners. All company, product and service names used in this catalog are for identification purposes only. Use of these names, trademarks, and brands does not imply endorsement.

Example Robots	
MANUFACTURER + MODEL NUMBER*	ROBOT
ABB IRB 1600	А
ABB IRB 2400	В
ABB IRB 2600	С
FANUC M-10iD	E
FANUC M-20iD	F
FANUC M-710iC	Н
Universal Robotics UR 20	Μ
Yaskawa GP12	R
Yaskawa GP25	S

# LOAD CALCULATIONS

# Working Load Capacity

AD TIES	AXIAL L <sub>A</sub>		RADIAL L <sub>R</sub>		PITCH M <sub>p</sub>		YAW M <sub>y</sub> ROLL M <sub>R</sub>		ROLL M <sub>R</sub> THRUS		UST	
RTU LOAD CAPACITIES	N	LBF	N	LBF	N-M	LBF-FT	N-M	LBF-FT	N-M	LBF-FT	N	LBF
A A	52,416	11,784	57,200	12,859	13,593	10,026	14,834	10,941	12,648	9,328	9,948	7,337

# Sizing and Selection Tips

The following equation is for the purpose of estimating the applied load factor to the wheel plate and track plate only. System drive components are not accounted for, but should also be considered. Working load capacities are based on empirical data on guide wheels used in general applications with static and dynamic load conditions. Guide wheels can routinely achieve travel life of one million cycles or higher when these specified load capacities are observed.

# Step 1: Calculate all forces applied to the wheel plate

Any forces applied on the wheel plate need to be considered, including inertial forces, gravitational forces, external forces such as tool pressure, impact loading, and payload. The most conservative calculations will use max foundational loading values from robot manufacturer catalogs.

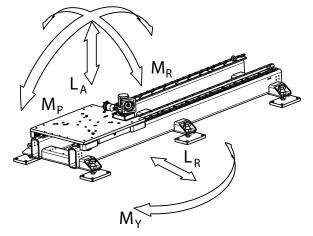
If assistance is required in resolving specific loads into the resultant forces, please contact our Applications Engineering staff.

# Step 2: Calculate load factor for the wheel plate

$L_{F} = \frac{F_{R}}{L_{R}}$	$- + \frac{F_{A}}{L_{A}} + \frac{T_{P}}{M_{P}} + \frac{T_{Y}}{M_{Y}} + \frac{T_{R}}{M_{R}} \leq 1$
WHERE	$L_{F}$ = Load factor
	$F_{R}$ = Resultant radial load
	$F_{A}$ = Resultant axial load
	$T_{p}$ = Resultant Pitch Moment Load
	T <sub>y</sub> = Resultant Yaw Moment Load
	$T_{R}$ = Resultant Roll Moment Load
	$L_{R}$ = Radial Working Load Capacity
	L <sub>A</sub> = Axial Working Load Capacity
	M <sub>P</sub> = Pitch Moment Load Capacity
	$M_{\gamma}$ = Yaw Moment Load Capacity
	$M_{R}$ = Roll Moment Load Capacity

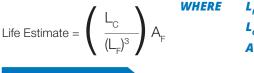
Since the robot can only be extended in one horizontal direction, it is often possible to use  $T_R = \max$  applied horizontal moment and  $T_P = 0$ .

If the load factor  $L_{\rm F}$  is >1, consider a larger size system.



#### Step 3: Calculate estimated life with adjustment factor

The Life Estimate below shares units with the Life Constant.



<b>L</b> <sub>F</sub> = Load Factor
<b>L</b> <sub>c</sub> = Life Constant
<b>A</b> <sub>F</sub> = Adjustment

Factor

A,

Life Constant L<sub>c</sub>

WHEEL SIZE	KILOMETERS OF TRAVEL LIFE	INCHES OF TRAVEL LIFE
4XL	218	8.58 x 10 <sup>6</sup>

# Adjustment Factor A<sub>F</sub> **CONDITIONS** Clean, adequate lubrication, low duty, low

Clean, adequate lubrication, low duty, low shock, low vibration	1.0 – 0.7
Moderate contamination, medium duty, medium shock, low to medium vibration	0.7 - 0.4
Heavy contamination, limited lubrication, high duty, high acceleration, medium to high shock, high vibration	0.4 - 0.1



#### **Components & Accessories**

DualVee®
MadeWell®
GV3
SL2
PRT2
HDS2
HDRT
MCS
Motor Mounts
Gantry Brackets
Wrenches

#### Manual Linear Guide Systems

Duaivee®
UtiliTrak <sup>®</sup>
MinVee®
GV3
Simple Select®
SL2
HDS2
MHD
HTS

# Actuated Linear

Guide Systems LoPro® XLA™ ECO60™ SlickStick™ SteadyRail™ HDLS HDCS PDU2 DAPDU2 SBD PSD SDM DLS

# Rotary Guide Systems PRT2 DTS2 DTS DTS+ ALR HDRT 1-Trak GFX

Robot Transfer Units

DualVee® RTU LoPro® RTU

#### **Custom Solutions**

Extruded Profile Guides Custom Bearings Custom Subassemblies Engineering Services Large Diameter Ring Guides and Track

BWC.COM

# Women's Business Enterprise



Certified WOSB

#### Contact

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Pittsburg, CA 94565

Quality Certifications



Certified Evergreen

• Certified Bay Area Green Business

#### **Certifications & Compliance**

- EN 9100:2018
- JISQ 9100:2016
- ISO 13485 & GMP Compliance
- Responsible Minerals Initiative
- RoHS
- International Traffic in Arms Regulations Compliant

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